

MATH 595 - LECTURE 13

GEODESICS

DEF. Given an A-connection ∇ on A a geodesic for ∇ is an A-path $\alpha: I \rightarrow A$ such that $D_\alpha \alpha = 0$.

In general, geodesics exist only for a small time:

$$\nabla_{\alpha^i} \alpha^j = \Gamma_{ij}^k \alpha^k, \quad \alpha(t) = \alpha^i(t) \alpha_i(\gamma_\alpha(t))$$

$$\rho(\alpha^i) = B_i^s \frac{\partial}{\partial x^s}, \quad \gamma_\alpha(t) = (\gamma_\alpha^1(t), \dots, \gamma_\alpha^m(t))$$

$$\begin{cases} \frac{d\alpha^k}{dt}(t) = -\Gamma_{ij}^k(\gamma_\alpha(t)) \alpha^i(t) \alpha^j(t) & (k=1, \dots, r) \\ \frac{d\gamma_\alpha^s}{dt}(t) = B_i^s(\gamma_\alpha(t)) \alpha^i(t) & (s=1, \dots, m) \end{cases}$$

So geodesics are integral curves of vector field

$$X^\nabla = B_i^s(\alpha) \xi^i \frac{\partial}{\partial x^s} - \Gamma_{ij}^k(\alpha) \xi^i \xi^j \frac{\partial}{\partial \xi^k} \in \mathfrak{X}(A)$$

This is called the geodesic spray of ∇

Proposition The geodesic spray is well-defined (independent of choice of coordinates) and satisfies:

$$(i) \quad d_\alpha \rho(X_\alpha^\nabla) = \rho(\alpha), \quad \forall \alpha \in A$$

$$(ii) \quad (m_t)_* X^\nabla = \frac{1}{t} X^\nabla, \quad \forall t > 0$$

Conversely, any vector field satisfying (i) and (ii) is the geodesic spray of a unique torsion-free connection.

Sketch of proof:

Given vector field:

$$X = u^s(\alpha, \xi) \frac{\partial}{\partial \alpha^s} + v^k(\alpha, \xi) \frac{\partial}{\partial \xi^k}$$

$$(i) + (ii) \Rightarrow \begin{cases} u^s(\alpha, \xi) = B^s_i(\alpha) \xi^i \\ v^k(\alpha, \xi) = v^k_{ij}(\alpha) \xi^i \xi^j \end{cases}$$

To find $\nabla_\alpha \alpha_i = \Gamma^k_{ij} \alpha_k$ with zero torsion and $X^\nabla = X$ solve the system:

$$\begin{cases} \Gamma^k_{ij} - \Gamma^k_{ji} = C^k_{ij} & ([\alpha_i, \alpha_j] = C^k_{ij} \alpha_k) \\ \Gamma^k_{ij} + \Gamma^k_{ji} = v^k_{ij} \end{cases}$$

Using partition of unity $\Rightarrow \nabla \omega_i X^\nabla = X$. \square

Corollary Given an A-connection ∇ on A there is a unique connection $\tilde{\nabla}$ with same geodesics and zero torsion

Exponential map

$$\left. \begin{array}{l} \nabla \equiv \text{A-connection on A} \\ \phi^t_{X^\nabla} \equiv \text{flow of geodesic spray} \end{array} \right\} \begin{array}{l} \exp_\nabla^n: \overset{\text{A}}{\cup} V \rightarrow M \\ \exp_\nabla^n(a) = \text{pr}(\phi^1_{X^\nabla}(a)) \end{array}$$

Exercise: Show that $\exp_\nabla^n|_{A_n V}$ is a submersion onto an open neighborhood $u \in U \subset O_x$.

This is not quite the "right" exponential map:

Prop. Let $G \cong M$ Lie group with $\text{Lie}(G) = A$. There is a map:

$$\exp_\nabla: V \rightarrow G \quad \text{w/ } O_n \subset V \subset A \text{ open}$$

which is a local diffeomorphism if V is sufficiently small neighborhood of O_n .

Proof

The left-invariant vector fields generate all vector fields tangent to t -fibers $\Rightarrow \exists$ unique Kndt-connection $\tilde{\nabla}$ s.t.:

$$\tilde{\nabla}_\alpha \vec{\beta} = \overleftarrow{\nabla}_\alpha \beta$$

One can think of $\tilde{\nabla}$ has a (smooth) family of ordinary connections on t -fibers.

$$\exp_\nabla : V \rightarrow G, \quad \exp_\nabla |_{V \cap A_x} := \exp_{\tilde{\nabla}} |_{\mathfrak{g}(x)}$$

Note that:

$$\text{so } \exp_\nabla = \text{pr}_M \quad \text{to } \exp_\nabla = \exp_\nabla^M$$

Rmk. As for Lie groups, one can express the groupoid structure in "exponential coordinates". The formulas now depend on choice of ∇ , so there is no "universal" Baker-Campbell-Hausdorff formula.

Still it is possible to use this approach to show that to every Lie algebroid there is a "local Lie groupoid" integrating it.

A-path homotopy Groupoid (a.k.a. Weinstein Groupoid)

Arm: Given algebroid $A \rightarrow M$ construct groupoid:

$$G(A) := \frac{A\text{-paths}}{A\text{-path homotopy}}$$

Lemma 1

A-path homotopy is an equivalence relation

Proof

• Reflexive: ε -constant A-path homotopy $\Rightarrow a_0 \sim a_0$

• Symmetry: $a_0 \sim a_1$ via $\underline{\Phi}$ then $a_1 \sim a_0$ via

$$\overline{\Phi}(t, \varepsilon) = \underline{\Phi}_1(t, 1-\varepsilon) dt - \underline{\Phi}_2(t, 1-\varepsilon) d\varepsilon$$

• Transitivity: $a_0 \sim a_1$ via $\underline{\Phi}$ and $a_1 \sim a_2$ via $\underline{\Phi}'$ then

$a_0 \sim a_2$ via:

$$\underline{\Phi}_{02}(t, \varepsilon) = \begin{cases} \underline{\Phi}'_1(t, 2\varepsilon) dt + 2\underline{\Phi}'_2(t, 2\varepsilon) d\varepsilon & 0 \leq t \leq 1 \\ & 0 \leq \varepsilon \leq 1/2 \\ \underline{\Phi}'_1(t, 2\varepsilon-1) dt + 2\underline{\Phi}'_2(t, 2\varepsilon-1) d\varepsilon & 0 \leq t \leq 1 \\ & 1/2 \leq \varepsilon \leq 1 \end{cases}$$

with $\phi: [0,1] \rightarrow [0,1]$ reparametrization in ε -direction with

$$\begin{cases} \phi(\varepsilon) = 0 & \text{if } 0 \leq \varepsilon \leq 1/2 \\ \phi(\varepsilon) = 1 & \text{if } 1/2 \leq \varepsilon \leq 1 \end{cases}$$

□

Lemma 2 If $\phi: [0,1] \rightarrow [0,1]$ is a reparametrization then a & a^ϕ are A-path homotopic.

Proof. Define $\underline{\Phi}: T(\mathbb{I} \times \mathbb{I}) \rightarrow A$ by:

$$\underline{\Phi}(t, \varepsilon) = ((1-\varepsilon) + \varepsilon\phi'(t)) \alpha((1-\varepsilon)t + \varepsilon\phi(t)) dt + (-t + \phi(t)) \alpha((1-\varepsilon)t + \varepsilon\phi(t)) d\varepsilon$$

Need to check this is A-path homotopy:

$$\left. \begin{aligned} - \underline{\Phi}_1(t, 0) &= \alpha(t) \\ - \underline{\Phi}_1(t, 1) &= \phi'(t) \alpha(\phi(t)) = \alpha^\phi(t) \\ - \underline{\Phi}_2(0, \varepsilon) &= 0 = \underline{\Phi}_2(1, \varepsilon) \end{aligned} \right\} \delta(t, \varepsilon) = \delta_\alpha((1-\varepsilon)t + \varepsilon\phi(t))$$

If $\alpha_t \in \Gamma(A)$ is any section extending $\alpha(t)$, then:

$$\alpha_{t,\varepsilon} = ((1-\varepsilon) + \varepsilon\phi'(t)) \alpha_{(1-\varepsilon)t + \varepsilon\phi(t)} \quad \beta_{t,\varepsilon} = (-t + \phi(t)) \alpha_{(1-\varepsilon)t + \varepsilon\phi(t)}$$

are extensions of $\underline{\Phi}_1$ and $\underline{\Phi}_2$ which satisfy:

$$\left(\frac{d}{dt} \beta_{t,\varepsilon} - \frac{d}{d\varepsilon} \alpha_{t,\varepsilon} \right) \Big|_{\delta(t,\varepsilon)} = -[\alpha_{t,\varepsilon}, \beta_{t,\varepsilon}] \Big|_{\delta(t,\varepsilon)} \quad \square$$

- $P(A) = \{A\text{-paths}\}$ " \sim " = A-path homotopy

- $\mathcal{G}(A) := P(A) / \sim \implies M$ w/ structure maps

Source/target maps: $s([a]) = \gamma_a(0)$, $t([a]) = \gamma_a(1)$

unit map: $u(x) = [0_x]$

Inverse map: $i([a]) = [\bar{a}]$

Multiplication: Fix a reparametrization w/ $\phi^{(u)}(0) = \phi^{(u)}(1) = 0$

$$[a_1] \cdot [a_2] := [a_1 \circ a_2]$$

Topology: On $P(A)$ consider C^1 -topology:

$$d(a_1, a_2) = \max \left\{ \sup_{t \in [0,1]} d^A(a_1(t), a_2(t)), \sup_{t \in [0,1]} d^{TA}(a_1'(t), a_2'(t)) \right\}$$

where d^A & d^{TA} are distances in A & TA . Then consider quotient topology on $\mathcal{G}(A)$.

Theorem

$\mathcal{G}(A)$ is a t -simply connected topological groupoid, independent of choice of reparametrization ϕ . Whenever A is integrable, $\mathcal{G}(A)$ has a compatible smooth structure such that it is a Lie groupoid integrating A .

Rmk:

• $\mathcal{G}(A)$ is called the **Weierstrass groupoid** of A .

• $\mathcal{G}(-)$ is a functor: if $\Phi: A_1 \rightarrow A_2$ is a Lie

algebroid morphism then we obtain a morphism of topolog. groupds

$$\mathcal{G}(\Phi): \mathcal{G}(A_1) \rightarrow \mathcal{G}(A_2), [a] \mapsto [\Phi \circ a]$$

If A_1 & A_2 are integrable, this is a smooth morphism integrating Φ .

$\mathcal{G}(A)$ is topological group: structure maps are continuous since they are continuous at the level of A -paths. One still needs to check that source/target are open maps. This follows from:

Lemma: $P(A) \rightarrow P(A)/\sim \cong \mathcal{G}(A)$ is open map

Given $D \subset P(A)$ open, we need to check that its saturation

$$\tilde{D} = \{ a' \in P(A) : a' \sim a \in D \}$$

is open. This follows by showing that if $a_0 \sim a_1$, there exists a homeomorphism $T: P(A) \rightarrow P(A)$ with $T(a_0) = a_1$.

Let $\Phi = \Phi_1 dt + \Phi_2 d\varepsilon$ be A -homotopy from a_0 to a_1 .

Let $\alpha_{t,\varepsilon} \neq \beta_{t,\varepsilon} \in P(A)$ such that:

$$\alpha_{t,\varepsilon}(\gamma(t,\varepsilon)) = \Phi_1(t,\varepsilon)$$

$$\beta_{t,\varepsilon}(\gamma(t,\varepsilon)) = \Phi_2(t,\varepsilon)$$

so that

$$\left(\frac{d}{d\varepsilon} \beta_{t,\varepsilon} - \frac{d}{d\varepsilon} \alpha_{t,\varepsilon} \right) \Big|_{\gamma(t,\varepsilon)} = - [\alpha_{t,\varepsilon}, \beta_{t,\varepsilon}] \Big|_{\gamma(t,\varepsilon)}$$

We can assume that $\beta_{t,\varepsilon}$ is compactly supported (since $\gamma(I \times I) \subset M$ is compact).

Given A -path $\tilde{a}: I \rightarrow A$ let $\tilde{\alpha}_t^0 \in P_c(A)$ be time-dependent section w/ compact support:

$$\tilde{\alpha}_t^0(\gamma_{\tilde{a}}(t)) = \tilde{a}(t)$$

Let $\tilde{\alpha}_{t,\varepsilon}$ be the solution of ODE:

$$\begin{cases} \frac{d}{d\varepsilon} \tilde{\alpha}_{t,\varepsilon} = \frac{d}{dt} \beta_{t,\varepsilon} + [\tilde{\alpha}_{t,\varepsilon}, \beta_{t,\varepsilon}] \\ \tilde{\alpha}_{t,0} = \tilde{\alpha}_t^0 \end{cases}$$

Then if

$$\tilde{\gamma}(t, \varepsilon) := \Phi_{\rho(\beta_{t, \varepsilon})}^{\varepsilon, 0}(\gamma_{\bar{a}}(t))$$

We see that

$$\underline{\tilde{\Phi}} = \tilde{\alpha}_{t, \varepsilon}(\tilde{\gamma}(t, \varepsilon)) dt + \beta_{t, \varepsilon}(\tilde{\gamma}(t, \varepsilon)) d\varepsilon$$

is an A -homotopy starting at a . We then set:

$$T(a) := \tilde{\alpha}_{t, 1}(\tilde{\gamma}(t, 1)).$$

• $\mathcal{G}(A)$ as 1-connected t -fibers (= S -fibers)

Fix $x \in M$ and let $\gamma_s = [a_s]$ be a loop in $S^{-1}(x)$ based at 1_x .
 $a_s: I \rightarrow A$ is a family of A -paths with $[a_0] = [a_1] = 1_x$ (no assumption on s -dependence). We can assume that $a_0(t) = a_1(t) = 0_x$.

Then we define

$$H: I \times I \rightarrow S^{-1}(x) \subset \mathcal{G}(A)$$

$$(s, \varepsilon) \mapsto [\varepsilon a_s(\varepsilon \cdot)]$$

Claim: H is a path-homotopy in $\mathcal{G}(A)$ between $s \mapsto \gamma_s$ and 1_x

• H is continuous:

• For fixed s , $\varepsilon \mapsto H(s, \varepsilon)$ is continuous because

$$[0, 1] \rightarrow P(A), \varepsilon \mapsto \varepsilon a_s(\varepsilon, \cdot) \text{ is continuous}$$

• For fixed ε , $s \mapsto H(s, \varepsilon)$ is continuous because

$$\left. \begin{array}{l} \Phi^\varepsilon: P(A) \rightarrow P(A), a \mapsto \varepsilon a(\varepsilon \cdot) \text{ is continuous} \\ \text{and satisfies } a_0 \sim a_1 \Rightarrow \Phi^\varepsilon(a_0) \sim \Phi^\varepsilon(a_1) \end{array} \right\} \Rightarrow \overline{\Phi}^\varepsilon: \mathcal{G}(A) \rightarrow \mathcal{G}(A) \text{ is continuous}$$

$$\Rightarrow s \mapsto H(s, \varepsilon) = \overline{\Phi}^\varepsilon \circ \gamma_s \text{ is continuous}$$

• Boundary conditions:

$$H(s, 0) = [0_x] = 1_x$$

$$H(s, 1) = [a_s] = \gamma_s$$

$$H(0, \varepsilon) = [\varepsilon a_0(\varepsilon \cdot)] = [0_x] = 1_x$$

$$H(1, \varepsilon) = [\varepsilon a_1(\varepsilon \cdot)] = [0_x] = 1_x$$