

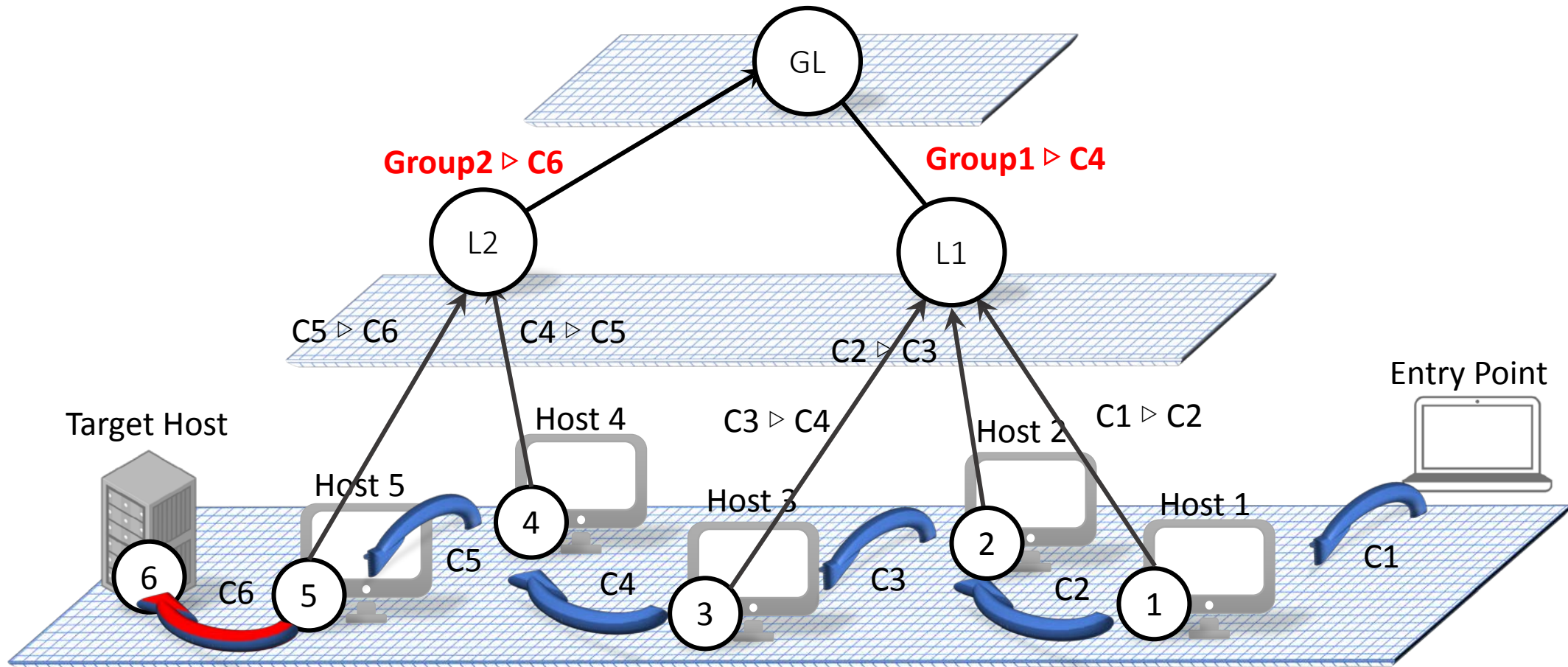
Lateral Movement Detection and Response

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Lateral Movement Detection

A critical step during APT to move from the entry point to target host



Response to Lateral Movement

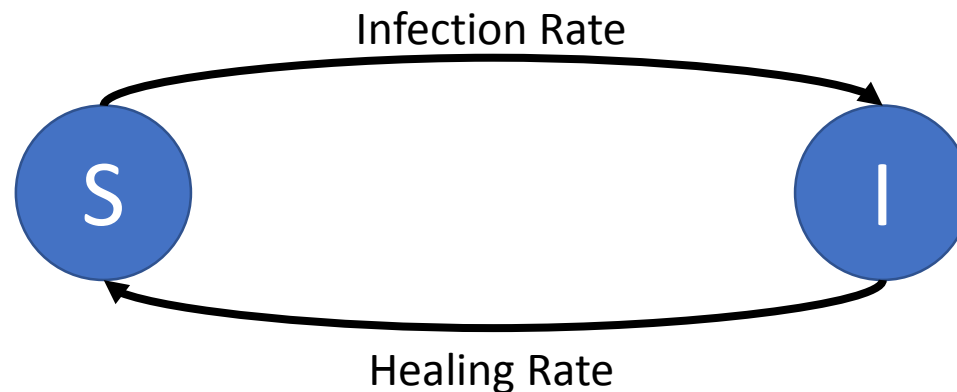
- Achieve resiliency against lateral movement
- Resilience by stopping virus spread while maintaining acceptable service availability, as opposed to disconnecting the whole network

Strategy:

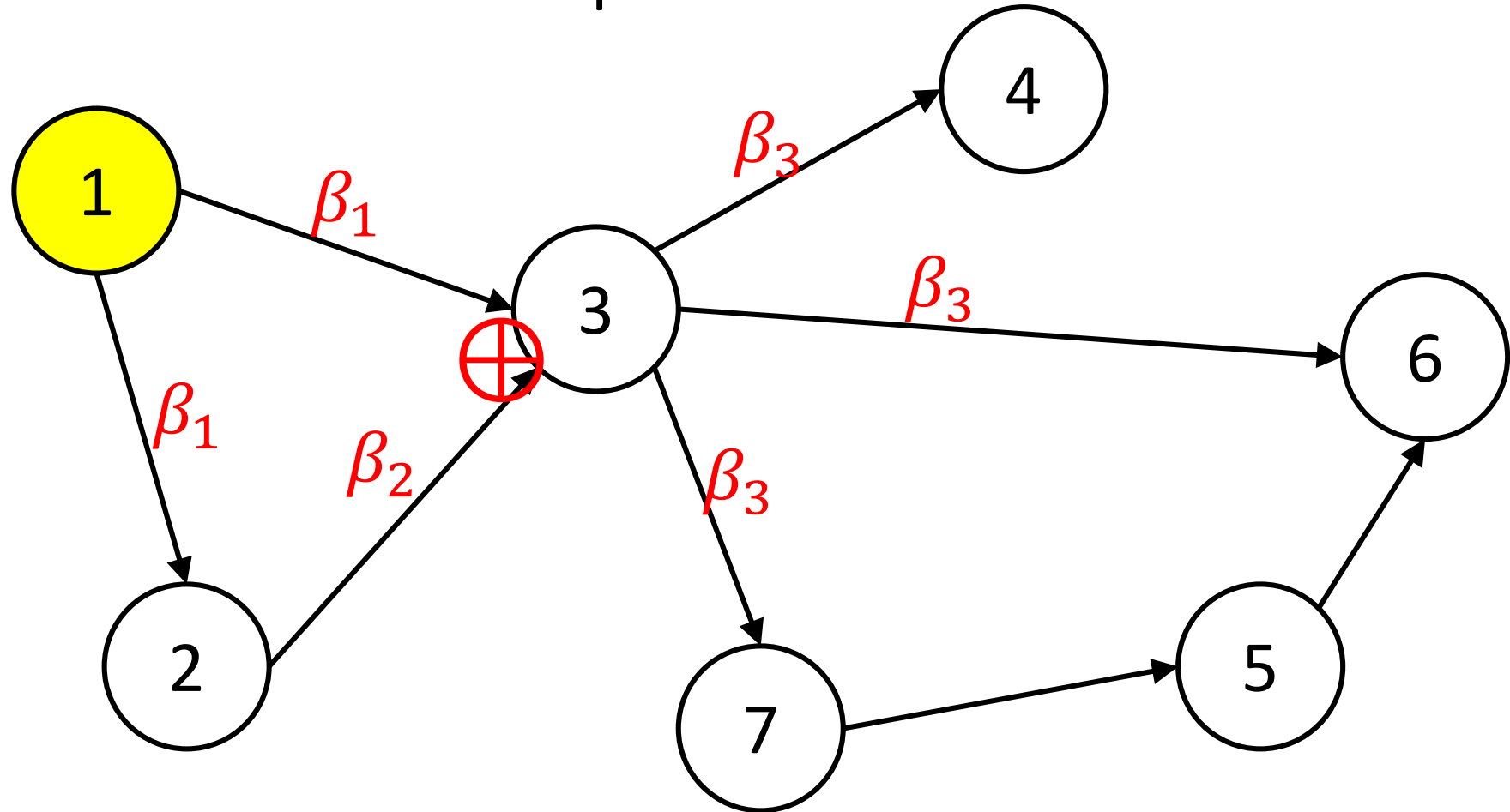
1. Learn attacker movement
2. Respond by limiting connectivity to stop spread
3. Recover the system

Lateral Movement Model

- Susceptible-infected-susceptible (SIS) CTMC virus spread model
- A node can be in two states: {**Susceptible**, **Infected**}
- Nodes are not cured



Virus Spread over Graph



- A node's infection rate depends on the state of neighboring nodes.
- Each node infects its neighbors with rate β_i .
- Each node is healed independently with rate δ_i .

Spread Dynamics

The total system dynamics as N-intertwined CTMCs:

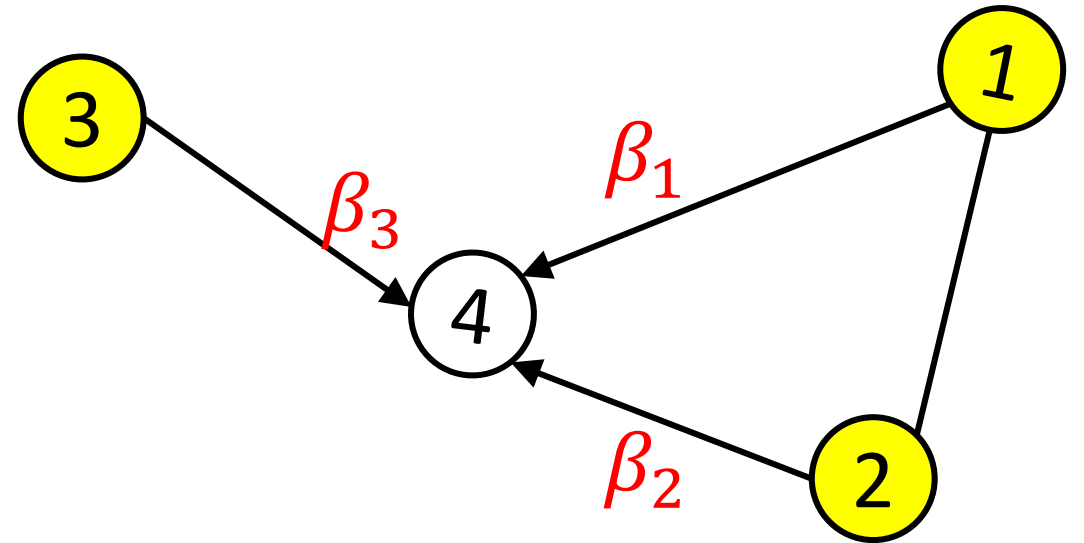
$$\dot{p} = (AB - P(t)AB - D)p$$

Controllable parameters:

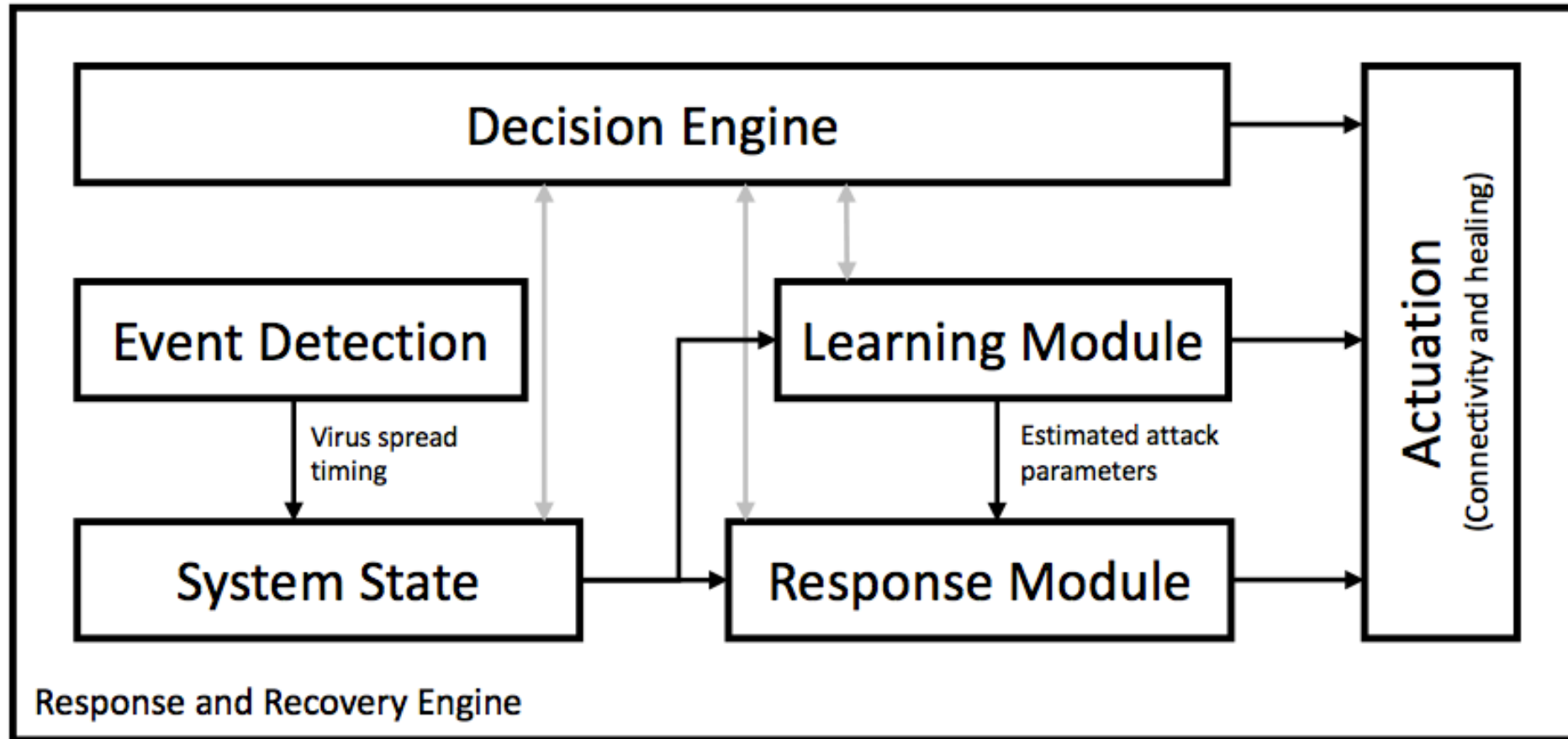
- The connectivity graph **A**
- The healing rate **D** = $\text{diag}(\delta_1, \dots, \delta_n)$

Unknown:

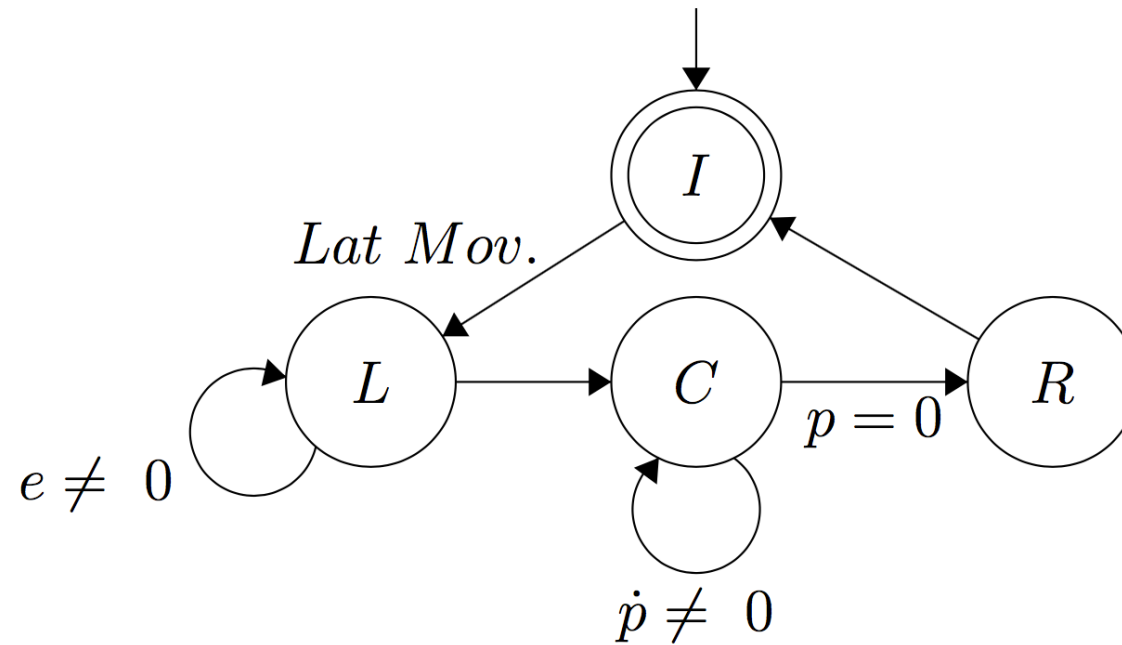
- The infection rate **B** = $\text{diag}(\beta_1, \dots, \beta_n)$



Response and Recovery Engine



RRE Decision Modes



Initial: no infection

Learn: estimate attacker parameters

Containment: stop attacker spread

Recovery: return system to secure state



Learning Phase

- Estimate the infection rate of each node when it's neighbors are infected.
- Measure the duration to infect a node using lateral movement chains

$$\mathcal{S}_i = (s_1, s_2, \dots, s_m) \quad \text{where} \quad s_i = t - t_{\text{healed}}$$

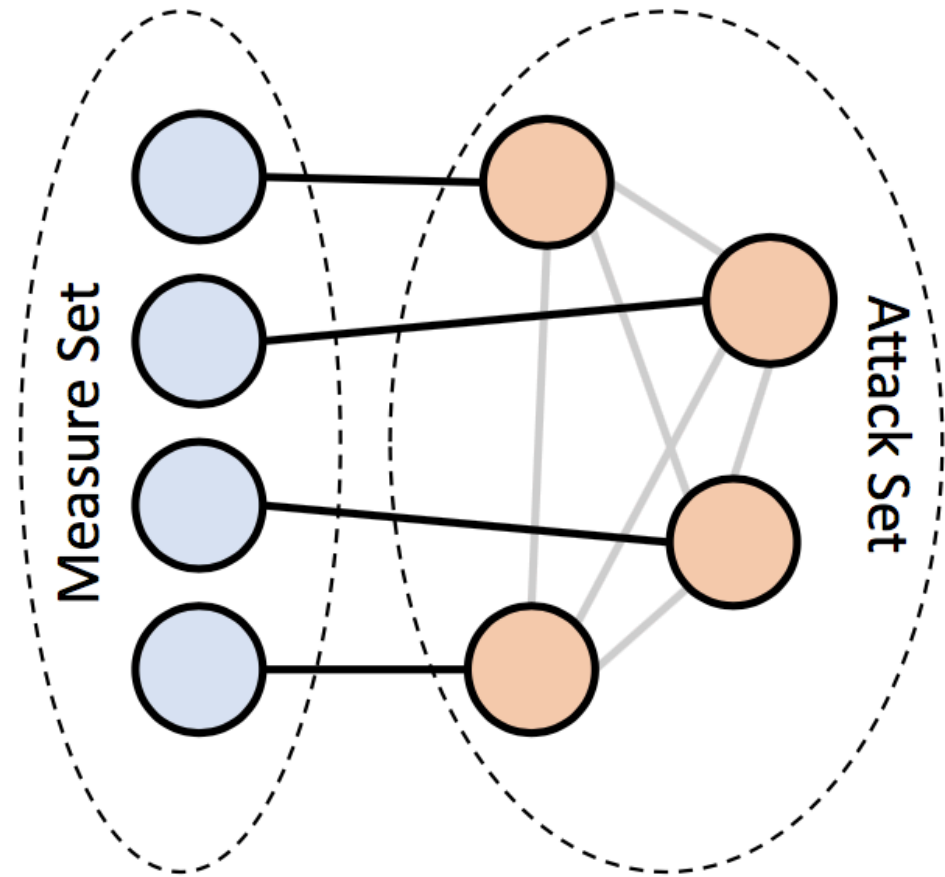
- Use the ML estimator: $\hat{\lambda}_i = \frac{m}{\sum_j s_i}$

Learning Strategy

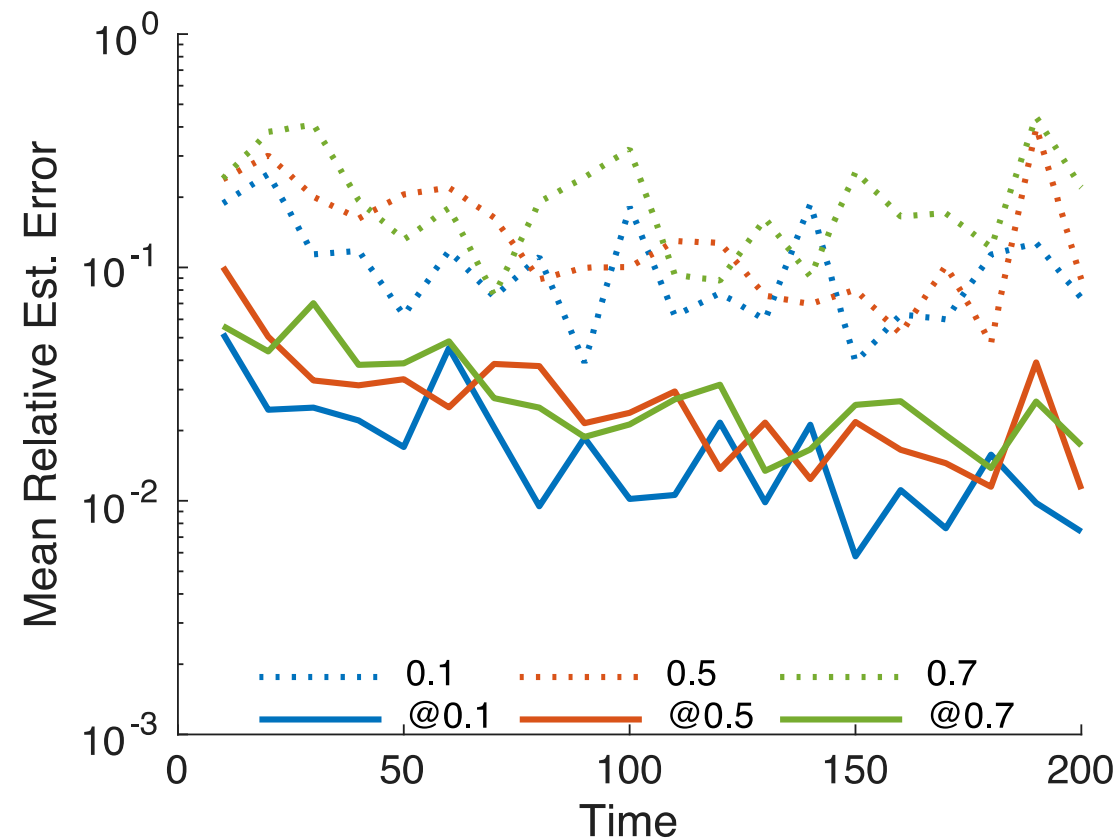
- Naïve approach: all nodes infected, heal one node at a time for sample collection
 - Slow learning
 - Highest availability
- Optimal approach: find independent sets as the minimal coloring of a graph
 - Finding coloring is NP-hard

Dynamic Strategy

- Divide nodes to attack set and measure set.
- Attack set is fully connected.
- Measure set has limited connectivity to the attack set.
- Switch the roles after data is collected.
- Solve: $A\beta = \hat{L}$



Estimation Error



- Error decreases as more data is collected
- A sparse connectivity matrix performs better overall

Containment Phase

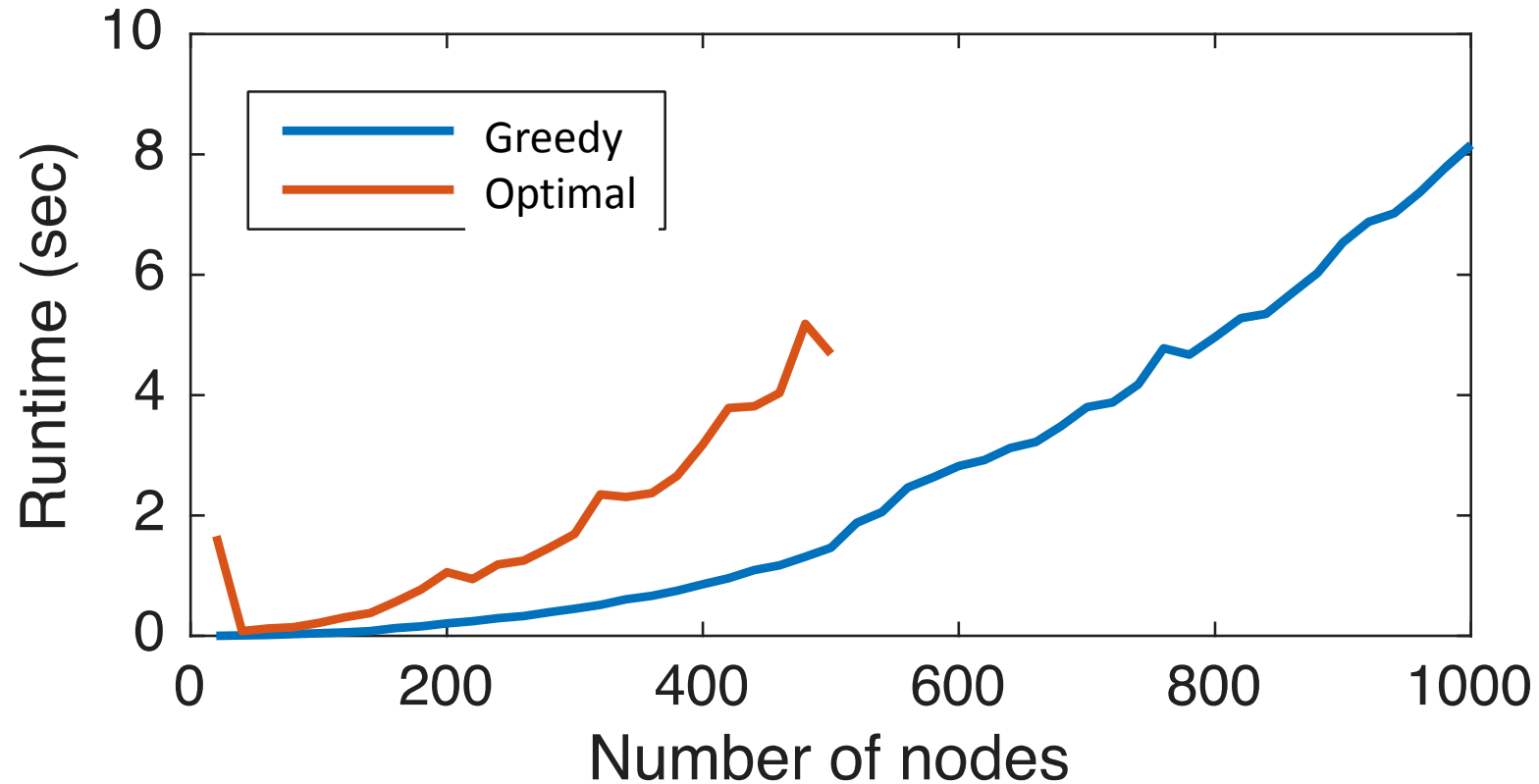
- After learning the parameters; we find the connectivity and healing rates to stop the spread
- **Goal:** achieve a globally asymptotic stable (GAS) disease-free equilibrium (DFE)
 - Starting from an initial state
 - Consequence: $p \rightarrow 0$ with an exponential decay
- Pick A, D such that $(AB-D)$ is Hurwitz

Resiliency during Containment

- Maximize availability such that A and D result in a stable DFE.
- Encoded as a Mixed-Integer Nonlinear Optimization Problem

$$\begin{array}{ll} \min_{A,d} & N^2 - \sum_i \sum_j a_{ij} \\ \text{Availability} & \text{s.t. } \max \lambda(A\hat{B} - \text{diag}(d)) < 0 \\ \text{Hurwitz Condition} & \sum_i d_i \leq c \\ \text{Limit cost} & A \in \{0, 1\}^{n \times n} \\ & d \in \mathbb{R}^n \end{array}$$

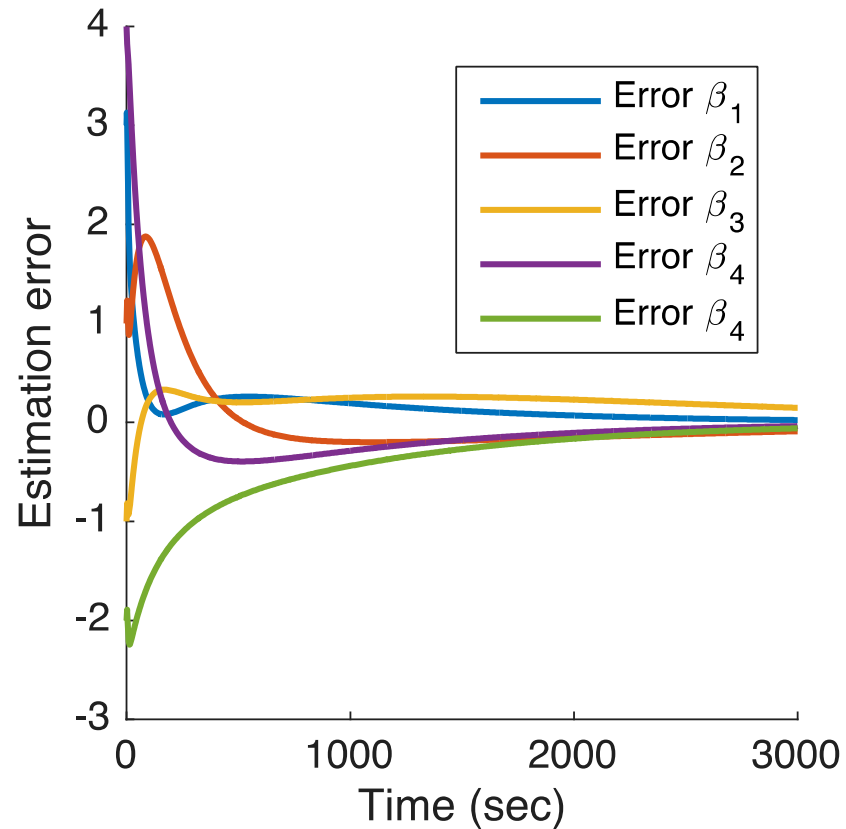
Connectivity matrix



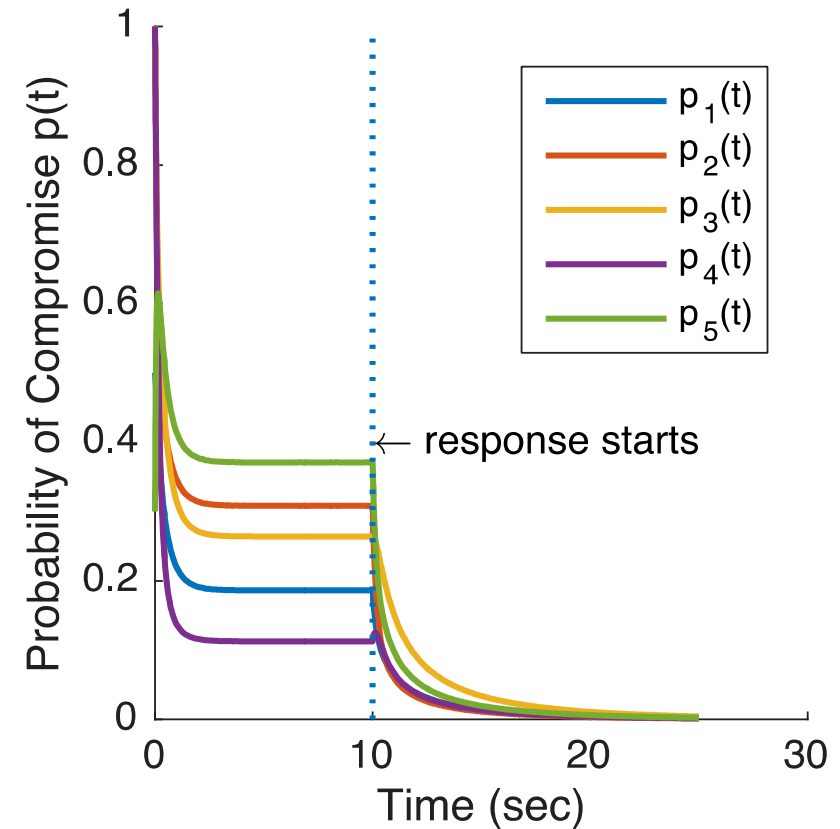
- The optimal solver cannot find matrices for $N > 500$
- The greedy solver is faster but the solutions are suboptimal

Simulation of RRE

Error of parameter estimation error



State evolution over time during the response phase



Parameters: $N=5$, topology changes, infection randomly selected for the experiment run, healing constant

Conclusion

- RRE achieves resilience by limiting connectivity during healing and learning
- Method is robust against estimation error and clock drifts
- Containment is theoretically fast

Future Work

- Design a feedback controller that uses learned estimates
 - Improve estimate
 - Robustness to errors
 - Maximize connectivity

State estimation: $\hat{p} = f(\tilde{\beta}, A, D)$

Measurements: $p = \{0,1\}$

Feedback controller: $D = \gamma \cdot \hat{p}$ such that $\gamma > 0$