Stability of Symplectic Leaves

Rui Loja Fernandes

Departamento de Matemática Instituto Superior Técnico

Paulette Libermann :: Héritage et Descendance (Institut Henri Poincaré, December 2009)

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- Establish stability results for symplectic leaves of Poisson manifolds;
- Understand the relationship between (apparently) distinct stability results in different geometric settings;

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Based on the paper:

• M. Crainic and RLF, Stability of symplectic leaves, Preprint arXiv:0810.4437 (to appear in *Inventiones Mathematicae*).

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Stability in Poisson geometry Universal Stability Theorem Proofs Flows Group actions Foliations

Flows: Stability of periodic orbits

Definition

A periodic orbit of a vector field $X \in \mathfrak{X}(M)$ is called stable if every nearby vector field also has a nearby periodic orbit.

Basic Fact: Stability is controlled by the Poincaré return map $h: T \rightarrow T$.

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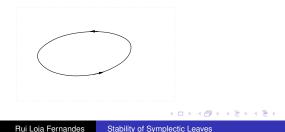
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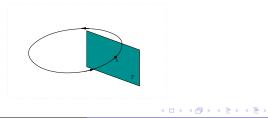
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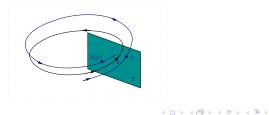
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Flows: Stability of periodic orbits

Simple assumptions on $d_x h$ lead to stability:

If 1 is not an eigenvalue of $d_x h$ then the orbit is stable. Consider the representation $\rho : \mathbb{Z} \to \operatorname{GL}(\nu(\mathcal{O})_x)$, defined by $n \cdot v := (d_x h)^n v.$

 $H^{\bullet}(\mathbb{Z}, \nu(\mathcal{O})_{x}) \equiv$ group cohomology with coefficients in $\nu(\mathcal{O})_{x}$.

Theorem

Let O be a periodic orbit of a vector field X and assume that

$$\mathcal{H}^1(\mathbb{Z},\nu(\mathcal{O})_x)=\mathbf{0}.$$

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Group actions: stability of orbits

■ Fix a manifold *M* and a Lie group *G* ■ Action α : *G* × *M* → *M* ⇔ homomorphism α : *G* → Diff(*M*)

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Group actions: stability of orbits

Fix a manifold *M* and a Lie group *G*

• Action α : $G \times M \to M \Leftrightarrow$ homomorphism α : $G \to \text{Diff}(M)$

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 $Act(G; M) \subset Maps(G; Diff(M))$

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Definition

An orbit \mathcal{O} of $\alpha \in Act(G; M)$ is called stable if every nearby action in Act(G; M) has a nearby orbit diffeomorphic to \mathcal{O} .

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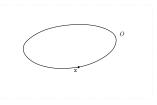
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Group actions: stability of orbits

The stability of an orbit \mathcal{O} is controlled by the isotropy representation:

 $\blacksquare \ G_x := \{g \in G : g \cdot x = x\} \text{ isotropy group at } x \in \mathcal{O}.$

■ $g \in G_x$ induces a map $\alpha_g : M \to M$, $y \mapsto g \cdot y$ that fixes x and maps the orbit to the orbit.



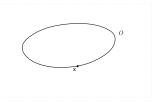
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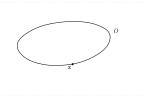


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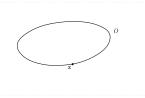


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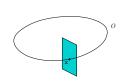
$$d_{x}\alpha_{g}: T_{x}M \to T_{x}M, d_{x}\alpha_{g}(T_{x}\mathcal{O}) = T_{x}\mathcal{O}.$$

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$$d_{x}\alpha_{g}: T_{x}M \to T_{x}M, d_{x}\alpha_{g}(T_{x}\mathcal{O}) = T_{x}\mathcal{O}.$$

$$\Rightarrow \rho(g): \nu(\mathcal{O})_{x} \to \nu(\mathcal{O})_{x}.$$

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Group actions: stability of orbits

Linear normal isotropy representation:

 $\rho: G_X \to GL(\nu(\mathcal{O})_X)$

 $H^{\bullet}(G_x, \nu(\mathcal{O})_x)$ denotes the corresponding group cohomology.

Theorem (Hirsch,Stowe)

Let O be a compact orbit and assume that

 $H^1(G_x,\nu(\mathcal{O})_x)=0.$

Then \mathcal{O} is stable: every nearby action has a family of nearby diffeomorphic orbits smoothly parametrized by $H^0(G_x, \nu(\mathcal{O})_x)$.

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Stability in Poisson geometry Universal Stability Theorem Proofs Flows Group actions Foliations

Foliations: stability of leaves

Fix a manifold *M* and denote by $Fol_q(M)$ the set of codimension *q* foliations. Frobenius says:

 $\operatorname{Fol}_q(M) \longleftrightarrow \{D : M \to \operatorname{Gr}_q(TM) | D \text{ is involutive} \}$

 \implies Fol_q(M) has a natural C^r-topology

Definition

A leaf *L* of a foliation $\mathcal{F} \in Fol_k(M)$ is called stable if every nearby foliation in $Fol_k(M)$ has a nearby leaf diffeomorphic to *L*.

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Foliations: stability of leaves

The stability of a leaf *L* is controled by the holonomy of *L*.



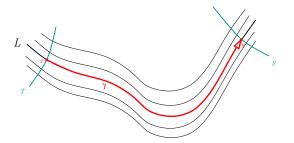
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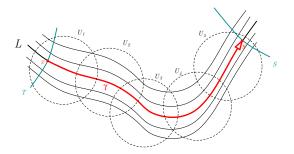
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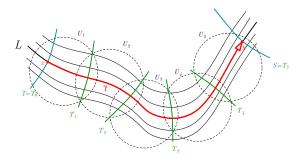
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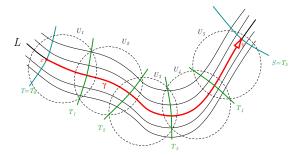


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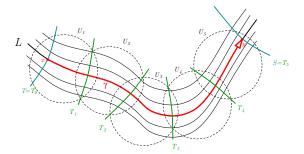
Fix $x \in L$ so that we have the holonomy homomorphism: Hol := Hol^{*T*,*T*} : $\pi_1(L, x) \rightarrow \text{Diff}_x(T)$.

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Note: The Poincaré return map is a special case of this.

Rui Loja Fernandes

Stability of Symplectic Leaves

Stability in Poisson geometry Universal Stability Theorem Proofs Flows Group actions Foliations

Foliations: stability of leaves

Differentiating gives the linear holonomy representation:

$$\rho: \pi_1(L, \mathbf{X}) \to GL(\nu(L)_{\mathbf{X}}), \quad \rho:= \mathrm{d}_{\mathbf{X}} \circ \mathrm{Hol}$$

 $H^{\bullet}(\pi_1(L, x), \nu(L)_x)$ denotes corresponding group cohomology.

Theorem (Reeb, Thurston, Langevin & Rosenberg)

Let L be a compact leaf and assume that

 $H^1(\pi_1(L, x), \nu(L)_x) = 0.$

Then L is stable: every nearby foliation has a family of nearby diffeomorphic leaves smoothly parametrized by $H^0(\pi_1(L, x), \nu(L)_x)$.

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Stability of leaves versus stability of orbits

In general, the two theorems are quite different (e.g., dimension of orbits of actions can vary).

However:

if G_x is discrete, dimension of orbits is locally constant;

if, additionally, *G* is 1-connected, then $\pi_1(\mathcal{O}, x) = G_x$;

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■ if, additionally, *G* is 1-connected, then $\pi_1(\mathcal{O}, x) = G_x$;

Then the linear holonomy coincides with the linear isotropy representation, and the theorem for actions follows from the theorem for foliations.

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Poisson structures Examples Cohomology Stability criteria

Poisson structures

For Poisson bracket $\{\ ,\ \}$ we denote by π the associated Poisson bivector:

 $\pi(\mathrm{d} f,\mathrm{d} g):=\{f,g\}.$

$$\mathsf{Poiss}(M) \quad \longleftrightarrow \quad \{\pi: M \to \wedge^2(TM) | \ [\pi,\pi] = 0\}.$$

 \Rightarrow Poiss(*M*) has a natural *C^r* topology

Definition

- stable if every nearby Poisson structure in Poiss(M) has a nearby leaf diffeomorphic to S.
- strongly stable if every nearby Poisson structure in Poiss(M) has a nearby leaf symplectomorphic to S.

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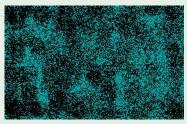
Definition

- stable if every nearby Poisson structure in Poiss(M) has a nearby leaf diffeomorphic to S.
- strongly stable if every nearby Poisson structure in Poiss(M) has a nearby leaf symplectomorphic to S.

Poisson structures Examples Cohomology Stability criteria

Examples (Constant and linear Poisson structures)

•
$$M = \mathbb{R}^2$$
 with $\pi = 0$

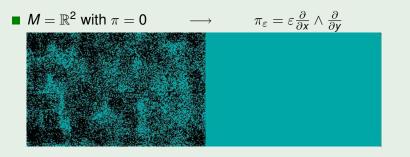


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Poisson structures Examples Cohomology Stability criteria

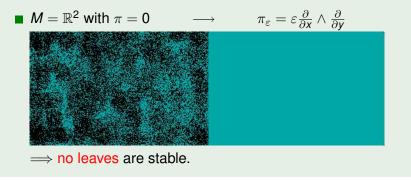
Examples (Constant and linear Poisson structures)



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Poisson structures Examples Cohomology Stability criteria

Examples (Constant and linear Poisson structures)



Rui Loja Fernandes Stability of Symplectic Leaves

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Poisson structures Examples Cohomology Stability criteria

Examples (Constant and linear Poisson structures)

$$\blacksquare M = \mathfrak{sl}^*(2,\mathbb{R}) \simeq \mathbb{R}^3$$

Rui Loja Fernandes Stability of Symplectic Leaves

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Poisson structures Examples Cohomology Stability criteria

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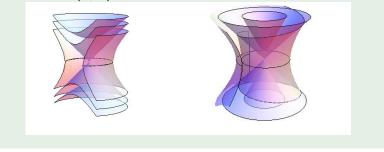
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Poisson structures Examples Cohomology Stability criteria

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Poisson structures Examples Cohomology Stability criteria

Examples (Constant and linear Poisson structures)

$$\blacksquare M = \mathfrak{sl}^*(2,\mathbb{R}) \simeq \mathbb{R}^3$$



 \implies some leaves are stable.

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Poisson structures Examples Cohomology Stability criteria

Examples (Constant and linear Poisson structures)

$$\blacksquare M = \mathfrak{su}^*(2) \simeq \mathbb{R}^3$$

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Poisson structures Examples Cohomology Stability criteria

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Rui Loja Fernandes Stability of Symplectic Leaves

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Poisson structures Examples Cohomology Stability criteria

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Poisson structures Examples Cohomology Stability criteria

Poisson cohomologies

Stability of a symplectic leaf *S* of a Poisson manifod (M, π) is controled by certain cohomologies:

- Poisson cohomology: $H^{\bullet}_{\pi}(M)$ is the cohomology of $(\mathfrak{X}^{k}(M), d_{\pi})$, the complex of multivector fields with $d_{\pi} := [\pi,]$.
- **Restricted Poisson cohomology**: $H^{\bullet}_{\pi,S}(M)$ is the cohomology of $(\mathfrak{X}^{\bullet}_{S}(M), \mathrm{d}_{\pi}|_{S})$, the complex of multivector fields along *S*.
- Relative Poisson cohomology: $H^{\bullet}_{\pi}(M, S)$ is the cohomology of the quotient complex:

$$\mathfrak{X}^{\bullet}(M, S) := \mathfrak{X}^{\bullet}_{S}(M) / \Omega^{\bullet}(S)$$

(the inclusion $\Omega^{\bullet}(S) \hookrightarrow \mathfrak{X}^{\bullet}_{S}(M)$ is obtained by dualizing the anchor $\pi^{\sharp} : T^{*}_{S}M \longrightarrow TS$).

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Poisson structures Examples Cohomology Stability criteria

Stability

Theorem (Crainic & RLF)

Let S be a compact symplectic leaf and assume that

 $H^2_{\pi}(M,S)=0.$

Then *S* is stable: every nearby Poisson structure has a family of nearby diffeomorphic leaves smoothly parametrized by $H^1_{\pi}(M, S)$.

- The relative Poisson cohomology $H^{\bullet}_{\pi}(M, S)$ is typically finite dimensional.
- $H^1_{\pi}(M, S)$ coincides with the space of leaves of the first jet approximation $j^1_S \pi$ which project diffeomorphically to *S*.
- Again, this result is quite different from the previous ones.

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Poisson structures Examples Cohomology Stability criteria

Strong stability

Theorem (Crainic & RLF)

Let S be a compact symplectic leaf and assume that

 $H^2_{\pi,S}(M)=0.$

Then *S* is strongly stable: every nearby Poisson structure has a family of nearby symplectomorphic leaves smoothly parametrized by by the image of $\Phi : H^1_{\pi,S}(M) \to H^1_{\pi}(M,S)$.

- The parameter space of strongly stable leaves is a subspace of the parameter space for stable leaves.
- It coincides with the space of leaves of j¹_Sπ which project diffeomorphically to S and which have symplectic form isotopic to ω_S.

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Poisson structures Examples Cohomology Stability criteria

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Poisson structures Examples Cohomology Stability criteria

Stability versus strong stability

The condition for strong stability (i.e., $H^2_{\pi,S}(M) = 0$) **does not** imply the condition for stability ($H^2_{\pi}(M, S) = 0$).

Conjecture

If S is a compact symplectic leaf and the map

 $\Phi: H^2_{\pi,S}(M) \to H^2_{\pi}(M,S)$

vanishes, then any Poisson structure close enough to π admits at least one nearby symplectic leaf diffeomorphic to S.

There is a similar conjecture for group actions due to Stowe (still open?).

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Poisson structures Examples Cohomology Stability criteria

Necessary conditions for stability

A Poisson structure π is said to be of first order around a symplectic leaf *S* if π is Poisson diffeomorphic to $j_S^1 \pi$ in some neighborhood of *S*.

Theorem (Crainic & RLF)

Let π be a Poisson structure which is of first order around a compact symplectic leaf S. Then:

(i) If *S* is stable, then the map $\Phi : H^2_{\pi,S}(M) \to H^2_{\pi}(M,S)$ vanishes.

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Poisson structures Examples Cohomology Stability criteria

Example: dual of a Lie algebra

$M = \mathfrak{g}^*$ where \mathfrak{g} is a compact semi-simple Lie algebra:

- Symplectic leaves are the coadjoint orbits: $S = O_{\xi}$;
- All leaves satisfy criteria for stability and strong stability: $H^2_{\pi,S}(M) = H^2_{\pi}(M, S) = 0.$
- We have $H^1_{\pi,S}(M) = H^2(S)$ and $H^1(M, S) = 0$;

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Conclusion: Every nearby Poisson structure has a one nearby symplectic leaf symplectomorphic to *S* and a dim $Z(\mathfrak{g}_{\xi})$ -family of symplectic leaves diffeomorphic to *S*.

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Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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Basic problem

Is there a general setup to deal with stability problems?

To answer this question one requires a setup where geometric objects such as flows, actions, foliations, Poisson structures, etc., are all on equal footing.

⇒ Lie groupoids/algebroids

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Lie theory

Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

Lie algebroids

Definition

A Lie algebroid is a vector bundle $A \rightarrow M$ with:

- (i) a Lie bracket $[,]_A : \Gamma(A) \times \Gamma(A) \rightarrow \Gamma(A);$
- (ii) a bundle map $\rho : A \rightarrow TM$ (the anchor);

such that:

$$[\alpha, f\beta]_{\mathcal{A}} = f[\alpha\beta]_{\mathcal{A}} + \rho(\alpha)(f)\beta, \quad (f \in C^{\infty}(\mathcal{M}), \alpha, \beta \in \Gamma(\mathcal{A})).$$

m $\rho \subset TM$ is a integrable (singular) distribution \downarrow Lie algebroids have a characteristic foliation

Lie theory

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Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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Lie algebroids Examples

Flows. For $X \in \mathfrak{X}(M)$, the associated Lie algebroid is: $A = M \times \mathbb{R}, \quad [f, g]_A := fX(g) - gX(f), \quad \rho(f) = fX.$ Leaves of *A* are the orbits of *X*.

Actions. For α ∈ Act(G; M), the associated Lie algebroid is:
 A = M × g, ρ = infinitesimal action,
 [f, g]_A(x) = [f(x), g(x)]_g + L_{ρ(f(x))}g(x) - L_{ρ(g(x))}f(x).
 Leaves of A are the orbits of α (for G connected).

Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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Lie algebroids Examples

■ Foliations. For *F* ∈ Fol_k(*M*), the associated Lie algebroid is:

$$A = T\mathcal{F}, \quad [X, Y]_A = [X, Y], \quad \rho = \mathsf{id}.$$

Leaves of A are the leaves of \mathcal{F} .

Poisson structures. For $\pi \in \text{Poiss}(M)$, the associated Lie algebroid is:

 $A = T^*M, \quad \rho = \pi^{\sharp},$ $[df, dg]_A = d\{f, g\}, \quad (f, g \in C^{\infty}(M)).$

Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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 Leaves of \mathcal{A} are the symplectic leaves of π .

Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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Universal Stability Theorem

For a fixed vector bundle A there is a natural C' topology on the set Algbrd(A) of Lie algebroid structures on A.

A leaf L of A is called stable if every nearby Lie algebroid structure in Algbrd(A) has a nearby leaf diffeomorphic to L.

The normal bundle $\nu(L)$ carries a canonical Bott type $A|_L$ -connection.

• One can define the restricted A-cohomology with coefficients in $\nu(L)$, denoted $H^{\bullet}(A|_L; \nu(L))$.

Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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Universal Stability Theorem

Theorem (Crainic & RLF)

Let L be a compact leaf of A, and assume that $H^1(A|_L; \nu(L)) = 0$. Then L is stable: every nearby Lie algebroid has a family of nearby leaves smoothly parametrized by $H^0(A|_L; \nu_L)$.

- The parameter space be characterized as the space of leaves of the first jet approximation to the Lie algebroid A along L.
- For Lie algebroid structures of first order type around L the condition in the theorem is also a necessary condition for stability.

Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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From Lie algebr(oids) to Lie group(oids)

The fundamental group of A based at x: $G_x(A) = \frac{\{A \text{-loops based at } x\}}{A \text{-homotopies}}.$

• $G_x(A)$ need not be smooth. If it is smooth, then it is a Lie group integrating the isotropy Lie algebra $g_x(A)$.

Parell transport along A-paths applied to the Bott representation of A|_L gives the linear holonomy representation:

hol :
$$G_X(A) \longrightarrow GL(\nu(L)_X)$$
.

Proposition

If $G_x(A)$ is smooth, then for any $x \in L$:

 $H^1(A|_L;\nu(L)) \cong H^1(G_x(A);\nu(L)_x).$

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Rui Loja Fernandes

Stability of Symplectic Leaves

Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

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Recovering the stability theorems:

Foliations: If $A = T\mathcal{F}$, then $G_x(A) = \pi_1(L, x)$, the Bott representation becomes the usual one on $\nu(L)$, and we have:

$$H^1(A|_L; \nu(L)) \cong H^1(\pi_1(L, x); \nu(L)_x).$$

We recover the classical result.

Actions: If $A = \mathfrak{g} \ltimes M$ is associated with a 1-connected Lie group *G*, then $G_x(A) = G_x$, the Bott representation becomes the linear isotropy Lie algebra on $\nu(\mathcal{O})_x$ and we have:

 $H^1(A; \nu(\mathcal{O})) \cong H^1(G_x; \nu(\mathcal{O})_x).$

We recover the classical result under the assumption that *G* is 1-connected.

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We recover the classical result under the assumption that G is 1-connected.

Lie theory Universal Stability Theorem From Lie algebr(oids) to Lie group(oids) Recovering the stability theorems Poisson vs algebroid stability

Poisson vs algebroid stability Examples

 $M = \mathfrak{g}^*$ with \mathfrak{g} the non-abelian 2-dimensional Lie algebra:

$$\pi = \mathbf{x} \frac{\partial}{\partial \mathbf{x}} \wedge \frac{\partial}{\partial \mathbf{y}}$$

so that $A = T^* \mathbb{R}^2$ and $[dx, dy] = dx, \quad \rho(dx) = x \frac{\partial}{\partial y}, \quad \rho(dy) = -x \frac{\partial}{\partial x}.$

• $H^2_{\pi,0}(\mathfrak{g}^*) = H^2(\mathfrak{g}) = 0$, so the origin is Poisson stable;

- $\blacksquare H^1(A|_0,\nu(\{0\})) = H^1(\mathfrak{g},\mathfrak{g}) = \mathbb{R};$
- The origin is not algebroid stable: take $A_{\varepsilon} = T^* \mathbb{R}^2$ with

$$[\mathrm{d}x,\mathrm{d}y]_{\varepsilon} = \mathrm{d}x, \quad \rho_{\varepsilon}(\mathrm{d}x) = x\frac{\partial}{\partial y}, \quad \rho_{\varepsilon}(\mathrm{d}y) = -x\frac{\partial}{\partial x} + \varepsilon\frac{\partial}{\partial y}.$$

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Poisson vs algebroid stability Examples

 $M = S \times \mathbb{R}$ with leaves $(S \times \{t\}, \omega_t)$. Look at stability of $S = S \times \{0\}$.

• Set $\sigma := \frac{d}{dt} \omega_t |_{t=0}$ and define:

 $C^{ullet}_{\sigma}(S) = \Omega^{ullet}(S) \oplus \Omega^{ullet-1}(S), \quad \mathrm{d}_{\sigma}(\omega,\eta) = (\mathrm{d}\omega + \sigma \wedge \eta, \mathrm{d}\eta)$

• One finds that:

 $\mathfrak{X}^{ullet}_{\pi}(M,S) \cong \Omega^{ullet-1}(S), \quad \mathfrak{X}^{ullet}_{\pi,S}(M) \cong C^{ullet}_{\sigma}(S) \cong \mathfrak{X}^{ullet}(T^*_SM;\nu(S))$

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Conclusion: the criteria for stability of symplectic leaves in the Poisson setting is stronger than the criteria arising from the general algebroid setting.

- There are Poisson structures π such that $A = T^*M$ has many closeby Lie algebroids which are not associated with a Poisson structure.
- There is a chain map $i : \mathfrak{X}^{\bullet}(M, S) \to \mathfrak{X}^{\bullet-1}(T^*_S M; \nu(S))$ inducing an injection in degree 2:

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Some non-sense about the proofs

■ All the stability theorems above say: infinitesimal stability ⇒ stability.

Likewise, the proof of each such stability theorem is a "infinite dimensional transversality argument".

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