

## Curriculum Vitae of Kwang-Ki K. Kim

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CONTACT INFORMATION I	Talbot Laboratory, Room 330C Department of Aerospace Engineering University of Illinois at Urbana-Champaign Urbana, IL 61802 USA	<i>Voice:</i> (217) 721-6482 <i>Fax:</i> (217) 244-0720 <i>E-mail:</i> kkim78@illinois.edu <i>Webpage:</i> <a href="https://netfiles.uiuc.edu/kkim78/www/">https://netfiles.uiuc.edu/kkim78/www/</a>
CONTACT INFORMATION II	77 Massachusetts Avenue, Room 66-060 Department of Chemical Engineering Massachusetts Institute of Technology Cambridge, MA 02139 USA	<i>Voice:</i> (617) 253-3112 <i>Fax:</i> (617) 258-0546 <i>E-mail:</i> kwangki@mit.edu <i>Webpage:</i>
RESEARCH INTERESTS	<ul style="list-style-type: none"> <li>• Robust Control Theory: Structure singular value (<math>\mu</math>) theory, Integral quadratic constraints (IQCs) (including full-block S-procedure and quadratic separators), Lyapunov-based analysis and control</li> <li>• Large-scale Interconnected/Networked Systems Analysis and Synthesis (Robust control perspective approaches for scalable and decomposable robust stability and performance guarantees)</li> <li>• Analysis and Synthesis Problems of Nonlinear Dynamical Systems</li> <li>• Real-time Model-based Predictive Suboptimal Control (a.k.a. “Model Predictive Control (MPC)”)</li> <li>• Model-based Statistical Fault Detection and Diagnosis with Integration into Stochastic Robust Model Predictive Control or Approximate Dynamic Programming</li> <li>• Bayesian and Non-Bayesian Inference, and Information Theory</li> <li>• Approximate Dynamic Programming (Dual Adaptive Control, Neuro-dynamic Programming, Temporal Difference Learning (TD(<math>\lambda</math>)), Q-Learning, etc.)</li> <li>• Optimization of Nonlinear Robust Controllers (a.k.a. “Adaptive Control”)</li> <li>• Optimization Theory and Algorithms (LP, QP, SDP, SOS, etc.)</li> <li>• Robust Optimization</li> <li>• Stochastic Programming</li> <li>• Convex Relaxation for Non-Convex Optimization</li> <li>• Deterministic and Stochastic Reachability Analysis and Viability Theory</li> <li>• Parameter Estimation for Mathematical System Models (a.k.a. “System Identification”)</li> <li>• Identification for Deterministic/Stochastic Robust Control: Dual Control Approaches</li> <li>• Robust Model Invalidation and Fault Detection &amp; Diagnosis</li> <li>• Behavioral Approaches for Analysis and Control of Uncertain Systems</li> <li>• <i>Applications</i> <ul style="list-style-type: none"> <li>- Nonlinear Internal Model Control</li> <li>- Formation and Collision Avoidance Control for Large-scale Multi-agent Systems</li> <li>- Analysis and Control of Interconnected Gene Regulatory Systems</li> <li>- Analysis and Control of Power Flow and Distribution Algorithms</li> <li>- Parameter and State Estimation for Detecting Local Concentration using Biosensors</li> <li>- Parameter Estimation and Sensitivity Analysis for Multidimensional Population Balance Models</li> <li>- Quality by Design for Manufacturing Process</li> </ul> </li> </ul>	

## EDUCATION

### **University of Illinois**, Urbana-Champaign, Illinois USA

Ph.D. Candidate, Aerospace Engineering, August 2009 (expected graduation date: February 2013)

- Dissertation Topic: “Deterministic and Stochastic, Model-based Robust and Adaptive Control of Uncertain Systems: Optimization Approaches”
- Advisor: Prof. Richard D. Braatz (MIT)

M.S., Aerospace Engineering, August 2009

- Dissertation: “Robust Control for Systems with Sector-bounded, Slope-restricted, and Odd Monotonic Nonlinearities Using Linear Matrix Inequalities”
- Advisor: Prof. Richard D. Braatz (MIT)

### **Massachusetts Institute of Technology**, Cambridge, Massachusetts USA

Visiting Graduate Student, November 2010 – May 2012

- Research Projects: “Stochastic Robust Fault Tolerant Model Predictive Control”, “Optimal Experiment Design for System Identification and Fault Detection & Diagnosis”, and “Robust Approximate Dynamic Programming”
- Advisor: Prof. Richard D. Braatz (MIT)

### **Yonsei University**, Seoul, Korea

B.S., Astronomy (Concentration on Astrophysics including Celestial Mechanics and Minor degree in Mechanical Engineering), February 2007

Graduate Student, Astronomy, February 2007 – August 2007

- Research Projects: “Optimal Trajectory Generation and Trajectory Estimation of Spacecrafts” and “Attitude Control of Small Satellites Using Magnetic Actuators”
- Advisor: Prof. Sang-Young Park (Yonsei University)

## HONORS AND AWARDS

- IEEE Multi-Conference on Systems and Control (MSC) Best Student Paper Award Finalist, 2012
- IFAC 3rd Workshop on Distributed Estimation and Control in Networked Systems (aka NECSYS) Best Student Paper Award Finalist, 2012
- IEEE Multi-Conference on Systems and Control (MSC) Best Student Paper Award Finalist, 2011
- Yonsei University: Highest Honors (The highest 1% GPA students honors), 2007
- Brain Korea (BK) Scholarship (awarded by Korean Ministry of Education), 2007
- National Research Laboratory (NRL) Fellowship (awarded by Korean Science and Engineering Foundation), 2007

## ACADEMIC EXPERIENCE

### **Yonsei University**, Seoul, Korea

*Graduate Student*

**February 2007 - August 2007**

Includes research projects sponsored by Ministry of Science and Technology of Korea.

### **University of Illinois**, Urbana-Champaign, Illinois USA

*Graduate Student*

**August 2007 - present**

Includes current Ph.D. research, Ph.D. and Masters level coursework (concentration on mathematical system and control theory, and optimization theory and algorithms) and research/consulting projects.

### **Massachusetts Institute of Technology**, Cambridge, Massachusetts USA

*Visiting Graduate Student*

**November 2010 - May 2012**

Includes current Ph.D. research and research/consulting projects.

## JOURNAL PUBLICATIONS

1. **K.-K. K. Kim**, E. R. Petron and R. D. Braatz. “Robust Nonlinear Internal Model Control of

Wiener Systems.” *Journal of Process Control*, 22(8): 1468–1477, 2012

2. **K.-K. K. Kim**, E. R. Petron and R. D. Braatz. “Universal Approximation with Error Bounds, Standard Representation, and Unified Stability Analysis for Dynamic Artificial Neural Network Models.” *International Journal of Robust and Nonlinear Control* (under review)
3. **K.-K. K. Kim** and R. D. Braatz. “Robust Static and Fixed-order Dynamic Output Feedback Control of Discrete-time Parametric Uncertain Lure Systems: SDP Approaches.” *International Journal of Robust and Nonlinear Control* (under review)
4. **K.-K. K. Kim** and R. D. Braatz. “Observer-based Output Feedback Control of Discrete-time Lure Systems with Sector-bounded Slope-restricted Nonlinearities.” *International Journal of Robust and Nonlinear Control* (accepted with minor revision)
5. **K.-K. K. Kim**, S. Skogestad, M. Morari, and R. D. Braatz. “Necessary and Sufficient Conditions for Robust Reliable Control in the Presence of Model Uncertainties and Actuator/Sensor Faults and Failures.” *Computer & Chemical Engineering* (forthcoming)
6. **K.-K. K. Kim** and R. D. Braatz. “Computational Complexity and Related Topics of Robustness Margin Calculation using SSV Theory: A Review of Theoretical and Algorithmic Developments.” *Computer & Chemical Engineering* (forthcoming)
7. **K.-K. K. Kim** and N. Hovakimyan. “Multi-Criteria Optimization for Filter Design of  $\mathcal{L}_1$  Adaptive Control.” *Journal of Optimization Theory and Applications* (under review)

CONFERENCE  
PROCEEDINGS  
(REFEREED)

1. **K.-K. K. Kim** and N. Hovakimyan. “Development of Verification and Validation Approaches for  $\mathcal{L}_1$  Adaptive Control: Multi-Criteria Optimization for Filter Design.” AIAA Guidance, Navigation, and Control Conference, Toronto, Canada, 2010
2. **K.-K. K. Kim** and R. D. Braatz. “Observer-based Output Feedback Control of Discrete-time Luré Systems with Sector-bounded Slope-restricted Nonlinearities.” American Control Conference, San Francisco, SF, 2011
3. **K.-K. K. Kim** and R. D. Braatz. “Robust Static and Fixed-order Dynamic Output Feedback Control of Discrete-time Luré Systems.” IFAC World Congress, Milano, Italy, 2011
4. **K.-K. K. Kim**, E. R. Petron and R. D. Braatz. “Universal Approximation with Error Bounds for Dynamic Artificial Neural Network Models: A Tutorial and Some New Results.” IEEE Multi-Conference on Systems and Control, Denver, CO, 2011
5. **K.-K. K. Kim**, E. R. Petron and R. D. Braatz. “Standard Representation and Stability Analysis of Dynamic Artificial Neural Networks: A Unified Approach.” IEEE Multi-Conference on Systems and Control, Denver, CO, 2011
6. E. Kharisov, **K.-K. K. Kim**, X. Wang and N. Hovakimyan. “Limiting Behavior of  $\mathcal{L}_1$  Adaptive Controllers.” AIAA Guidance, Navigation, and Control Conference, Portland, Oregon, 2011
7. **K.-K. K. Kim**, E. Kharisov and N. Hovakimyan. “Filter Design for  $\mathcal{L}_1$  Adaptive Output-Feedback Controller.” IEEE Conference on Control and Decision, Orlando, FL, 2011
8. **K.-K. K. Kim** and R. D. Braatz. “Probabilistic Analysis and Control of Uncertain Dynamic Systems: Generalized Polynomial Chaos Expansion Approaches.” American Control Conference, Montreal, Canada, 2012
9. **K.-K. K. Kim**, K. S. Cheong, K. Chen and R. D. Braatz. “Parameter Estimation, Analysis, and Design of Synthetic Gene Switching Models: System Behavior- and Performance-based Approaches.” IFAC ADCHEM, Singapore, 2012
10. **K.-K. K. Kim** and R. D. Braatz. “On the Robustness of Interconnected or Networked Uncertain Multi-agent Systems.” 20th International Symposium on Mathematical Theory of Networks and Systems, Melbourne, Australia, 2012

11. **K.-K. K. Kim** and R. D. Braatz. “Remarks on Convex Stability Conditions for Interconnected or Networked Linear Multi-agent Systems.” 3rd IFAC Workshop on Distributed Estimation and Control in Networked Systems, Santa Barbara, SF, 2012
12. **K.-K. K. Kim** and R. D. Braatz. “Generalized Polynomial Chaos Expansion Approaches to Approximate Stochastic Receding Horizon Control with Applications to Probabilistic Collision Checking and Avoidance.” IEEE Multi-Conference on Systems and Control, Dubrovnik, Croatia, 2012
13. **K.-K. K. Kim** and R. D. Braatz. “Continuous- and Discrete-time D-Stability, and Joint D-Stability of Interconnected Systems:  $\mu$  Theory and Diagonal Stability Approaches.” IEEE Conference on Control and Decision, Hawaii, 2012
14. H. Jang, **K.-K. K. Kim**, J. H. Lee and R. D. Braatz. “Fast Moving Horizon Estimation for a Distributed Parameter System.” 12th International Conference on Control, Automation and Systems, Jeju Island, Korea, 2012
15. **K.-K. K. Kim** and R. D. Braatz. “Further Remarks on Robustness Analysis of Uncertain Linear Descriptor Systems: Unified Approaches using gLFT, LMI, and SSV.” American Control conference, Washington, DC, 2013 (under review)
16. **K.-K. K. Kim** and R. D. Braatz. “Convex Relaxation of Sequential Optimal Input Design for a Class of Structured Large-scale Systems: Process Gain Estimation.” American Control conference, Washington, DC, 2013 (under review)
17. **K.-K. K. Kim** and R. D. Braatz. “Optimal Input Design for System Identification via Adaptation and Receding Horizon Methods: Semidefinite Programming Relaxation Approaches.” American Control conference, Washington, DC, 2013 (under review)
18. **K.-K. K. Kim** and R. D. Braatz. “Semidefinite Programming Relaxation of Optimum Active Input Design for Fault Detection and Diagnosis: Model-based Finite Horizon Prediction.” European Control Conference, Zurich, Switzerland, 2013 (under review)
19. **K.-K. K. Kim** and R. D. Braatz. “Linear Lyapunov Functional for Cone Invariant LTI Systems: An Alternative to Copositive Quadratic Lyapunov Solutions.” European Control Conference, Zurich, Switzerland, 2013 (under review)
20. **K.-K. K. Kim**, Davide M. Raimondo and R. D. Braatz. “Optimum Input Design for Fault Detection and Diagnosis: Model-based Prediction and Statistical Distance Measures.” European Control Conference, Zurich, Switzerland, 2013 (under review)

CONFERENCE  
PROCEEDINGS  
(ABSTRACT)

1. H. Jang, **K.-K. K. Kim**, J. H. Lee and R. D. Braatz. “Design of a Parameter and State Estimation Method for Detecting Local Concentration On the Surface of a Carbon-Nanotube Based Sensor.” AIChE 2012 Annual Meeting, Pittsburgh, PA, 2012
2. M. Jiang, X. Zhu, M. Molaro, M. L. Rasche, D. M. Raimondo, **K.-K. K. Kim**, H. Zhang, K. Chadwick, L. Zhou, Z. Zhu, M. Wong, D. O’Grady, D. Hebrault, J. Tedesco. and R. D. Braatz. “A multidimensional population balance model for growth and dissolution identified from a designed temperature-cycling experiment.” AIChE 2012 Annual Meeting, Pittsburgh, PA, 2012. Abstract 604g.

PAPERS IN  
PREPARATION

1. **K.-K. K. Kim** and R. D. Braatz. “Fault Tolerant Stochastic Robust Model Predictive Control: Bayesian Tests and Model Switching.” IEEE Conference on Control and Decision, Firenze, Italy, 2013 (under preparation for conference proceedings)
2. **K.-K. K. Kim** and R. D. Braatz. “Approximate Dynamic Programming Approaches to Chance Constrained Stochastic MPC.” IEEE Conference on Control and Decision, Firenze, Italy, 2013 (under preparation for conference proceedings)

3. **K.-K. K. Kim** and R. D. Braatz. “Conic Lyapunov Theory: Dissipation Inequalities and Robustness.” IEEE Conference on Control and Decision, Firenze, Italy, 2013 (under preparation for conference proceedings)
4. **K.-K. K. Kim** and R. D. Braatz. “Mathematical Programs for Characterizing Design Space of Quality-by-Design: A Unification.” IEEE Conference on Control and Decision, Firenze, Italy, 2013 (under preparation for conference proceedings)
5. **K.-K. K. Kim** and R. D. Braatz. “Statistical Approaches for Characterizing Design Space of Quality-by-Design.” IEEE Conference on Control and Decision, Firenze, Italy, 2013 (under preparation for conference proceedings)
6. **K.-K. K. Kim** and R. D. Braatz. “Bayesian Inference Problems for Identification of Biochemical Reaction Networks.” IEEE Conference on Control and Decision, Firenze, Italy, 2013 (under preparation for conference proceedings)

INVITED TALKS

- **MIT Process Systems Engineering Laboratory Seminar Series** **March, 2012**  
*“Robust Static and Fixed-order Dynamic Output Feedback Control of Discrete-time Uncertain Luré Systems: SDP Approaches”*

PROFESSIONAL EXPERIENCE

<b>Journal of Process Control, IFAC:</b> <i>Reviewer</i>	<b>2008 - Present</b>
<b>Automatica, IFAC:</b> <i>Reviewer</i>	<b>2009 - Present</b>
<b>IEEE Transaction on Control Systems Technology, IEEE CSS:</b> <i>Reviewer</i>	<b>2009 - Present</b>
<b>IEEE Transaction on Automatic Control, IEEE CSS:</b> <i>Reviewer</i>	<b>2011 - Present</b>
<b>IEEE Control Systems Magazine, IEEE CSS:</b> <i>Reviewer</i>	<b>2012 - Present</b>
<b>IEEE CDC, IEEE MSC, ACC, AIAA GNC, IFAC:</b> <i>Reviewer</i>	<b>2008 - Present</b>
<b>IEEE Multi-Conference on Systems and Control</b>	<b>2011</b>
<i>Session Co-Chair for “Robust Model-Based Control”</i>	
<b>American Control Conference</b>	<b>2012</b>
<i>Session Chair for “Stochastic Systems”</i>	

MEMBERSHIP

<b>American Institute of Aeronautics and Astronautics:</b> <i>Student Member</i>	<b>2009 - Present</b>
<b>Institute of Electrical and Electronics Engineers:</b> <i>Student Member</i>	<b>2010 - Present</b>
<b>Society for Industrial and Applied Mathematics:</b> <i>Student Member</i>	<b>2011 - Present</b>
<b>American Institute of Chemical Engineers:</b> <i>Student Member</i>	<b>2012 - Present</b>