

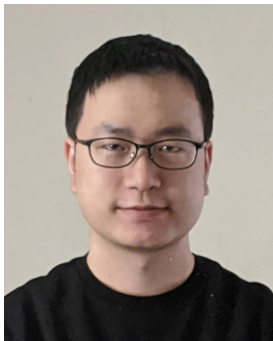


AIFARMS

Artificial Intelligence for Future Agricultural
Resilience, Management, and Sustainability



Adaptive Knowledge Transfer on Evolving Domains



Jun Wu

University of Illinois
Urbana-Champaign



Hanghang Tong

University of Illinois
Urbana-Champaign



Elizabeth Ainsworth

University of Illinois
Urbana-Champaign



Jingrui He

University of Illinois
Urbana-Champaign

Presented by **Jun Wu**

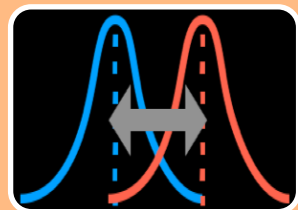
Email: junwu3@illinois.edu

Homepage: <https://publish.illinois.edu/junwu3/>



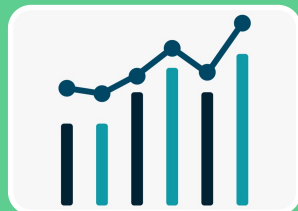
Background

- Dynamic transfer learning
- Assumptions



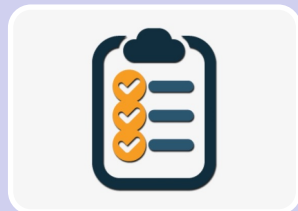
Methodology

- Label-informed \mathcal{C} -divergence
- Generalization error bound
- Adversarial VAE framework



Experiments

- Performance comparison
- Ablation study

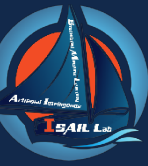


Conclusion

- Algorithm & analysis & evaluation



Background

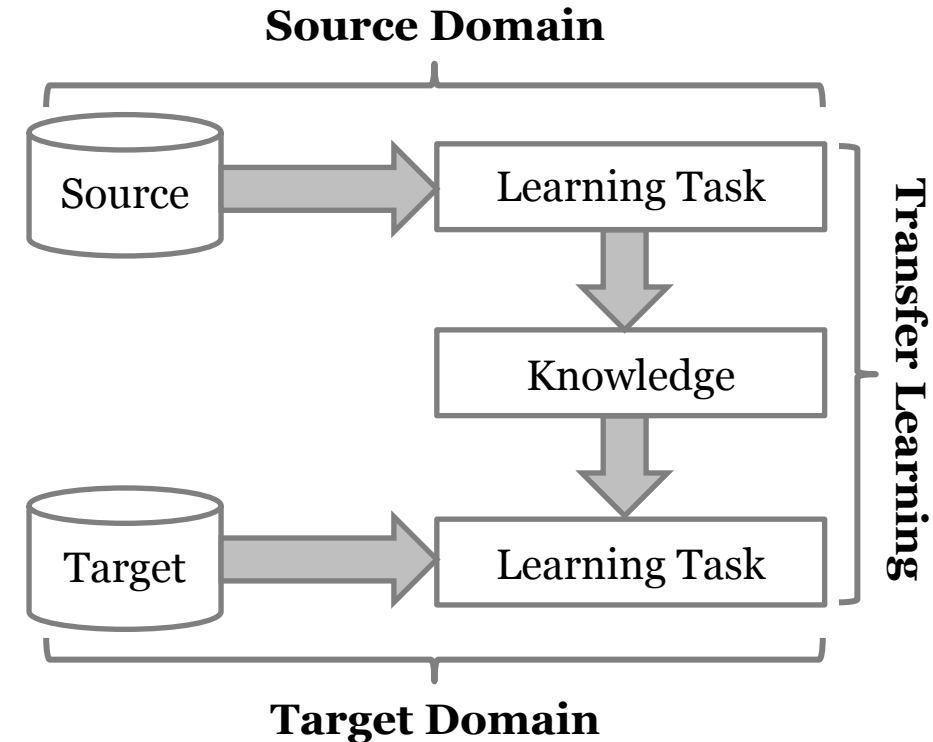


❑ Transfer Learning

- **Input:** A source domain and a target domain
- **Output:** Prediction function on the target domain

❑ Assumptions

- **Relatedness:** Domains are distributionally similar.
- **Static domains:** All the domain data are static



Background



Transfer Learning

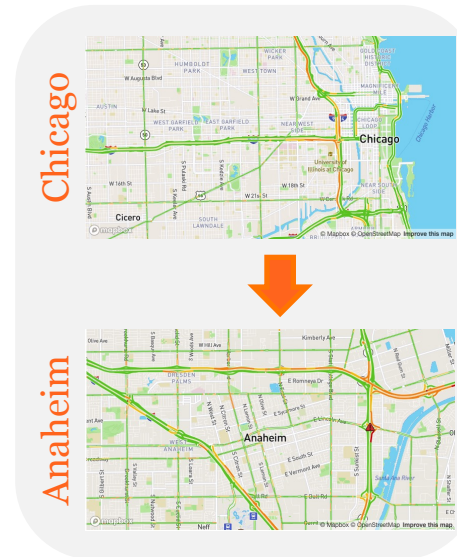
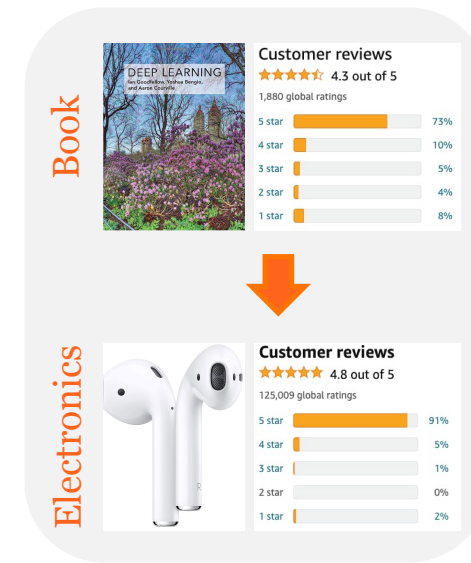
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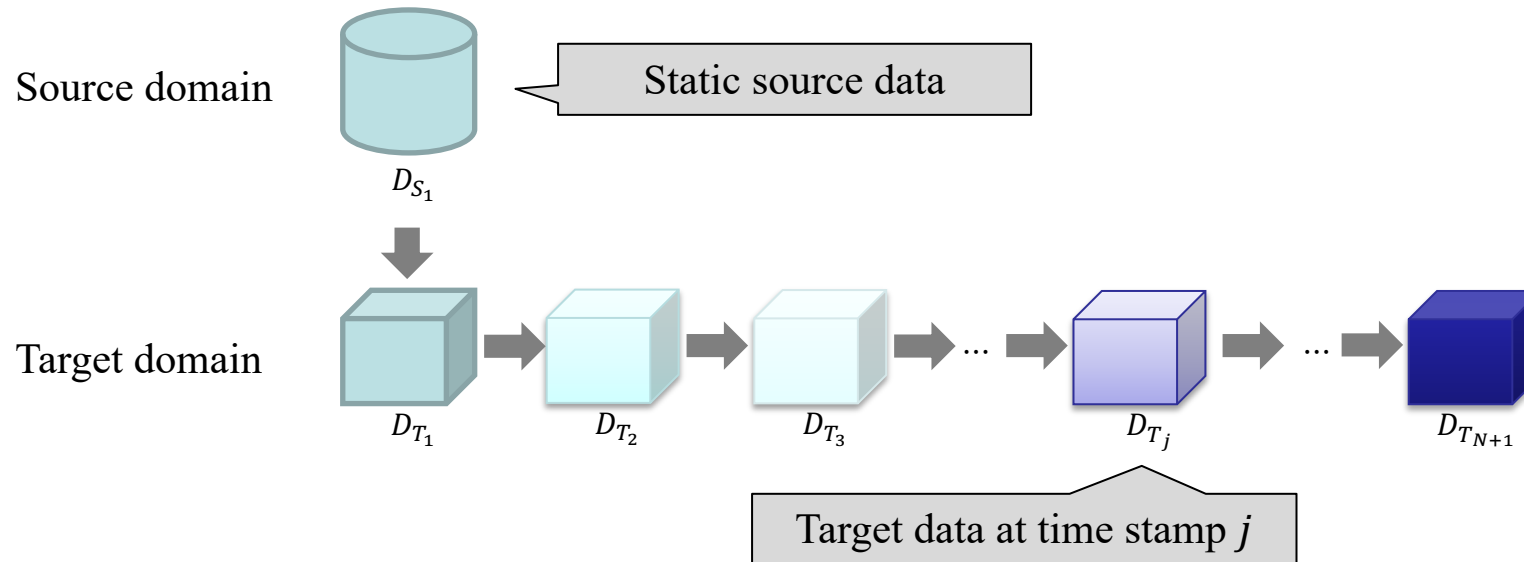
Applications

- **Computer vision:** Object recognition
- **Natural language processing:** Sentiment analysis
- **Graph mining:** Traffic flow prediction
- **Agriculture analysis:** Plant phenotyping



□ Dynamic transfer learning

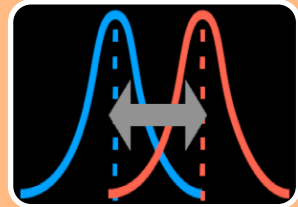
- Input: A static source domain (fully labeled);
A time-evolving target domain (limited labeled and adequate unlabeled)
- Goal: **Learn a prediction function for the newest target domain**
- Assumptions
 - **Relatedness**: The source and initial target domains are distributionally related.
 - **Evolution**: The target domain is continuously evolving over time.





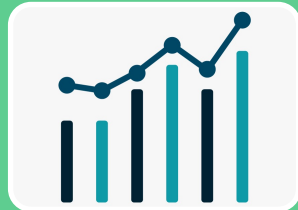
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Label-Informed Domain Discrepancy

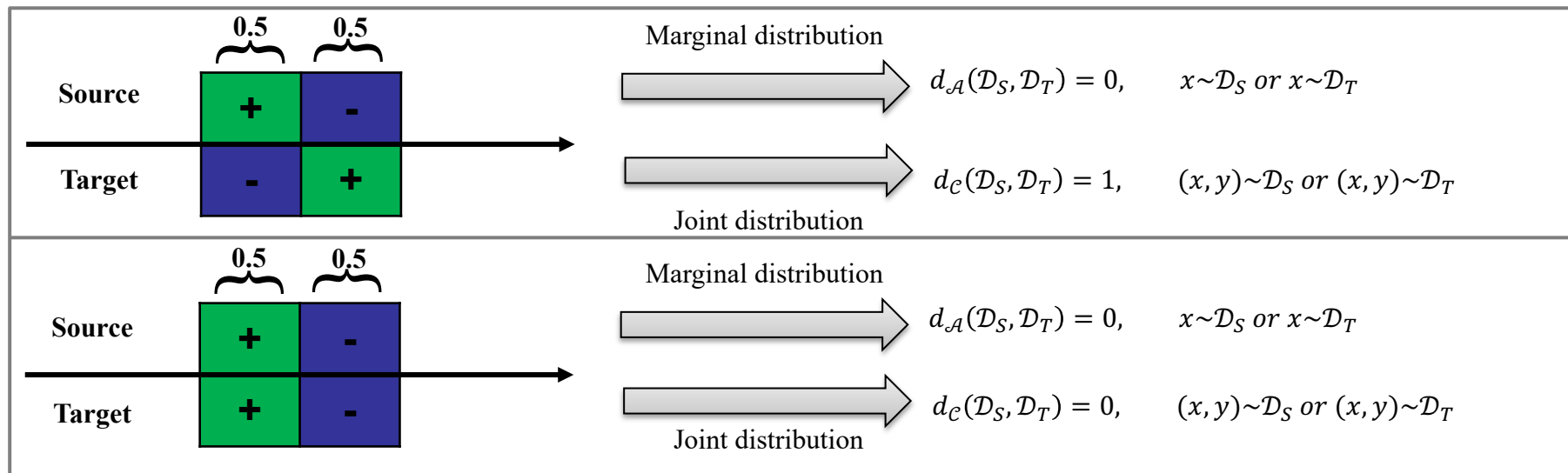


Label-informed domain discrepancy (\mathcal{C} -divergence):

- Key idea: Measure the **joint distribution difference** over both input and output spaces

$$d_{\mathcal{C}}(\mathcal{D}_S, \mathcal{D}_T) = \sup_{h \in \mathcal{H}} \left| \Pr_{\mathcal{D}_S}[\{I(h), y = 1\} \cup \{\overline{I(h)}, y = 0\}] - \Pr_{\mathcal{D}_T}[\{I(h), y = 1\} \cup \{\overline{I(h)}, y = 0\}] \right|$$

Comparison with existing marginal discrepancy measures, e.g., \mathcal{A} -distance [1]



[1] Shai Ben-David, et al. "A theory of learning from different domains." *Machine learning* 2010.

- The expected target error $\epsilon_{T_{t+1}}$ on time stamp $t+1$ is bounded by
 - (i) Empirical classification error $\hat{\epsilon}_{T_0}$ on source data
 - (ii) Empirical classification error $\hat{\epsilon}_{T_j}$ ($j = 1, \dots, t$) on historical target data
 - (iii) Label-informed domain discrepancy d_c among domains

Theorem: Assume the loss function $L(\cdot, \cdot)$ is bounded. Given a source domain \mathcal{D}_S (denoted as \mathcal{D}_{T_0}) and historical target domain $\{\mathcal{D}_{T_j}\}_{j=1}^t$, for $h \in \mathcal{H}$ and $\delta \in (0, 1)$, with probability at least $1 - \delta$, the target domain error $\epsilon_{T_{t+1}}$ on the newest target domain is bounded as follows.

$$\epsilon_{T_{t+1}}(h) \leq \frac{1}{\bar{\mu}} \left(\sum_{j=0}^t \mu^{t-j} \hat{\epsilon}_{T_j}(h) + M \sum_{j=0}^t \mu^{t-j} d_c(\hat{\mathcal{D}}_{T_j}, \hat{\mathcal{D}}_{T_{t+1}}) + M\Lambda \right)$$

where Λ is a Rademacher complexity term.

Proposed Algorithm: TransLATE



□ TransLATE: Transfer learning with label-informed distribution alignment

□ Objective function

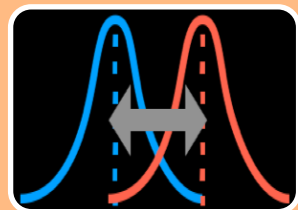
$$\mathcal{J} = \sum_{j=0}^t \mu^{t-j} \left(\underbrace{L_{clc}(T_j, T_{t+1})}_{\text{Empirical error}} + \overbrace{d_C(\hat{\mathcal{D}}_{T_j}, \hat{\mathcal{D}}_{T_{t+1}})}^{\text{Label-informed domain discrepancy}} + \underbrace{\lambda L_{ELBO}(T_j, T_{t+1})}_{\text{Variational Autoencoder for feature extraction}} \right)$$

- Assume data distribution is **continuously evolving**, i.e., $0 \leq \mu \leq 1$
- **Variational autoencoder** learns the common feature space
- The empirical error on historical target task is iteratively estimated



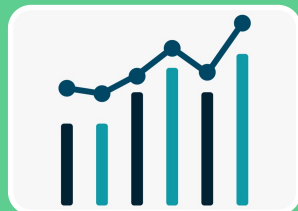
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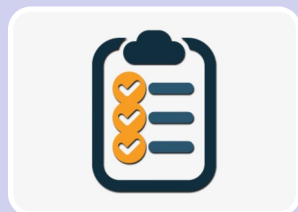
Methodology

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Experiments

- Performance comparison
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Conclusion

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Experiments



□ Data sets

- Synthetic
- Office-31
- Office-Home

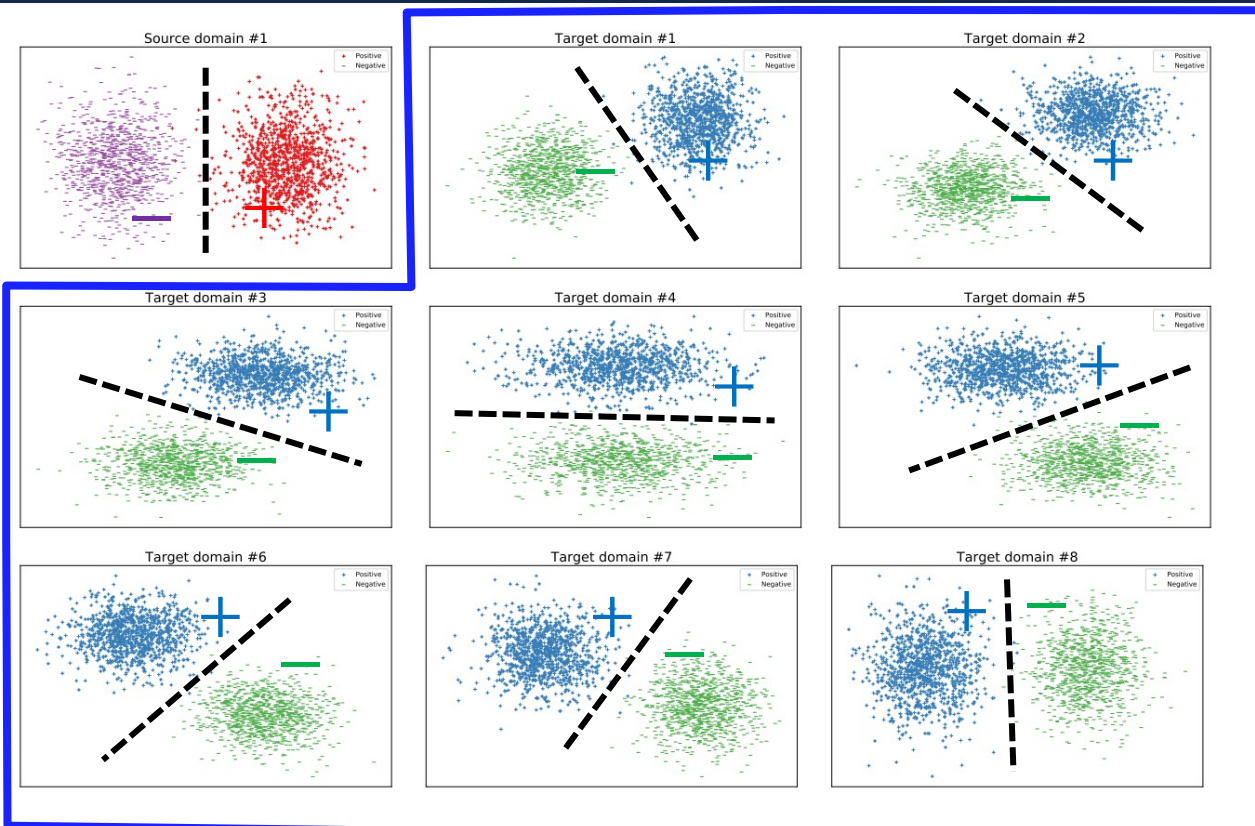
□ Metric

- Classification accuracy

□ Baselines

- Single domain: SourceOnly, TargetERM
- Static adaptation: DAN, DANN, and MDD
- Dynamic adaptation: CUA, GST, and CIDA

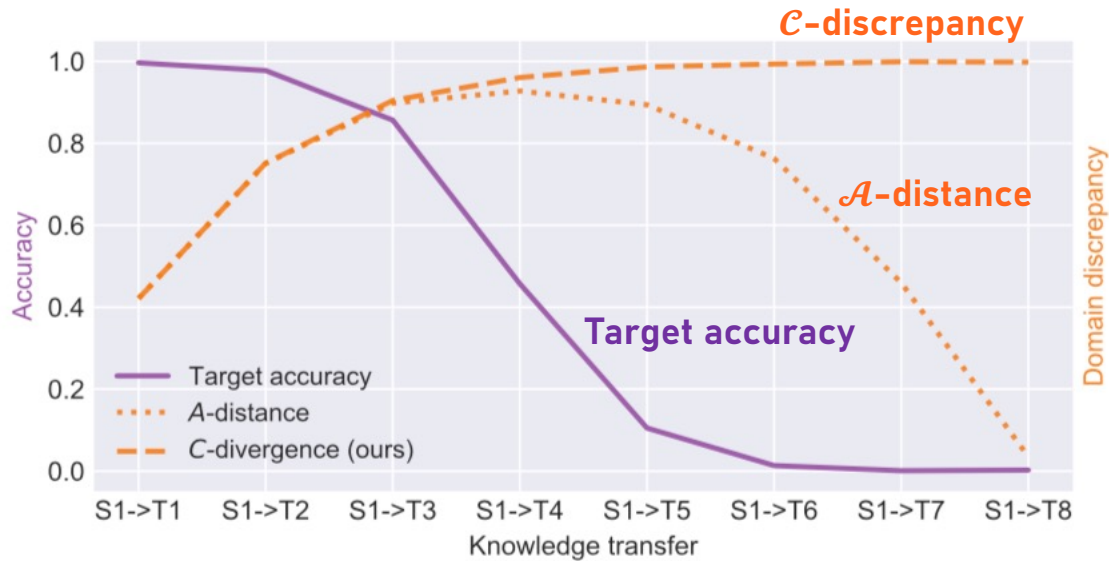
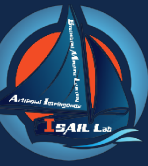
Source domain



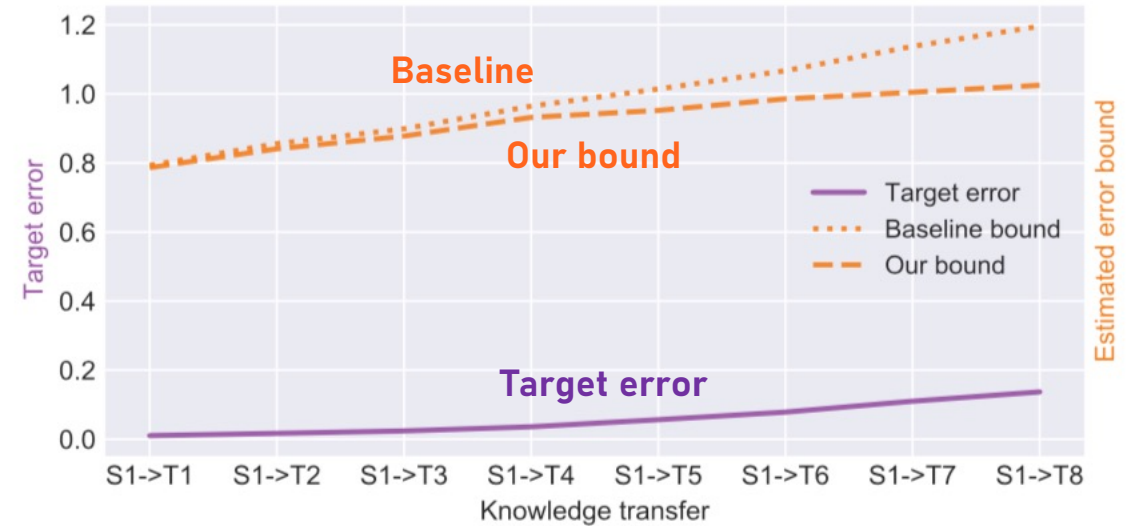
Time evolving target domain



Model Analysis



Comparison of domain discrepancy and target error



Comparison of different error bounds

Observations:

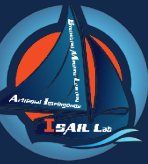
(a) Compared to \mathcal{A} -distance [1], \mathcal{C} -divergence better characterizes the transferability from the source to the target domains

(b) Our \mathcal{C} -divergence based error bound is much tighter than the baseline [1] based on \mathcal{A} -distance

[1] Shai Ben-David, et al. "A theory of learning from different domains." *Machine learning* 2010.



Results



	Amazon → Webcam					DSLR → Webcam				
	T1	T2	T3	T4	T5	T1	T2	T3	T4	T5
SourceOnly	0.7490	0.2255	0.2282	0.1275	0.1503	0.9651	0.4309	0.3329	0.1611	0.2027
TargetERM	0.5584	0.3933	0.4215	0.3396	0.3732	0.4966	0.4201	0.4188	0.3248	0.4067
DAN [9]	0.8537	0.5007	0.4993	0.3638	0.4470	0.9772	0.7302	0.6161	0.4765	0.5302
DANN [3]	0.8389	0.4993	0.4121	0.3973	0.3382	0.9651	0.7356	0.6416	0.4510	0.5490
MDD [19]	0.8940	0.6738	0.5490	0.5141	0.4295	0.9724	0.8738	0.7315	0.5047	0.5289
TransLATE _∞	0.9154	0.6376	0.5758	0.4591	0.4846	0.9785	0.8591	0.7289	0.4926	0.5557
CUA [2]	0.8349	0.6805	0.6389	0.6456	0.6805	0.9852	0.8805	0.8792	0.8362	0.8617
GST [6]	0.8456	0.5987	0.6013	0.5584	0.5960	0.9739	0.8376	0.8134	0.7570	0.7865
CIDA [14]	0.8805	0.7638	0.7624	0.7195	0.7476	0.9812	0.8577	0.8376	0.7973	0.7960
TransLATE	0.9154	0.8134	0.8081	0.7611	0.7826	0.9785	0.9235	0.9208	0.8886	0.9154
	Art → Real World					Clipart → Product				
	T1	T2	T3	T4	T5	T1	T2	T3	T4	T5
SourceOnly	0.7220	0.3947	0.3135	0.2650	0.3512	0.5944	0.1866	0.1342	0.1074	0.1550
TargetERM	0.5643	0.3297	0.3010	0.2582	0.3299	0.6033	0.3805	0.4232	0.3061	0.3791
DAN [9]	0.7341	0.4901	0.4193	0.3686	0.4597	0.7186	0.4201	0.3921	0.3352	0.4113
DANN [3]	0.7359	0.5092	0.4155	0.3850	0.4686	0.7063	0.4440	0.3694	0.3343	0.4303
MDD [19]	0.7435	0.5056	0.4331	0.3874	0.4686	0.7264	0.4765	0.3886	0.3514	0.4294
TransLATE _∞	0.7560	0.5273	0.4575	0.4080	0.4850	0.7411	0.5017	0.4436	0.3634	0.4595
CUA [2]	0.7370	0.5732	0.5181	0.4932	0.5372	0.7143	0.4922	0.4431	0.4310	0.4879
GST [6]	0.7367	0.5283	0.4795	0.4681	0.4826	0.7285	0.5232	0.4782	0.4531	0.4943
CIDA [14]	0.7420	0.5643	0.4983	0.4896	0.5130	0.7226	0.5076	0.4334	0.4030	0.4362
TransLATE	0.7560	0.6046	0.5447	0.5097	0.5459	0.7411	0.5747	0.5318	0.5009	0.5422

Classification accuracy

Office-31

Office-Home

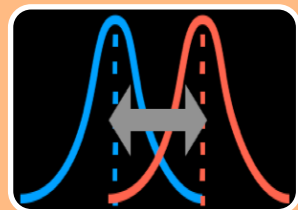
Observation:
TransLATE achieves significantly better performance (+10%) on the newest target domain.





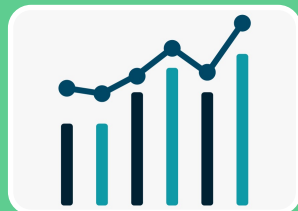
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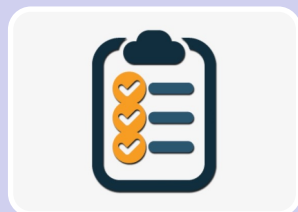
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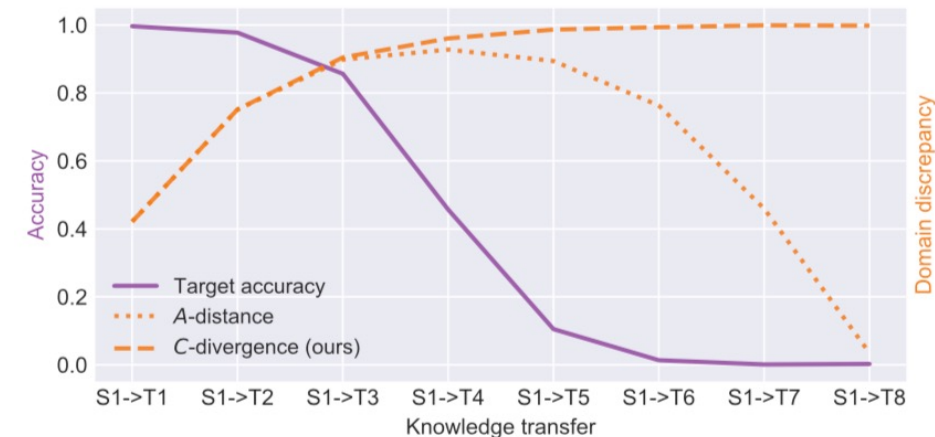
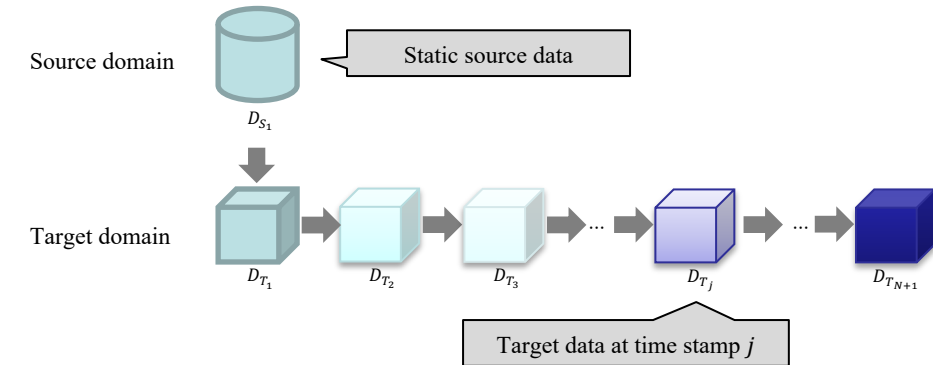
- Algorithm & analysis & evaluation



Conclusion



- ❑ **Problem:** Dynamic transfer learning with time evolving target domain
- ❑ **Analysis:** Generalization error bounds with the proposed \mathcal{C} -divergence
- ❑ **Algorithm:** Adversarial variational autoencoder framework based on empirical \mathcal{C} -divergence
- ❑ **Evaluation:** Competitive performance on modeling the newest target domain



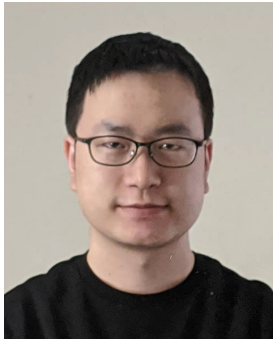


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