

ImVerde: Vertex-Diminished Random Walk for Learning Imbalanced Network Representation

Presenter: **Jun Wu**

joint work with

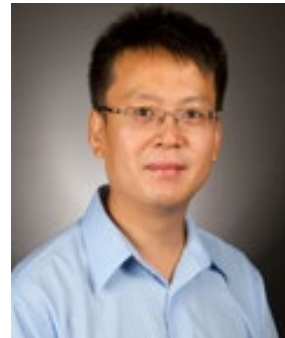
Dr. Jingrui He

and

Dr. Yongming Liu



Arizona State University
Jingrui.he@asu.edu



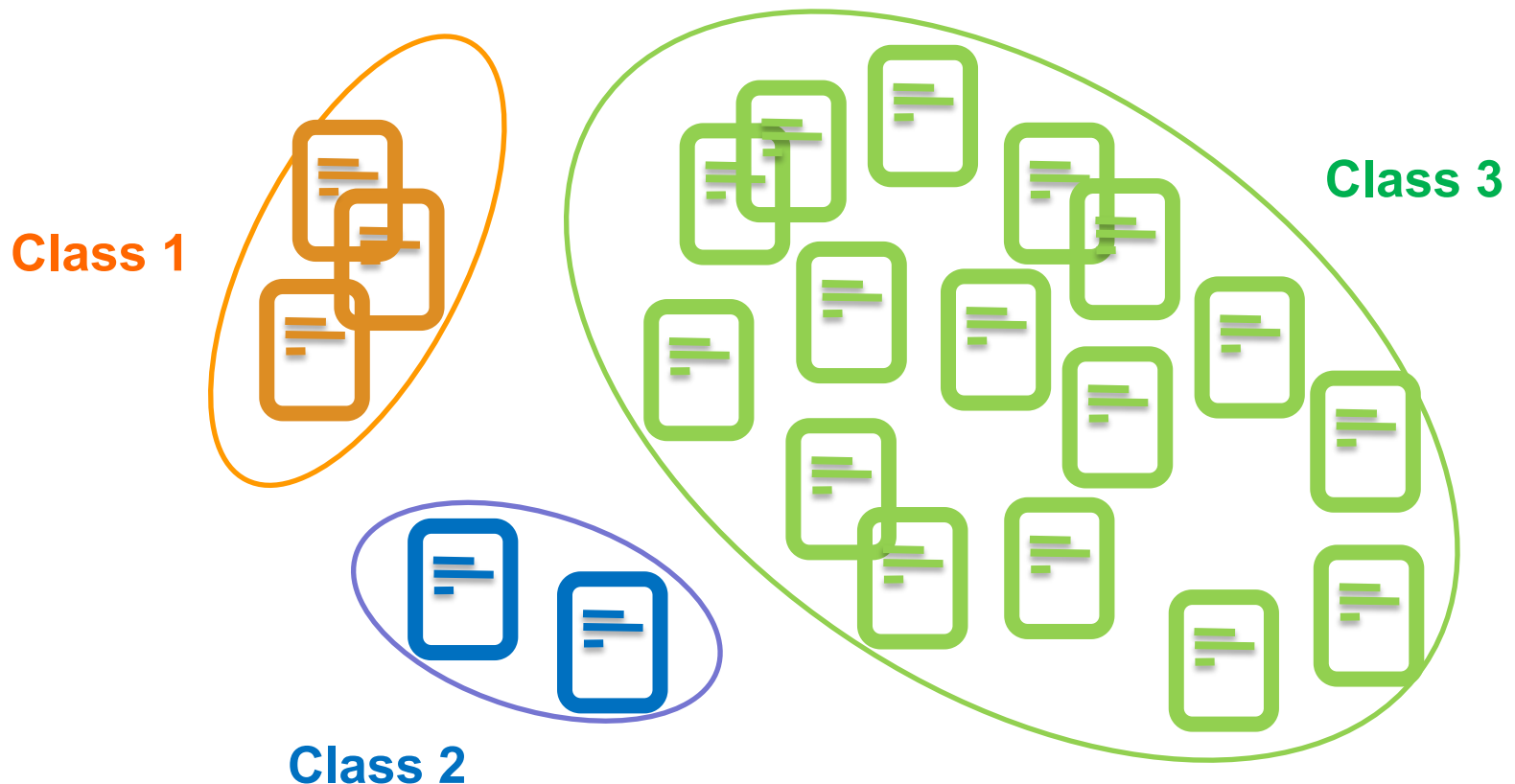
Arizona State University
Yongming.Liu@asu.edu

Roadmap

- Motivation
- Proposed *VDRW* algorithm
- Proposed *ImVerde* framework
- Experiments
- Conclusion

Imbalanced data is everywhere...

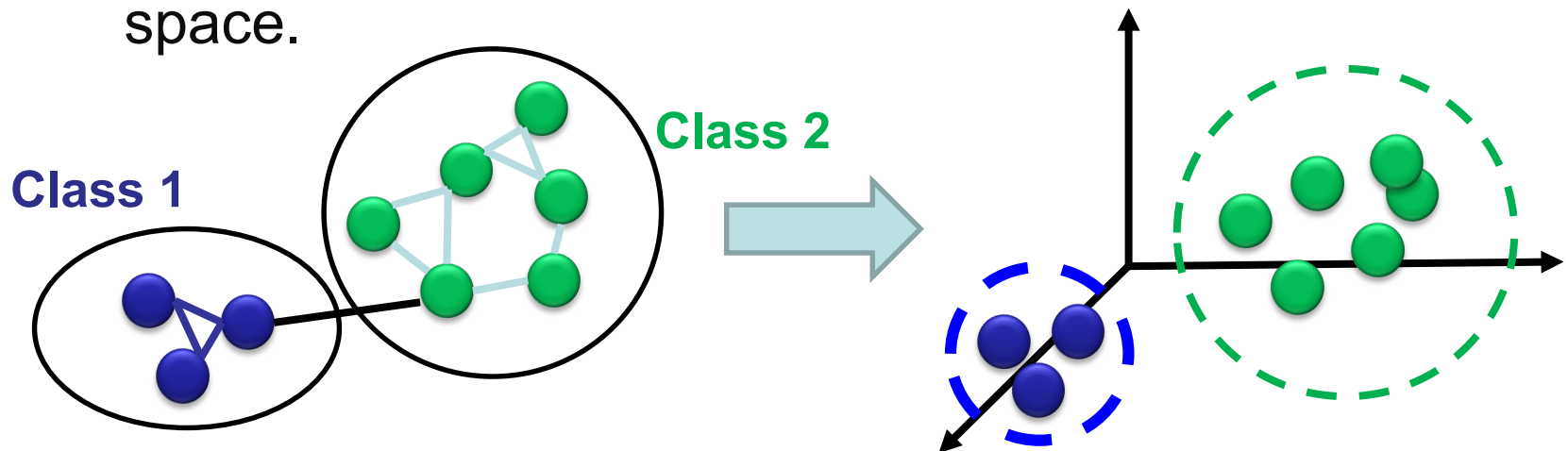
- The data distribution from different classes are significantly skewed.



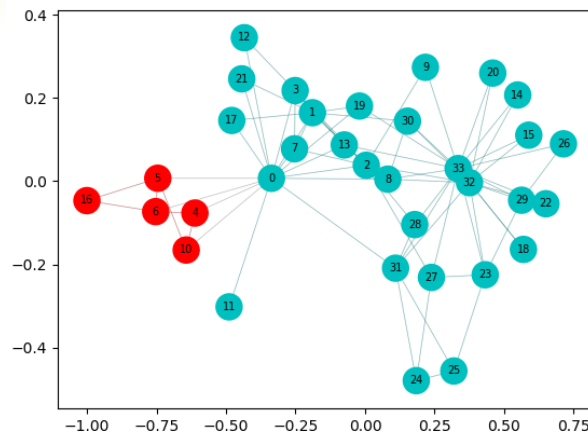
Representation learning

- Problem definition

- Input: (i) a (directed or undirected) network $G = (V, E)$,
(ii) imbalanced class labels for nodes in V
- Output: a low-dimensional vector representation for each node $v \in V$, so that the minority class is separated from majority class in the embedding feature space.



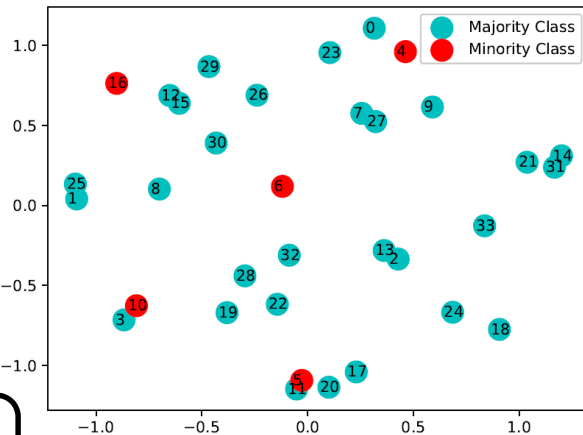
Imbalanced network embedding



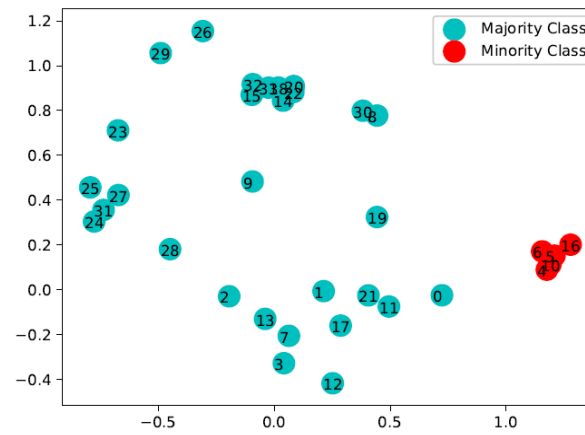
Karate network

Network embedding

Network embedding



Planetoid



ImVerde

Visualization via t-SNE

Visualization via t-SNE

Roadmap

- Motivation
- Proposed *VDRW* algorithm
- Proposed *ImVerde* framework
- Experiments
- Conclusion

Vertex-Diminished Random Walk

- Intuition: the probability of a transition to one node would decrease each time when it is visited.

$$P(Y_{t+1} = j | \mathcal{F}_t) = \frac{R_{Y_t, j} f(S_j(t))}{\sum_i R_{Y_t, i} f(S_i(t))} \quad (1)$$

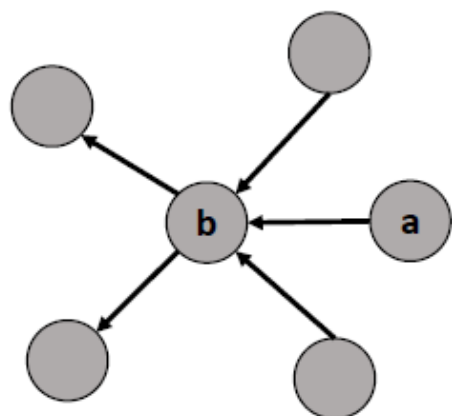
where

$$f(S_j(t)) = \alpha^{S_j(t)} \quad (2)$$

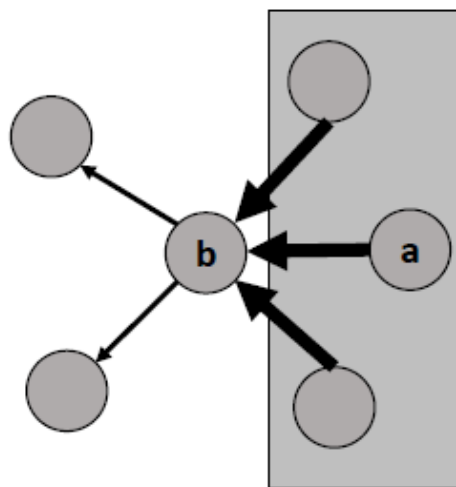
R_{ij} : transition probability from node i to node j
 $S_j(t)$: the number of visits to node j up to time t
 $f(\cdot)$: a visiting function based on $S_j(t)$
 α : hyper-parameter to be specified

Vertex-Diminished Random Walk

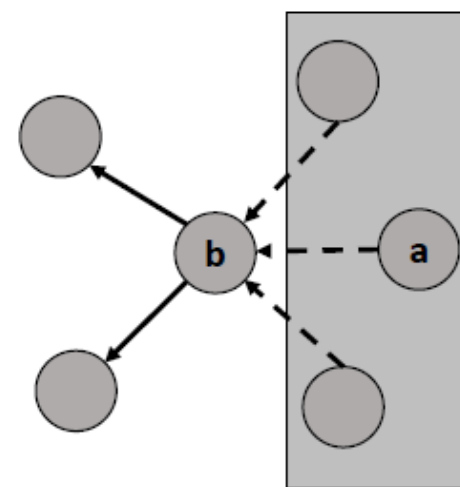
- Intuition: the probability of a transition to one node would decrease each time when it is visited.



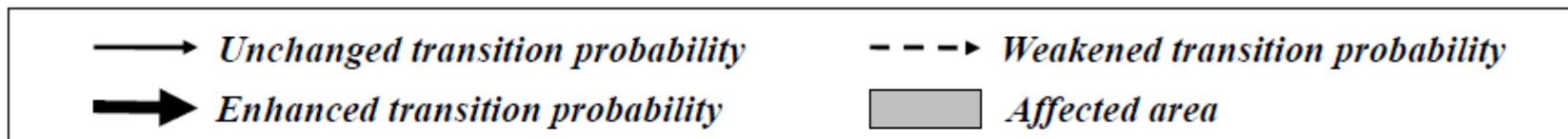
(a) Random Walk



(b) VRRW



(c) VDRW



$$f(S_j(t)) = 1$$

$$f(S_j(t)) = S_j(t)$$

$$f(S_j(t)) = \alpha^{S_j(t)}$$

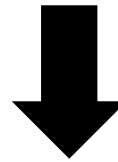
Vertex-Diminished Random Walk

- Convergence analysis

$$V_i(t) = \frac{f(S_i(t))}{\sum_i f(S_i(t))}$$

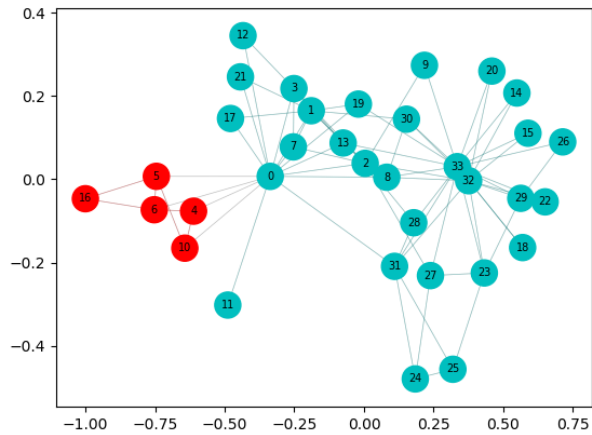
Theorem 1: With probability one, $\text{dist}(V(t), \mathcal{C} \cup \mathcal{C}_0) \rightarrow 0$
where

$$\text{dist}(x, A) = \inf\{|x - y| : y \in A\}$$

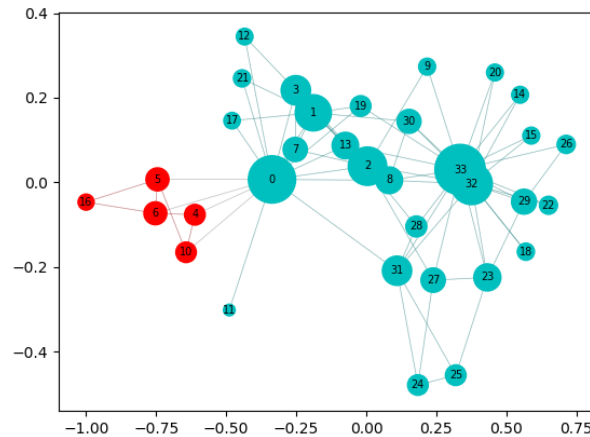


Corollary 3: If all the off-diagonal entries of R are positive and all the principal minors of R are invertible, $V(t)$ converges almost surely.

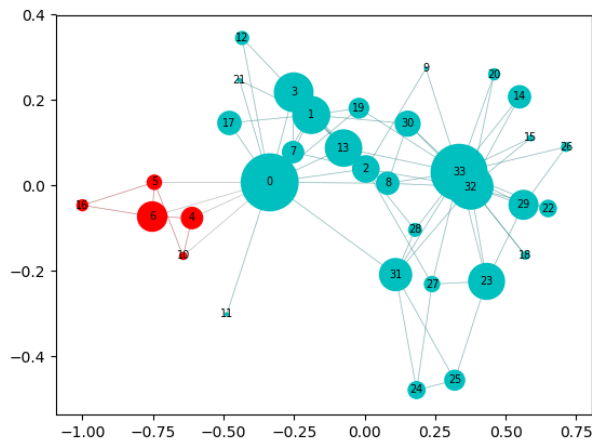
Vertex-Diminished Random Walk



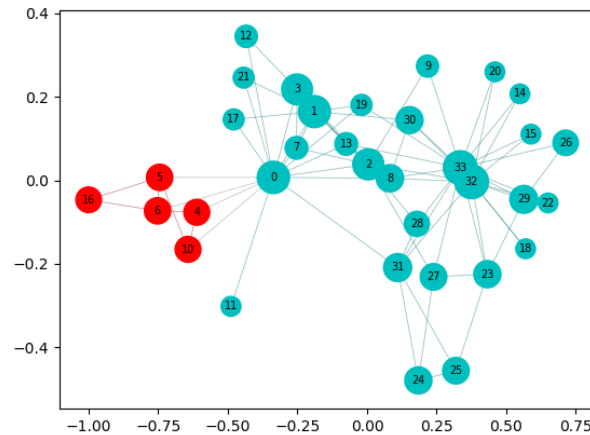
Karate Network



Random Walk



Vertex-Reinforced Random Walk

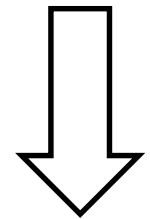


Vertex-Diminished Random Walk

● Minority class

● Majority class

Larger circle



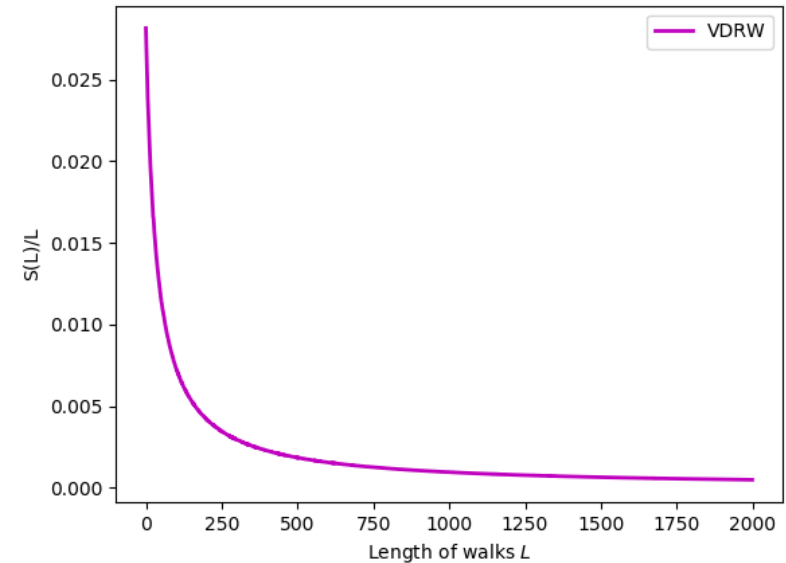
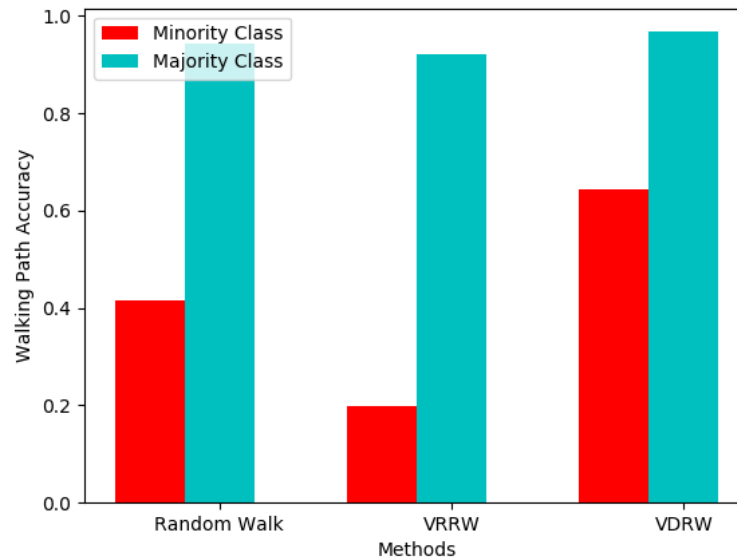
Higher visited times

Vertex-Diminished Random Walk

Walking 10 steps for 100 times

Walking 2000 steps once

Minority class Majority class



Accuracy of node-context pairs

Convergence analysis

Case study on the Karate network

Roadmap

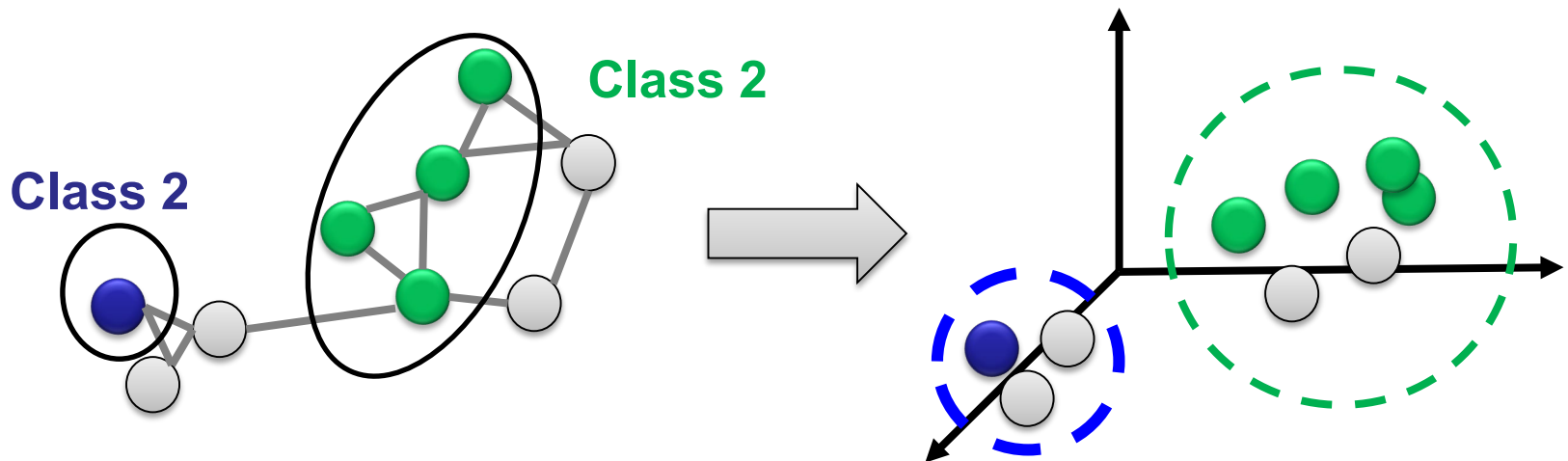
- Motivation
- Proposed *VDRW* algorithm
- Proposed *ImVerde* framework
- Experiments
- Conclusion

Imbalanced network embedding

- The loss of our semi-supervised framework:

$$\mathcal{L} = \mathcal{L}_s + \lambda \mathcal{L}_u$$

- \mathcal{L}_s : supervised loss of predicting the label
- \mathcal{L}_u : unsupervised loss of predicting the graph context
 - Assumption: nodes with the same context would have the similar embeddings



Imbalanced network embedding

- Unsupervised loss

$$\mathcal{L}_u = - \sum_{(v_i, v_c)} [\log \sigma(w_c^T e_i) + k \cdot \mathbb{E}_{v_n \sim P_n(v_c)} \log \sigma(-w_n^T e_i)]$$

(v_i, v_c) : a node-context pair of node i and its corresponding context c

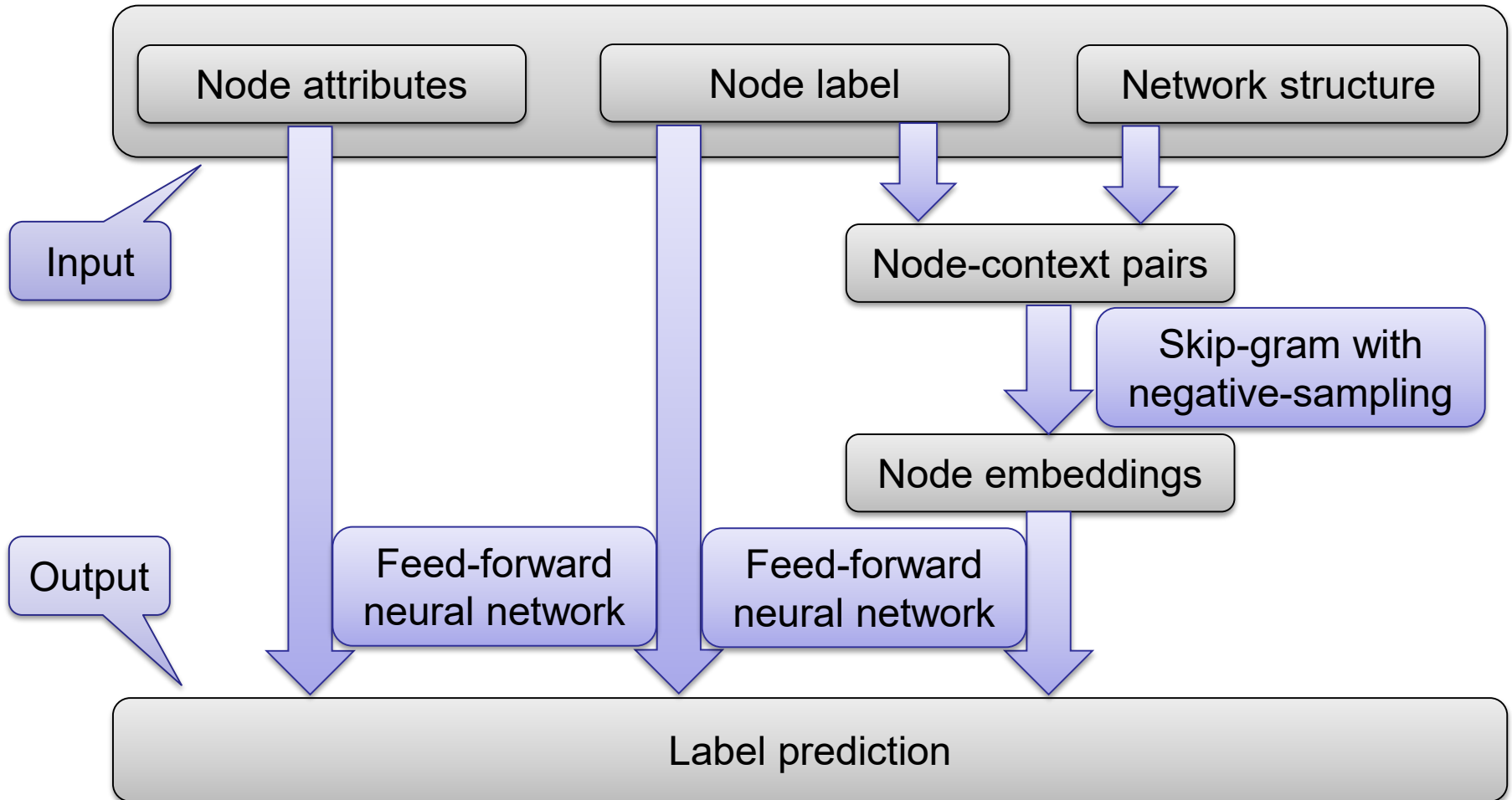
e_i : embedding of node i

w_c : representation of context c

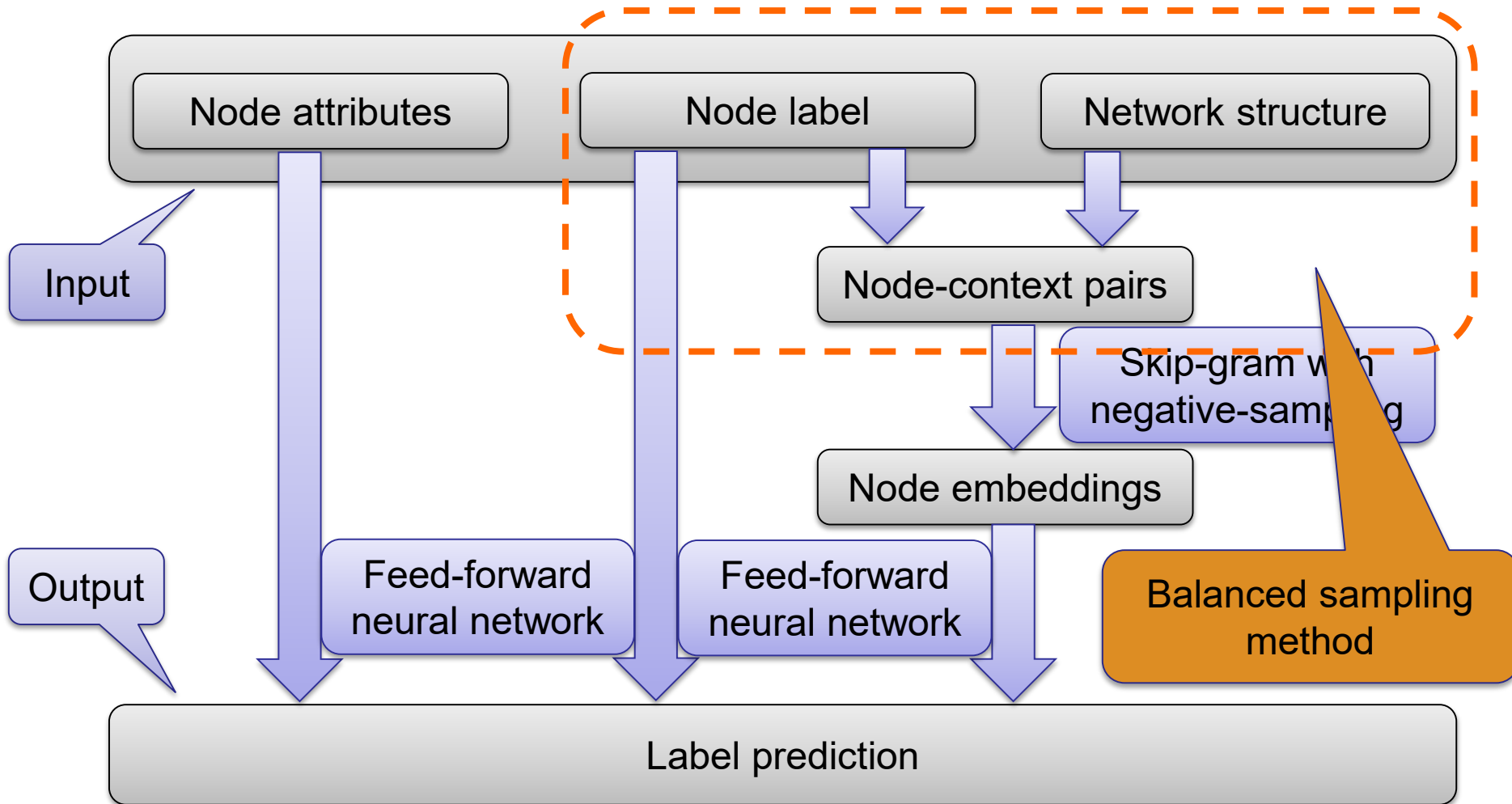
- Supervised loss (cross-entropy error)

$$\mathcal{L}_s = - \frac{1}{l} \sum_{i=1}^l \log \frac{\exp([h^{l1}(x_i) \ h^{l2}(e_i)]^T y_i)}{\sum_{y'} \exp([h^{l1}(x_i) \ h^{l2}(e_i)]^T y')}$$

Imbalanced network embedding

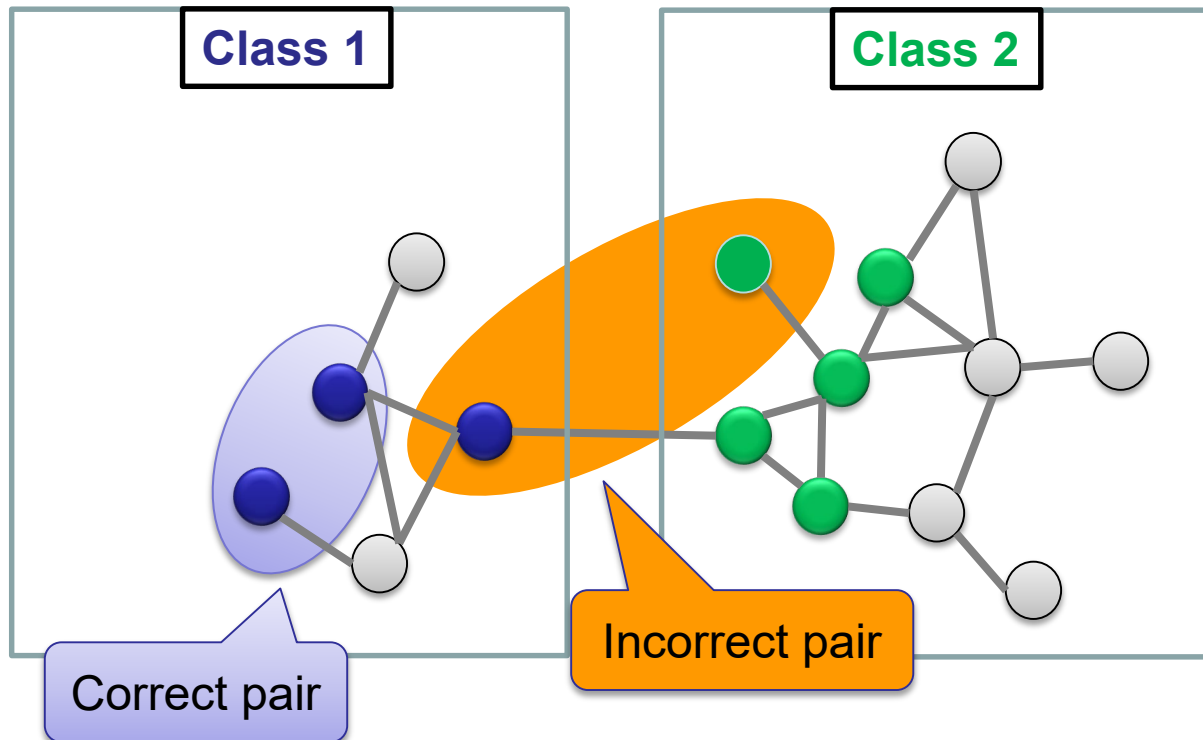


Imbalanced network embedding



Imbalanced network embedding

- Key intuition: node-context pairs within the same class are crucial for learning node representation in the minority class.



Context sampling

- Node-context pair sampling:
 - Label information: nodes with the same label would be seen as the contexts for each other
 - Network structure: short VDRW can explore the context for each node within the class

Context sampling

- Node-context pair sampling:

- Label y_i would be seen
- Network context v_c he

Algorithm 2 Context Sampling

Input: Graph G with transition matrix \mathbf{R} , labels $y_{1:l}$

initial node v_s

jumping probability r

length of walking sequences T

Output: Node-context pairs (v_i, v_c)

1: **Initialize:** Add v_s to walking path p ;

2: **for** $t = 0$ to $T - 1$ **do**

3: **if** Node is labeled **then**

4: With r , select one node v with the same label;

5: With $1 - r$, select its neighbor v based on \mathbf{R} ;

6: **else**

7: Select its neighbor v based on \mathbf{R} ;

8: **end if**

9: Update \mathbf{R} using VDRW;

10: Update the walking path p ;

11: **end for**

12: Return the node-context pairs sampled from path p .

Balanced-batch sampling

- It adopted the under-sampling method to select the seeds for mini-batch training

- All the labeled minority instances are selected

$$|S_{min}|$$

- Randomly select the labeled majority instances

$$|S'_{maj}| = |S_{min}|$$

- Randomly select the unlabeled instances

$$|S_{other}| = Batchsize - |S'_{maj}| - |S_{min}|$$

Roadmap

- Motivation
- Proposed *VDRW* algorithm
- Proposed *ImVerde* framework
- Experiments
- Conclusion

Experiments

- Data sets:

	# nodes	# edges	# classes	# features
Cora	2,708	5,439	7	1,433
Citeseer	3,327	4,732	6	3,703
Pubmed	19,717	44,338	3	500
NTSB	1,473	11,784	4	4,424

- Baseline methods:

- Planetoid
- Node2vec
- DeepWalk
- SMOTE

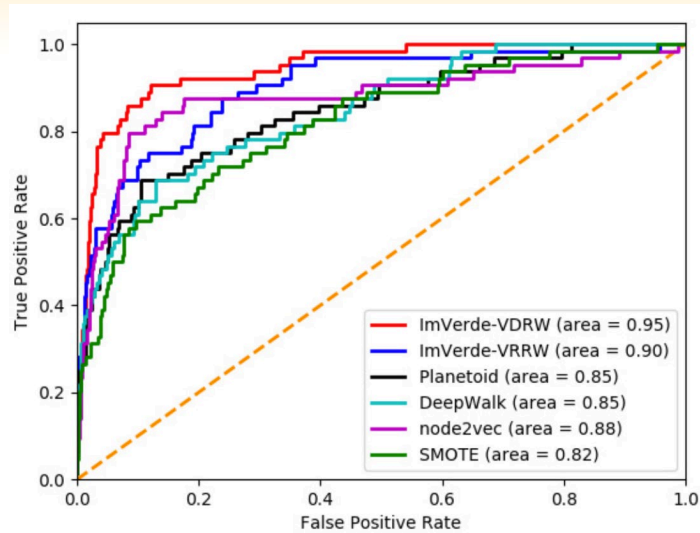
NTSB: each node represents one accident report from National Transportation Safety Board database, and each edge reflects the similarity between two reports using TF-IDF features. Node labels correspond to the accident causes.

Binary node classification

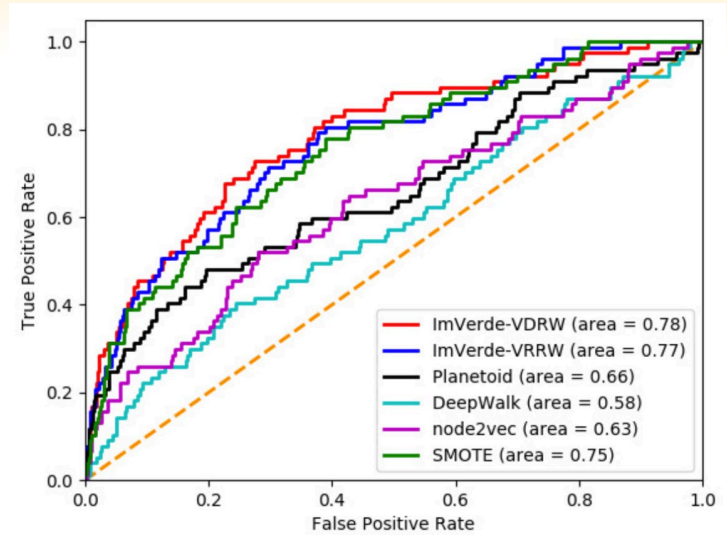
	Planetoid	DeepWalk	node2vec	SMOTE	<i>ImVerde-VDRW</i>
Cora_1	0.639	0.650	0.612	0.473	0.720
Cora_2	0.749	0.778	0.761	0.664	0.852
Cora_3	0.900	0.863	0.840	0.707	0.910
Cora_4	0.783	0.657	0.761	0.723	0.826
Cora_5	0.637	0.610	0.471	0.641	0.769
Cora_6	0.557	0.722	0.505	0.584	0.805
Cora_7	0.501	0.474	0.503	0.404	0.657
Citeseer_1	0.238	0.116	0.169	0.252	0.304
Citeseer_2	0.396	0.225	0.250	0.550	0.513
Citeseer_3	0.651	0.616	0.693	0.605	0.666
Citeseer_4	0.608	0.352	0.415	0.729	0.732
Citeseer_5	0.706	0.512	0.610	0.790	0.785
Citeseer_6	0.591	0.310	0.432	0.644	0.651
Pubmed_1	0.298	0.335	0.203	0.631	0.631
Pubmed_2	0.454	0.632	0.497	0.669	0.663
Pubmed_3	0.489	0.736	0.462	0.685	0.653

Average precision for the binary node classification (The best results are indicated in bold)

Binary node classification

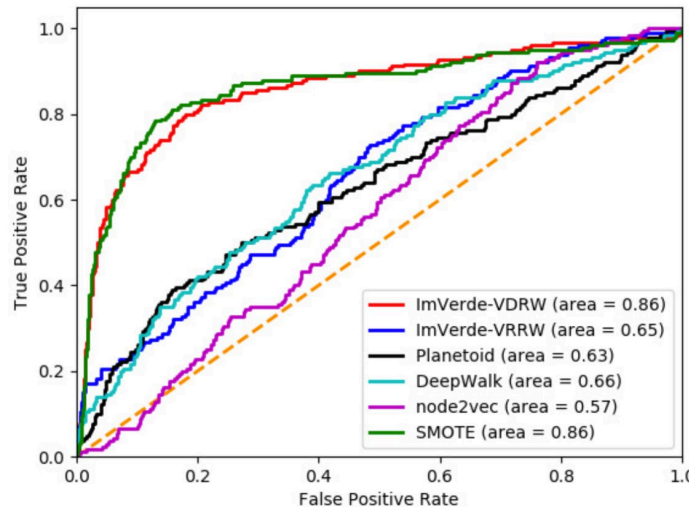


(a) Cora



(b) Citeseer

Higher
is
better



(c) Pubmed

The ROC curve and AUC value for node classification on (a) Cora, (b) Citeseer, (c) Pubmed data sets

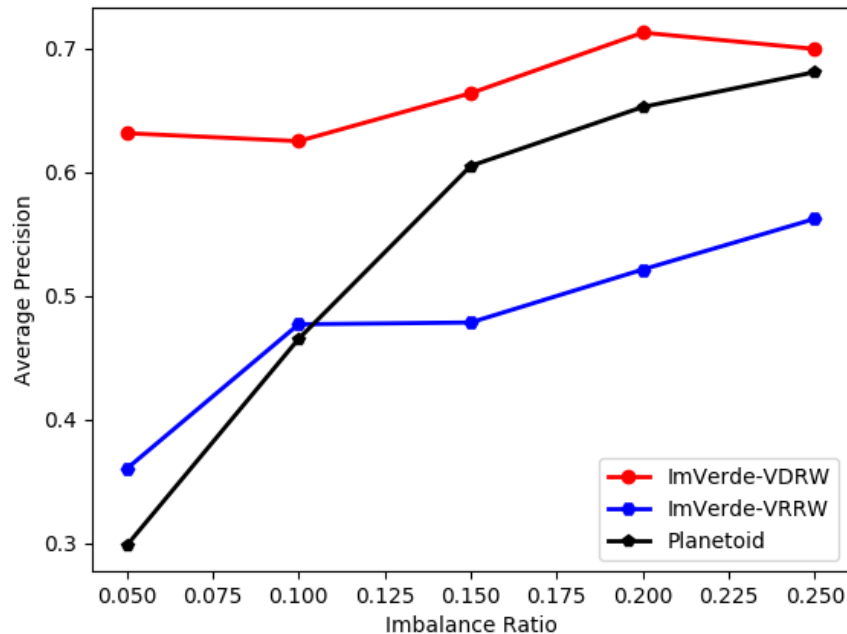
Multi-class node classification

	Accuracy
Planetoid	0.311
DeepWalk	0.458
node2vec	0.408
<i>ImVerde-VRRW</i>	0.416
<i>ImVerde-VDRW</i>	0.460

The accuracy of multi-class text classification on NTSB data set

Imbalance analysis

Higher
is
better



The average precision with different imbalance ratio on Pubmed data set

Roadmap

- Motivation
- Proposed *VDRW* algorithm
- Proposed *ImVerde* framework
- Experiments
- Conclusion

Conclusion

- Vertex-Diminished Random Walk (VDRW) is proposed, which is effective to extract the node-context pairs from imbalanced network
- A novel semi-supervised framework, *ImVerde*, is presented to learn the network representation from imbalanced data
- Experimental results on real-world data sets demonstrated the effectiveness of the proposed model

Thanks! & Questions?

Presenter: **Jun Wu**

Email: junwu6@asu.edu

