

Understanding Non-convex Optimization for Matrix Completion

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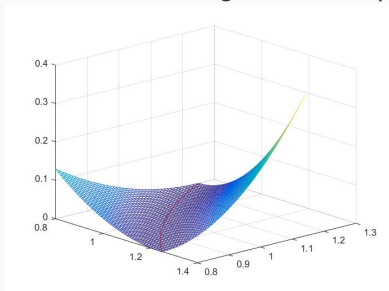
Joint work with Zhi-Quan Luo (U of Minnesota and CUHK-SZ)

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What I Will Talk About

We will prove: a **non-convex** factorization formulation can be solved to **global optima**.

Matrix factorization has a certain geometrical property:



Introduction

Motivation: Recommendation System

- Recommendation systems (personalized)

			
Richard	5	1	4
Mary	?	2	5
Steve	4	3	2

- Question: predict missing ratings?
- Assumption: **low-rank**.
- **Matrix Completion** (MC): recover a **low-rank** matrix M from **partial** data [Candes,Recht-09].

MC and big data

- Low-rank models are ubiquitous
 - “small” information from “big” data
- **Idea of MC:** To extract “small” information, a few samples enough
- Other applications:
 - Structure-from-motion in **computer vision**
[Tomasi,Kanade-92],[Chen,Suter-04]
 - System identification in **control** [Liu,Vandenberghe-08]
 - Collaborative ranking (search, advertisements, marketing, etc.) [Yi et al.-11],[Lu,Neghaban-14]
 - Genomic data integration [Cai-Cai-Zhang-14]

Fill in the gap?

- Matrix factorization (**non-convex**): $M = UV^T$.

$$M = UV^T$$

- Interestingly, always **global-min** for MC, if M low-rank.
- Long been used in recommendation systems [Funk'06], [Koren'09]
- Question:** any **theory**?

Summary of Results

Theorem 1 (**local geometry**) For a properly regularized non-convex formulation, there is **no bad stationary point** in a certain neighborhood of the global optima.

Theorem 2 (**global convergence**) Starting from certain initial point, most standard algorithms converge to global optima.

Background and Formulation

Brief History of Matrix Completion

Convex (08-10): Theory for convex formulation [Candes-Tao'08]
[Candes-Recht'09], [Gross'09], [Recht'09], [Chen'14].

Non-convex Grassman manifold: [Keshavan-Montanari-Oh'09]

Non-convex Resampling AltMin (12-14): [Jain et al.'12],
[Keshavan'12], [Hardt'13], [Hardt-Wooters'14].

- Subtle issue: Theory does not match algorithm.

Our work: [Geometry of Matrix Factorization](#) [Sun-Luo'14].

Factorization is Fundamental

Previous understanding: extension of CS/LASSO

Current: “factorization” is crucial.

Recent “trend”: Matrix factorization.

- **Industry:** embedding at, say, facebook
- **Theory:** PCA [Musco,Musco-15] , Laplacian linear system [Kyng,Sacheva'16]
- **Non-convex optimization:** tensor decomposition, phase retrieval, dictionary learning, etc.

Factorization for Matrix Completion

- Notations:
 - $M \in \mathbb{R}^{n \times n}$, rank $r \ll n$ ¹
 - Ω : set of sampled positions.
- Matrix factorization formulation (non-convex):

$$P_0 : \min_{X \in \mathbb{R}^{n \times r}, Y \in \mathbb{R}^{n \times r}} \frac{1}{2} \|\mathcal{P}_\Omega(M - XY^T)\|_F^2. \quad (1)$$

where \mathcal{P}_Ω is a sampling operator

$$\mathcal{P}_\Omega(Z)_{ij} = \begin{cases} Z_{ij} & (i, j) \in \Omega, \\ 0 & (i, j) \notin \Omega. \end{cases}$$

¹ M can be rectangular; assume square just for simplicity.

Algorithms to solve MF

- Recall: $\min_{X,Y} \|\mathcal{P}_\Omega(M - XY^T)\|_F^2$.
- Algorithmic idea: **solve smaller sub-problems**
 - Coordinate Descent for MC [Koren-09],[Wen-Yin-Zhang-12],[Yu et al. 12][Hastie et al. 14]
 - SGD for MC [Koren-09], [Funk-06], [Gemulla et al. 11], [Recht-Re-13], [Zhuang et al. 13].
- SGD solves Netflix problem (500k \times 20k) in **≤ 3 mins!** [Recht-Re-13]

Local Geometry

Full-Observation Case: Low-rank Approximation

- **Matrix factorization** formulation (non-convex):

$$\min_{X, Y \in \mathbb{R}^{n \times r}} \frac{1}{2} \|M - XY^T\|_F^2. \quad (2)$$

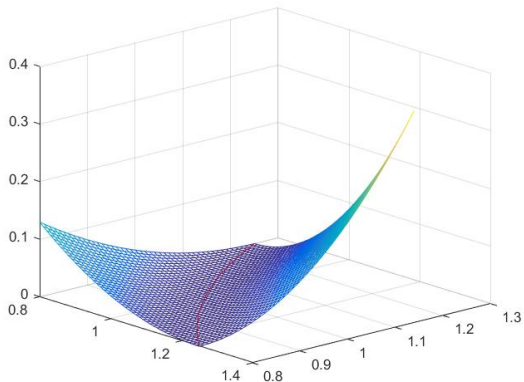
- **Claim:** Optimal solution = best rank- r approximation.
- Is this problem hard? Why?
- AltMin equivalent to [power method](#) [Szlam, Tulloch, Tygert'16]
What about other algorithms?

Simplest Case

Consider $n = r = 1$, i.e.

$$\min_{x,y} (xy - 1)^2.$$

Nice geometry: locally no other critical points.

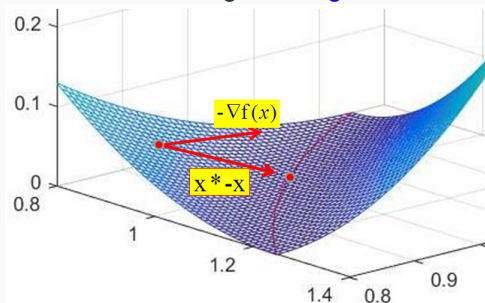


Step 1: Local Geometry of $\|M - XY^T\|_F^2$

Lemma²: In a neighborhood of M , $\forall x = (X, Y)$, \exists optimal x^* s.t.

$$\langle \nabla f(x), x - x^* \rangle \geq c \|x - x^*\|^2.$$

Interpretation: local direction aligns with global direction $x^* - x$.



Corollary: Locally no bad critical point!

²Related to Polyak inequality, Lojaswicz inequality, error bound, etc.

Step 2: Geometry of $\|\mathcal{P}_\Omega(M - XY^T)\|_F^2$

Question: why $f(x, y) = (xy - 1)^2$ has nice geometry?

- **“Answer”:** strong convexity of $(z - 1)^2$ preserved after $z \rightarrow xy$

³Techniques: new [perturbation analysis](#) + probability tools

Step 2: Geometry of $\|\mathcal{P}_\Omega(M - XY^T)\|_F^2$

Question: why $f(x, y) = (xy - 1)^2$ has nice geometry?

- “Answer”: strong convexity of $(z - 1)^2$ preserved after $z \rightarrow xy$

Challenge: $\|\mathcal{P}_\Omega(M - Z)\|_F^2$ **not strongly convex!**

Lemma 2[S-L'14] (RIP): In a local “incoherent” region,³

$$\|\mathcal{P}_\Omega(M - Z)\|_F^2 \geq c\|M - Z\|^2.$$

“Incoherent” means $Z = XY^T$ where X, Y have **bounded row norms**.

³Techniques: new **perturbation analysis** + probability tools

Step 3: Geometry with Constraints/Regularizers

Need to add regularizer G_1 to force incoherence.

- Issue: ∇G_1 not aligned with global direction $x^* - x$.

Need to add one more regularizer G_2 to correct G_1 ⁴.

Theorem [S-Luo]: Any stationary point of $F + G_1 + G_2$ in a local incoherent region is a **global-min**, i.e., the original matrix, under standard assumptions on M, Ω .

⁴Technique: Perturbation analysis for “pre-conditioning”, rather involved.

Formulation with Regularizers

- Our formulation

$$\min F(X, Y) + G_1(X, Y) + G_2(X, Y),$$

G_1, G_2 guarantee (X, Y) close to

$$(X, Y) \in K_1 = \{\|X^{(i)}\| \leq \beta_1, \quad \|Y^{(i)}\| \leq \beta_1, \quad \forall i.\}$$

$$(X, Y) \in K_2 = \{\|X\|_F \leq \beta_T, \quad \|Y\|_F \leq \beta_T\},$$

- K_1 : incoherence (row-norm)
- K_2 : boundedness

Simulation: push # of samples to **fundamental limit** $\approx 2nr$.

Summary

- **Goal:** Understand why MF works
- **Result:** guarantee for **non-convex** matrix completion
- **Fundamental question:** Why low-rank approximation is “easy”? **Go beyond power method!**
- **Take-away:** MF has nice **geometry**
 - with missing entries, regularization needed

References

- [Sun-Luo-14] Ruoyu Sun and Zhi-Quan Luo, “**Guaranteed Matrix Completion via Non-convex Factorization,**”
–2015 [INFORMS Optimization Society Student Paper Competition](#), Honorable Mention.
–*FOCS* (Foudation of Computer Science) 2015.
–To appear in *IEEE Transaction on Information Theory*,2016.
- [Sun-15] Ruoyu Sun, “**Matrix Completion via Non-convex Factorization: Algorithms and Theory,**” Ph.D. Dissertation, University of Minnesota, 2015.
- Remark: [Sun-Luo-14] focuses on theory;
My thesis [Sun-15] presents new numerical findings supporting theory.

Thank You!