

# Lecture 16: Computation tree logic CTL Model Checking

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# Class project

Midterm project presentation: **3/26** and **3/28**. (Next week!)

- **5-min** presentations for each team. (5% of final grade)
- Slides due on **3/25**. We will compile all slides into a single file for fast switching.
- Presentation includes **problem setting**, proposed **methodology**, and **initial results**.
- I will give you some feedback after your presentation (1-min)

In addition: each person should give feedback for **3** projects that interest you most on each day. (total **6** feedbacks; count towards the **5% class participation** grades. Feedback will be submitted to Canvas and also shared to peers. Feedback template will be given.)

# Outline

- Temporal logics
  - Computational Tree Logic (CTL)
- CTL model checking for automata
  - Setup
  - CTL syntax and semantics
  - Model checking algorithms
  - Example
- References: Model Checking, Second Edition, by Edmund M. Clarke, Jr., Orna Grumberg, Daniel Kroening, Doron Peled and Helmut Veith
- Principles of Model Checking, by Christel Baier and Joost-Pieter Katoen

# Introduction to temporal logics

Temporal logics: Formal language for representing, and reasoning about, propositions qualified in terms of a sequence

Amir Pnueli received the ACM Turing Award (1996) for seminal work introducing temporal logic into computer science and for outstanding contributions to program verification.



Large follow-up literature, e.g., different temporal logics MTL, MITL, PCTL, ACTL, STL, applications in synthesis and monitoring

# Setup: States are labeled

We have a set of **atomic propositions (AP)**

These are the properties that hold in each state, e.g., “light is green”, “has 2 tokens”, “oven is hot”

We have a **labeling function** that assigns to each state, a set of propositions that hold at that state

$$L: Q \rightarrow 2^{AP}$$

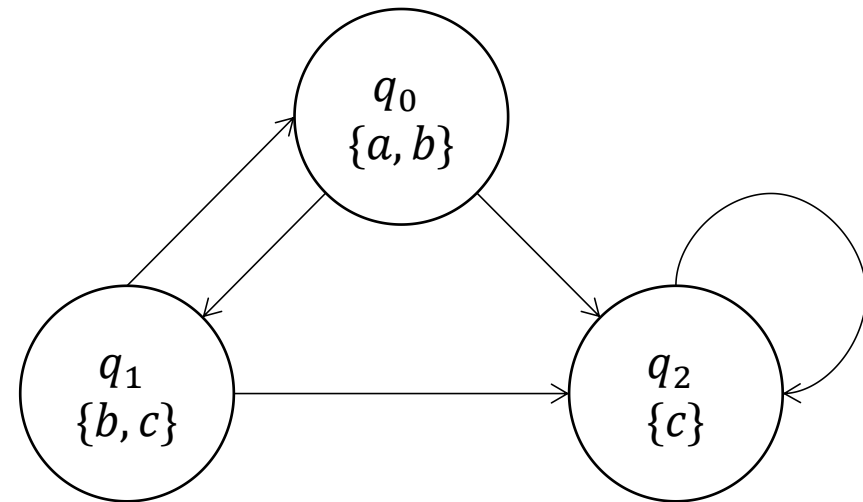
# Notations

Automata with state labels but no action labels (“Kripke structure”)

$$\mathcal{A} = \langle Q, Q_0, T, L \rangle$$

$$AP = \{a, b, c\}$$

$$L(q_0) = \{a, b\}$$

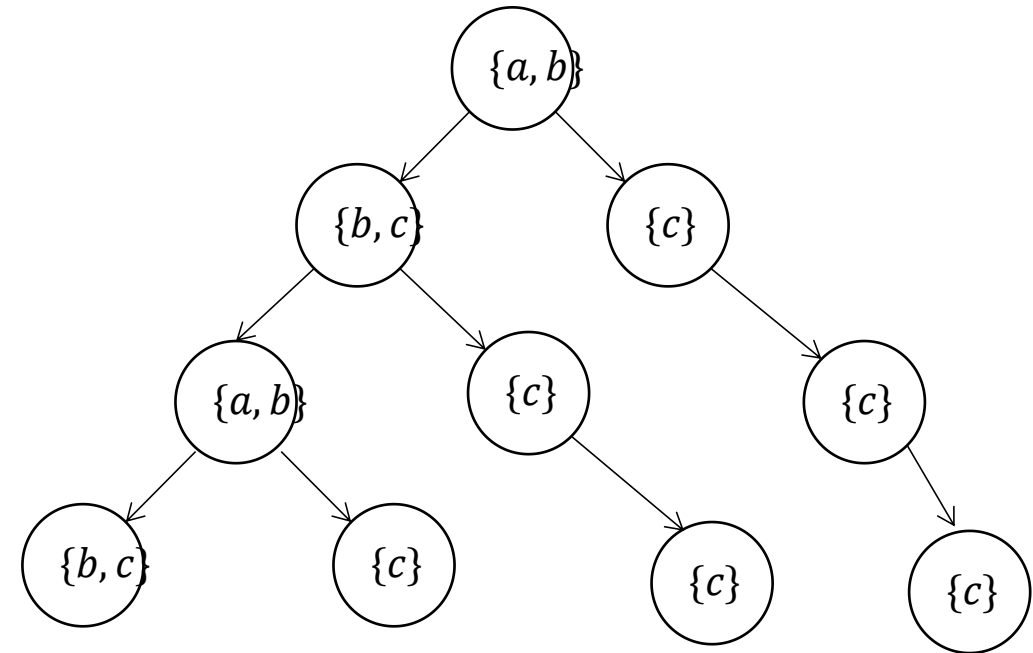
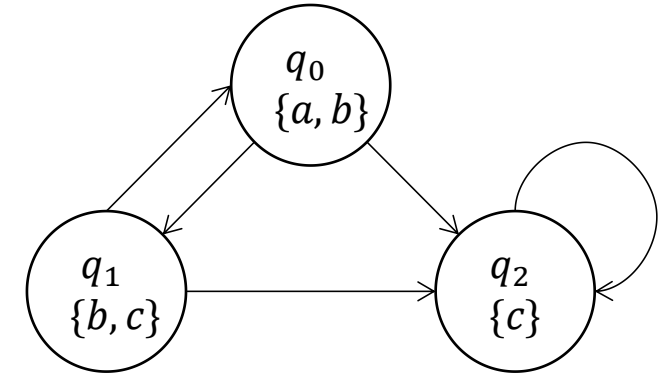


# Computational tree logic (CTL)

## Unfolding the automaton

We get a tree, representing all possible computations

A **CTL formula** allows us to specify subsets of paths in this tree



# CTL quantifiers

## Path quantifiers

E: Exists some path

A: All paths

$\phi$ : “no collision”

Invariance:  $AG\phi$

## Temporal operators

X: Next state

U: Until (“p U q” means “p holds until q holds”)

F: Eventually (some time in future)

G: Globally (always)

$\phi$ : “one token”

Stabilization:  $AF\phi$



# Visualizing CTL semantics

## Path quantifiers

E: Exists some path

A: All paths

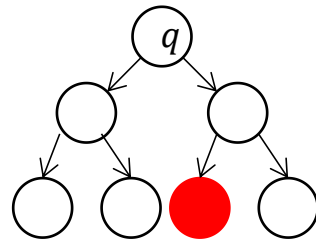
## Temporal operators

X: Next state

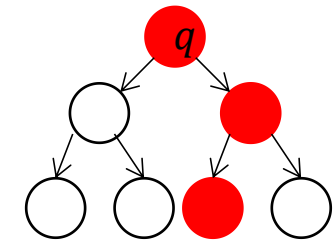
U: Until

F: Eventually

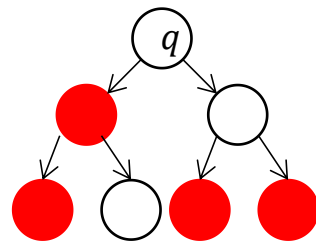
G: Globally (Always)



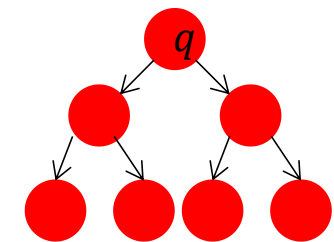
$$q \models EF \text{ red}$$



$$q \models EG \text{ red}$$



$$q \models AF \text{ red}$$



$$q \models AG \text{ red}$$

# Visualizing CTL semantics

## Path quantifiers

E: Exists some path

A: All paths

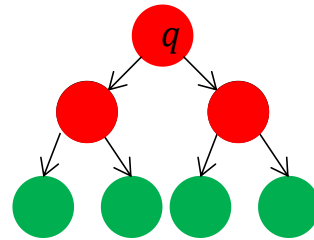
## Temporal operators

X: Next state

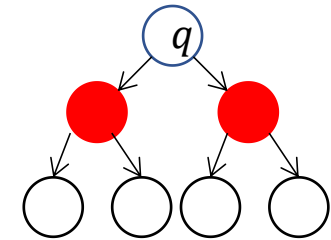
U: Until

F: Eventually

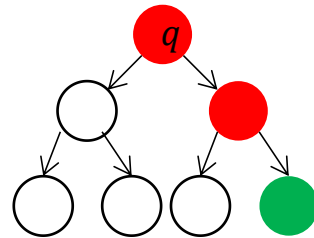
G: Globally (Always)



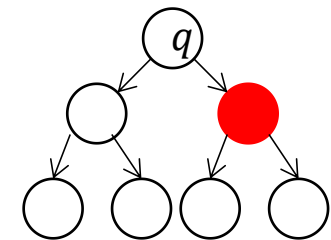
$$q \models A [red \ U \ green]$$



$$q \models AX \ red$$



$$q \models E [red \ U \ green]$$



$$q \models EX \ red$$

# CTL syntax

## CTL syntax

*State Formula (SF)* ::=  $true \mid p \mid \neg f_1 \mid f_1 \wedge f_2 \mid E \phi \mid A \phi$

*Path Formula (PF)* ::=  $Xf_1 \mid f_1 U f_2 \mid Gf_1 \mid Ff_1$

where  $p \in AP, f_1, f_2 \in SF, \phi \in PF$

## Examples:

everything in the previous two slides;

**AG** ( $p_1 \Rightarrow$  **AF**  $p_2$ )

## Non-examples

$AXX a$ ; path and state operators must alternate in CTL

# CTL syntax

## CTL syntax

*State Formula (SF)* ::=  $true \mid p \mid \neg f_1 \mid f_1 \wedge f_2 \mid E \phi \mid A \phi$

*Path Formula (PF)* ::=  $Xf_1 \mid f_1 U f_2 \mid Gf_1 \mid Ff_1$

where  $p \in AP$ ,  $f_1, f_2 \in SF$ ,  $\phi \in PF$

**Depth** of formula: number of production rules used

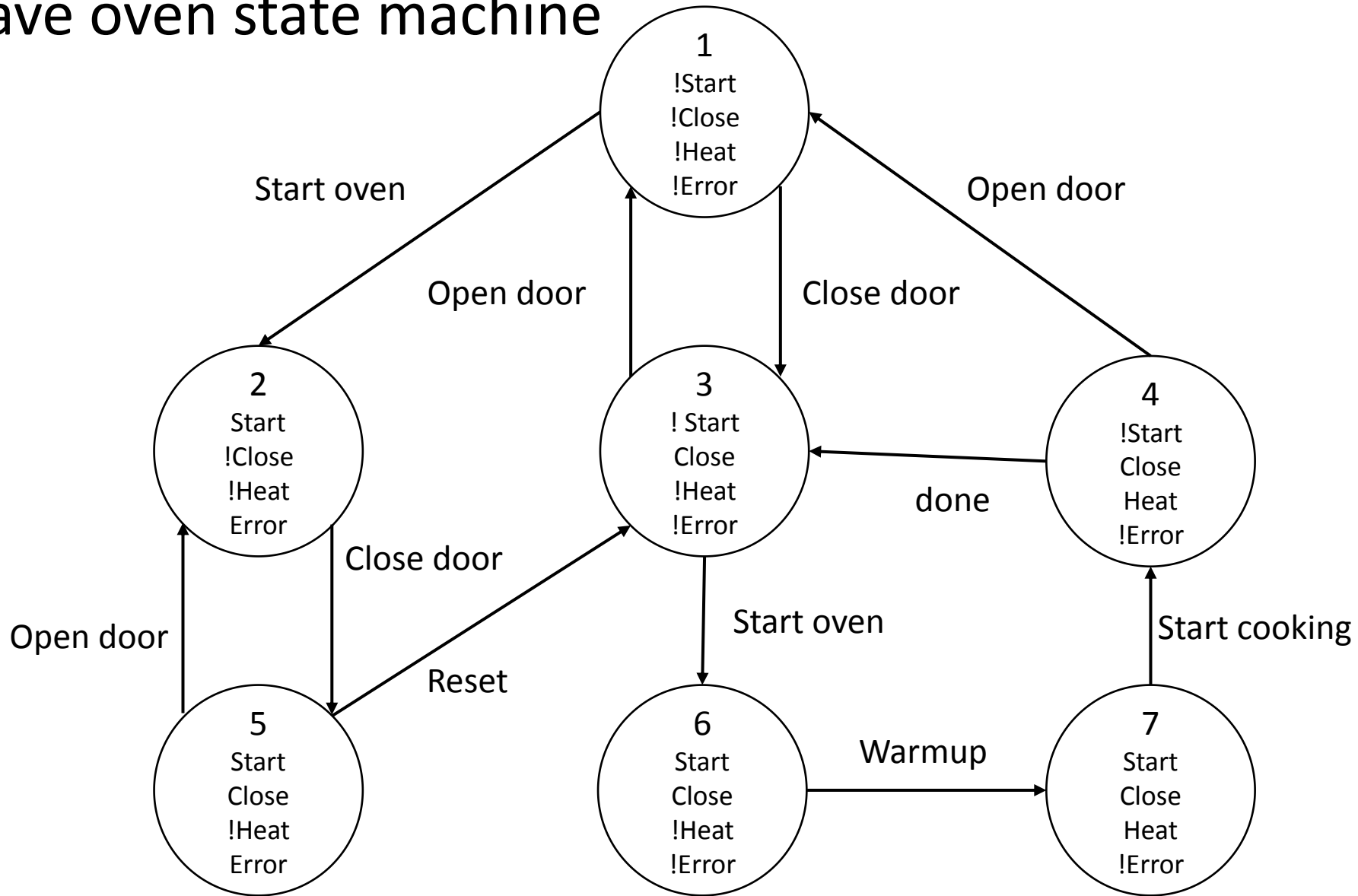
$EX a$ ; (depth 3)

$AX EX a$ ; (depth 5)

$AG AF \text{ green}$ ; (depth 5)

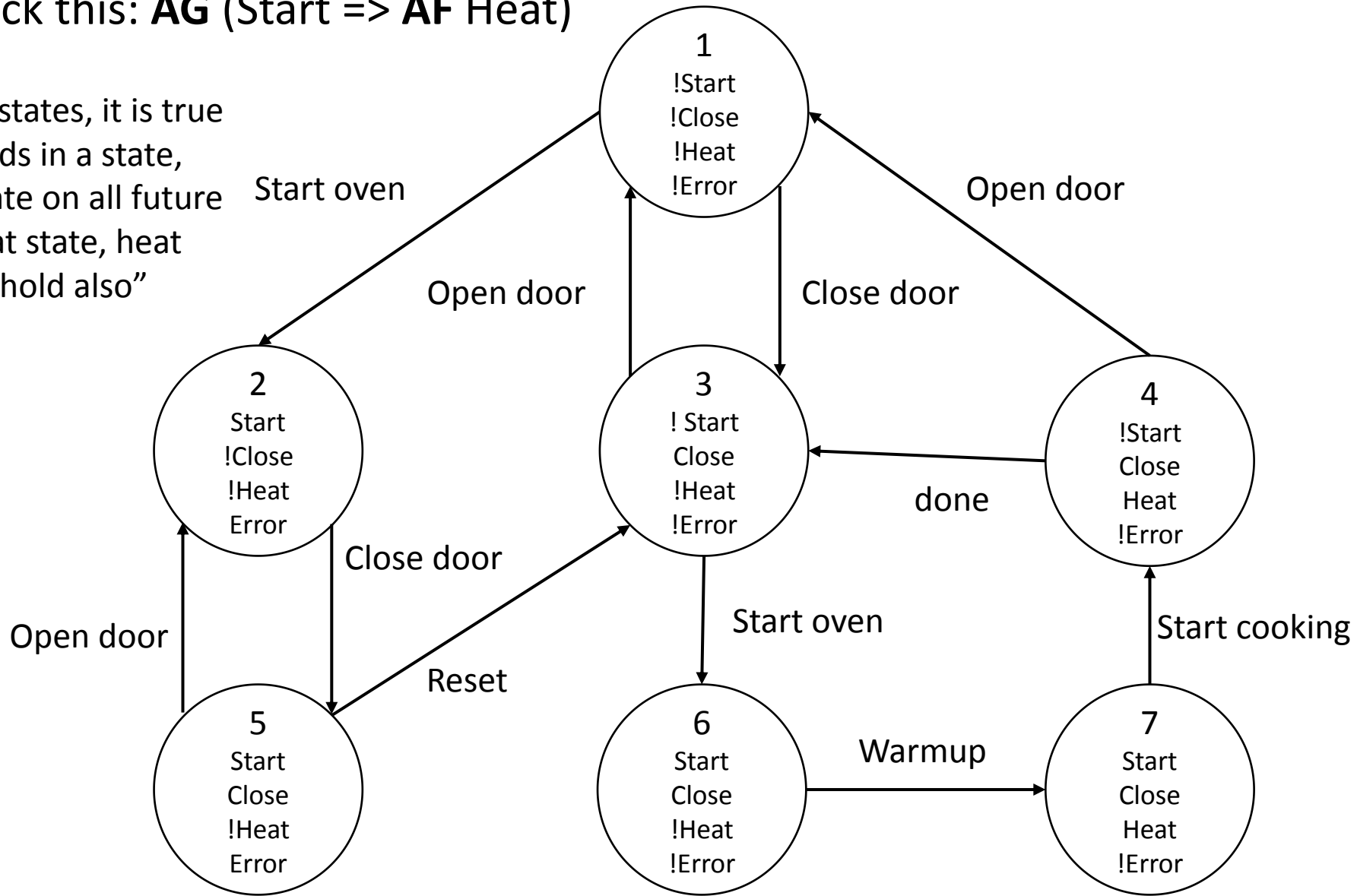
$AF AG \text{ single token}$  (depth 5)

# microwave oven state machine



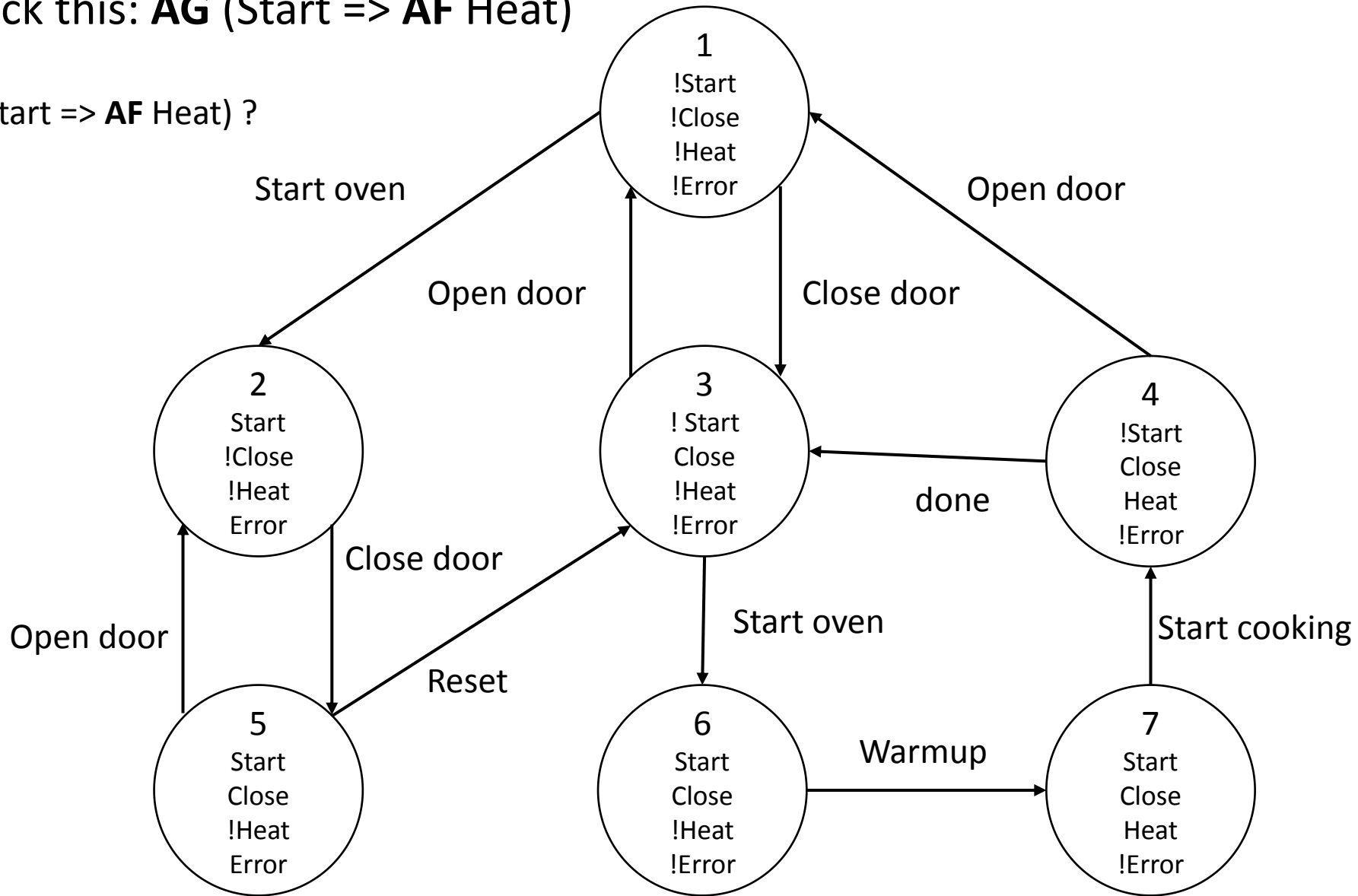
# Let's check this: **AG** (Start => **AF** Heat)

**English:** "In all states, it is true that if start holds in a state, then in some state on all future paths from that state, heat will eventually hold also"



Let's check this: **AG** (Start => **AF** Heat)

$q_1 \models \mathbf{AG} (\text{Start} \Rightarrow \mathbf{AF} \text{Heat}) ?$



# CTL semantics

Automaton  $\mathcal{A} = \langle Q, Q_0, T, L \rangle$ ,  $q \in Q$

CTL formula  $\phi$

For a state  $q$ ,  $q \models \phi$  denotes that  $q$  satisfies  $\phi$

For a execution  $\alpha$ ,  $\alpha \models \phi$  denotes that path (execution)  $\alpha$  satisfies  $\phi$



# CTL semantics (cont.)

Here  $\models$  is defined inductively as:

Example:  $q_1 \models \mathbf{AG} (\text{Start} \Rightarrow \mathbf{AF} \text{Heat})$

$$q \models p \iff p \in L(q), \text{ for } p \in AP$$

$$q \models \neg f_1 \iff q \not\models f_1$$

$$q \models f_1 \wedge f_2 \iff q \models f_1 \wedge q \models f_2$$

$$q \models E\phi \iff \exists \alpha, \alpha.fstate = q, \alpha \models \phi$$

$$q \models A\phi \iff \forall \alpha, \alpha.fstate = q, \alpha \models \phi$$

$$\alpha \models Xf \iff \alpha[1] \models f$$

$$\alpha \models f_1 U f_2 \iff \exists i \geq 0, \alpha[i] \models f_2 \text{ and } \forall j < i \alpha[j] \models f_1$$

$$\alpha \models F f_1 \iff \exists i \geq 0, \alpha[i] \models f_1$$

$$\alpha \models G f_1 \iff \forall i \geq 0, \alpha[i] \models f_1$$

Automaton satisfies property:  
 $\mathcal{A} \models f$  iff  $\forall q \in Q_0, q \models f$

# Universal CTL operators

***X***, ***U***, ***G*** can be used to derive other operators

$$\text{true } U f \equiv F f$$

$$Gf \equiv \neg F(\neg f)$$

All combinations can be expressed using ***EX***, ***EU***, ***EG***

$AXf$	$AGf$	$AFf$	$A[f_1 U f_2]$
$\neg EX(\neg f)$	$\neg EF(\neg f)$	$\neg EG(\neg f)$	$\neg(E[(\neg f_1)U\neg(f_1 \vee f_2)] \vee EG(\neg f_2))$
$EX$	$EG$	$EF$	$EU$
$EX$	$EG$	$E(\text{true } U f)$	$EU$

# Algorithm for deciding $\mathcal{A} \models f$

Algorithm works by structural induction on the depth of the formula

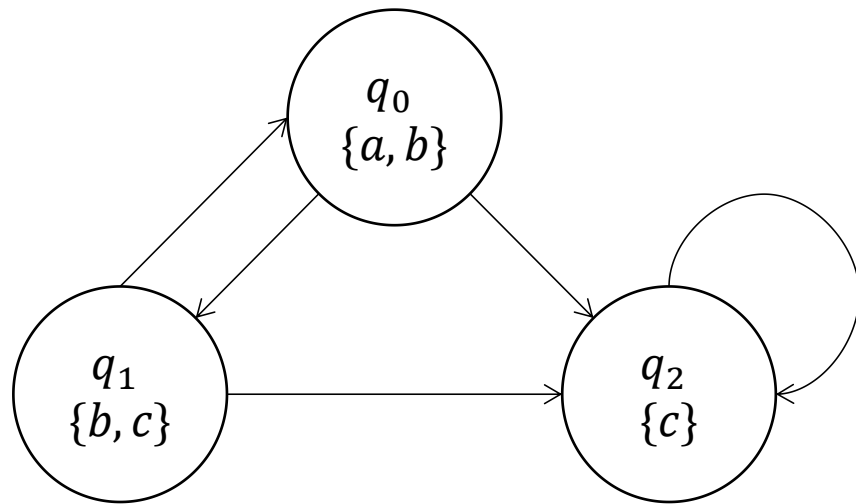
Explicit state model checking

Compute the subset  $Q' \subseteq Q$  such that  $\forall q \in Q'$  we have  $q \models f$

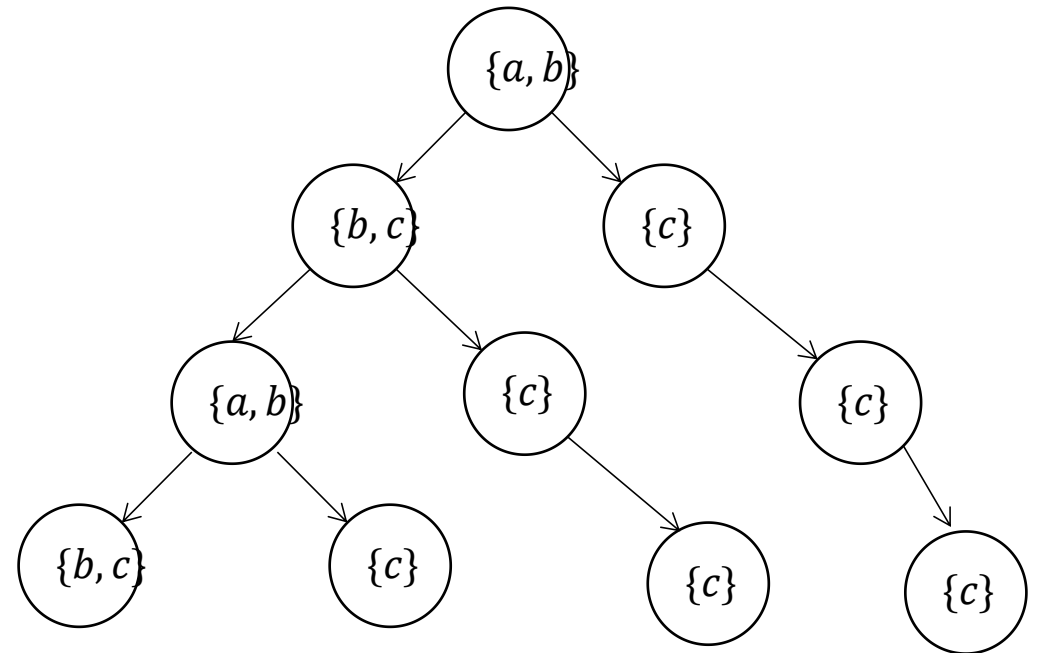
If  $Q_0 \subseteq Q'$  then we can conclude  $\mathcal{A} \models f$

# Algorithm for deciding $\mathcal{A} \models f$

Since all CTL operators can be expressed by EX, EU, EG, we just need to figure out how to check these operators



$\mathcal{A}$



CTL: e.g., **AG** ( $a \Rightarrow \mathbf{AF} b$ )

# Induction on depth of formula

Algorithm computes a function  $label: Q \rightarrow CTL(AP)$  that labels each state with a CTL formula

- Initially,  $label(q) = L(q)$  for each  $q \in Q$
- At  $i^{th}$  iteration  $label(q)$  contains all sub-formulas of  $f$  of depth  $(i - 1)$  that  $q$  satisfies

At termination  $f \in label(q) \Leftrightarrow q \models f$

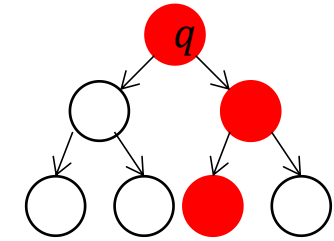
# $CheckEG(f_1, Q, T, L)$

From  $\mathcal{A}$  we construct a new automaton  $\mathcal{A}' = \langle Q', T', L' \rangle$  such that

$$Q' = \{q \in Q \mid f_1 \in label(q)\}$$

$$T' = \{\langle q_1, q_2 \rangle \in T \mid q_1 \in Q'\}$$

$$L': Q' \rightarrow 2^{AP} \quad \forall q' \in Q', L'(q') := L(q')$$



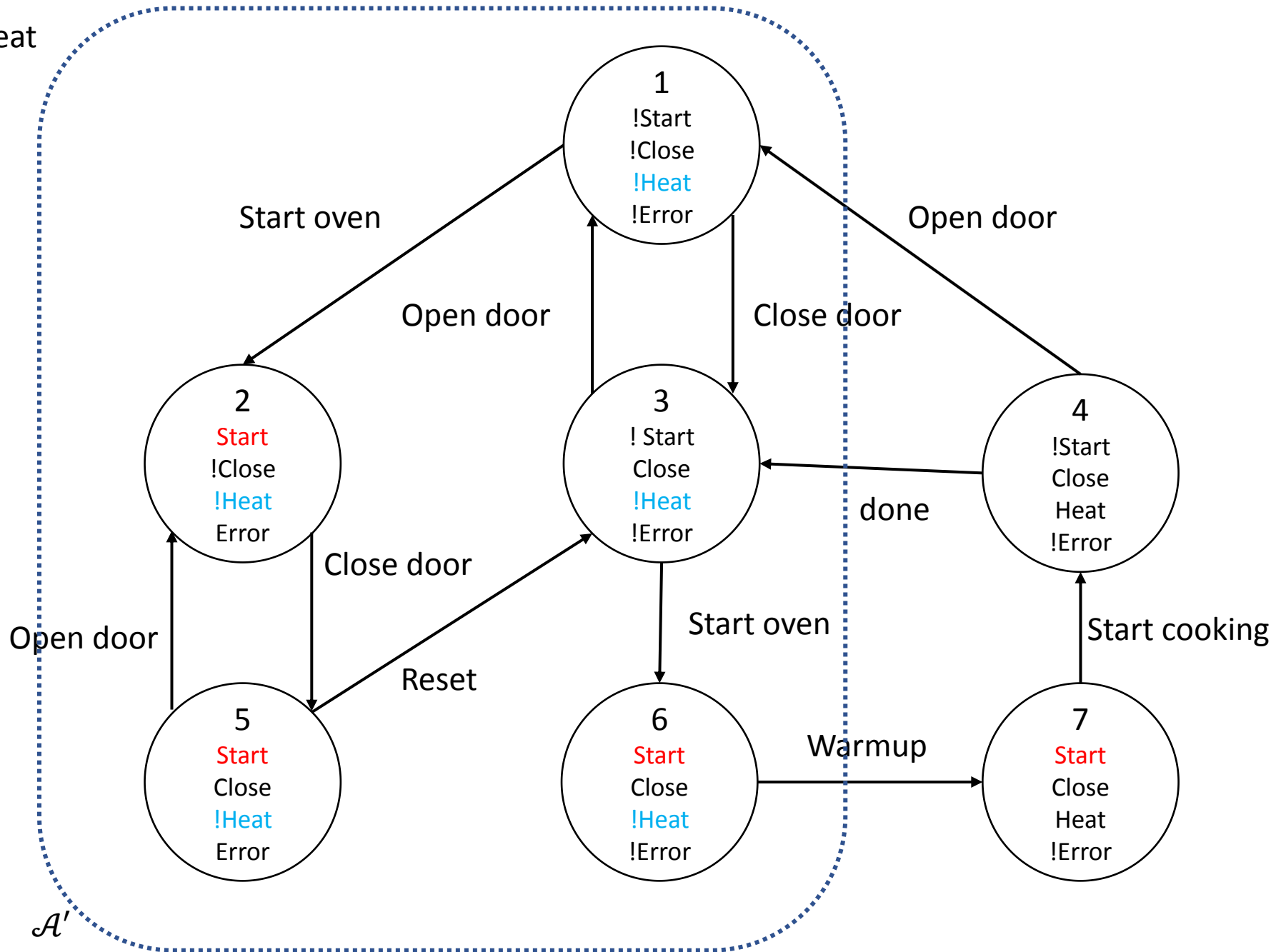
**Claim.**  $q \models EGf_1$  iff

(1)  $q \in Q'$

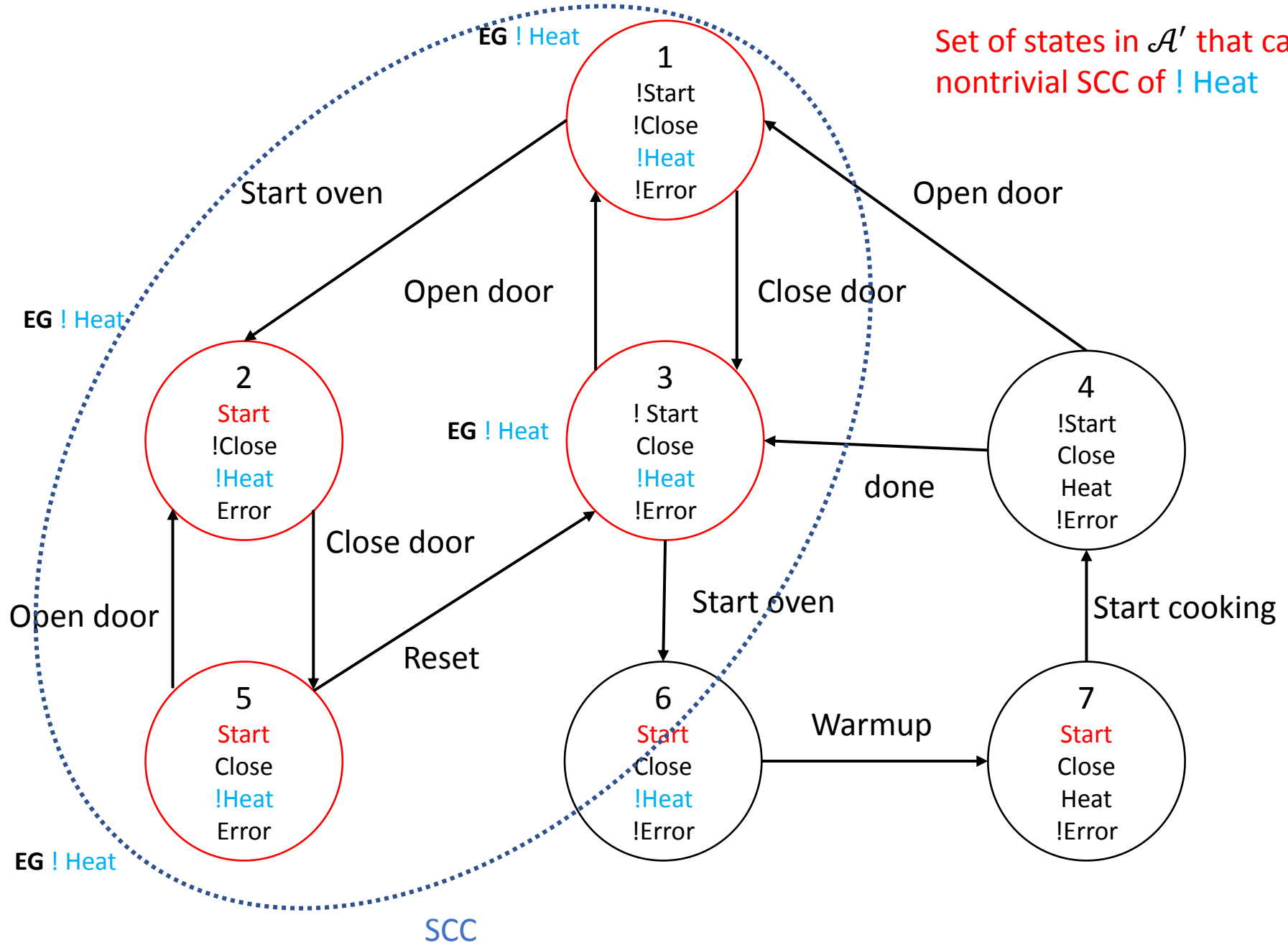
(2)  $\exists \alpha \in Execs_{\mathcal{A}'}$ , with  $\alpha.fstate = q$  and  $\alpha.lstate$  is in a nontrivial **Strongly**

**Connected Components**  $C$  of the graph  $\langle Q', T' \rangle$

Check EG ! Heat



$\mathcal{A}'$





**Claim.**  $\mathcal{A}, q \models EGf_1$  iff

(1)  $q \in Q'$  and

(2)  $\exists \alpha \in Execs_{\mathcal{A}}$ , with  $\alpha.fstate = q$  and  $\alpha.lstate$  is in a nontrivial SCC  $C$  of the graph  $\langle Q', T' \rangle$

**Proof.** Suppose  $\mathcal{A}, q \models EGf_1$

Consider any execution  $\alpha$  with  $\alpha.fstate = q$ . Obviously,  $q \models f_1$  and so,  $q \in Q'$ . Since  $Q$  is finite  $\alpha$  can be written as  $\alpha = \alpha_0\alpha_1$  where  $\alpha_0$  is finite and every state in  $\alpha_1$  repeats infinitely many times.

Let  $C$  be the states in  $\alpha_1$ .  $C \in Q'$ .

Consider any two  $q_1$  and  $q_2$  states in  $C$ , we observe that  $q_1 \rightleftarrows q_2$ , and therefore  $C$  is a SCC.

Consider (1) and (2). We construct a path  $\alpha = \alpha_0\alpha_1$  such that  $\alpha_0.fstate = q$  and  $\alpha_0 \in Q'$  and  $\alpha_1$  visits some states infinitely often.

# *CheckEG*( $f_1, Q, T, L$ )

Let  $Q' = \{q \in Q \mid f_1 \in \text{label}(q)\}$

Let  $\mathbb{C}$  be the set of nontrivial SCCs of  $\langle Q', T' \rangle$

$T = \cup_{C \in \mathbb{C}} \{q \mid q \in C\}$

for each  $q \in T$

$\text{label}(q) := \text{label}(q) \cup \{EGf_1\}$

while  $T \neq \emptyset$

for each  $q \in T$

$T := T \setminus \{q\}$

for each  $q' \in Q'$  such that  $(q', q) \in T'$

if  $EGf_1 \notin \text{label}(q')$  then

$\text{label}(q') := \text{label}(q') \cup \{EGf_1\}$

$T := T \cup \{q'\}$

Find all states in  $Q'$  that  
can reach the SCCs

**Proposition.** For any state  $\text{label}(q) \ni EGf_1$  iff  $q \models EGf_1$ .

**Proposition.** Finite  $Q$  therefore terminates and in  $O(|Q| + |T|)$  steps.

# CheckEU( $f_1, f_2, Q, T, L$ )

Let  $S = \{q \in Q \mid f_2 \in \text{label}(q)\}$

for each  $q \in S$

all states where  $f_2$  is true already satisfies

$\text{label}(q) := \text{label}(q) \cup \{E[f_1 U f_2]\}$

while  $S \neq \emptyset$

for each  $q' \in S$

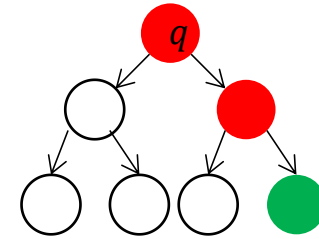
$S := S \setminus \{q'\}$

for each  $q \in T^{-1}(q')$       Check all states whose next state is  $q'$

if  $f_1 \in \text{label}(q)$  then      This if statement will be always true for EF  $f_2$

$\text{label}(q) := \text{label}(q) \cup \{E[f_1 U f_2]\}$

$S := S \cup \{q\}$



$E[f_1 U f_2]$

**Proposition.** For any state  $label(q) \ni E[f_1 U f_2]$  iff  $q \models E[f_1 U f_2]$ .

**Proposition.** Finite  $Q$  therefore terminates and in  $O(|Q| + |T|)$  steps.

# Structural induction on formula

Six cases to consider based on structure of  $f$

$f = p$ , for some  $p \in AP$ ,  $\forall q, label(q) := label(q) \cup f$

$f = \neg f_1$  if  $f_1 \notin label(q)$  then  $label(q) := label(q) \cup f$

$f = f_1 \wedge f_2$  if  $f_1, f_2 \in label(q)$  then  $label(q) := label(q) \cup f$

$f = EXf_1$  if  $\exists q' \in Q$  such that  $(q, q') \in T$  and  $f_1 \in label(q')$ , then  $label(q) := label(q) \cup f$

$f = E[f_1 U f_2]$   $CheckEU(f_1, f_2, Q, T, L)$

$f = EGf_1$   $CheckEG(f_1, Q, T, L)$

# Putting it all together

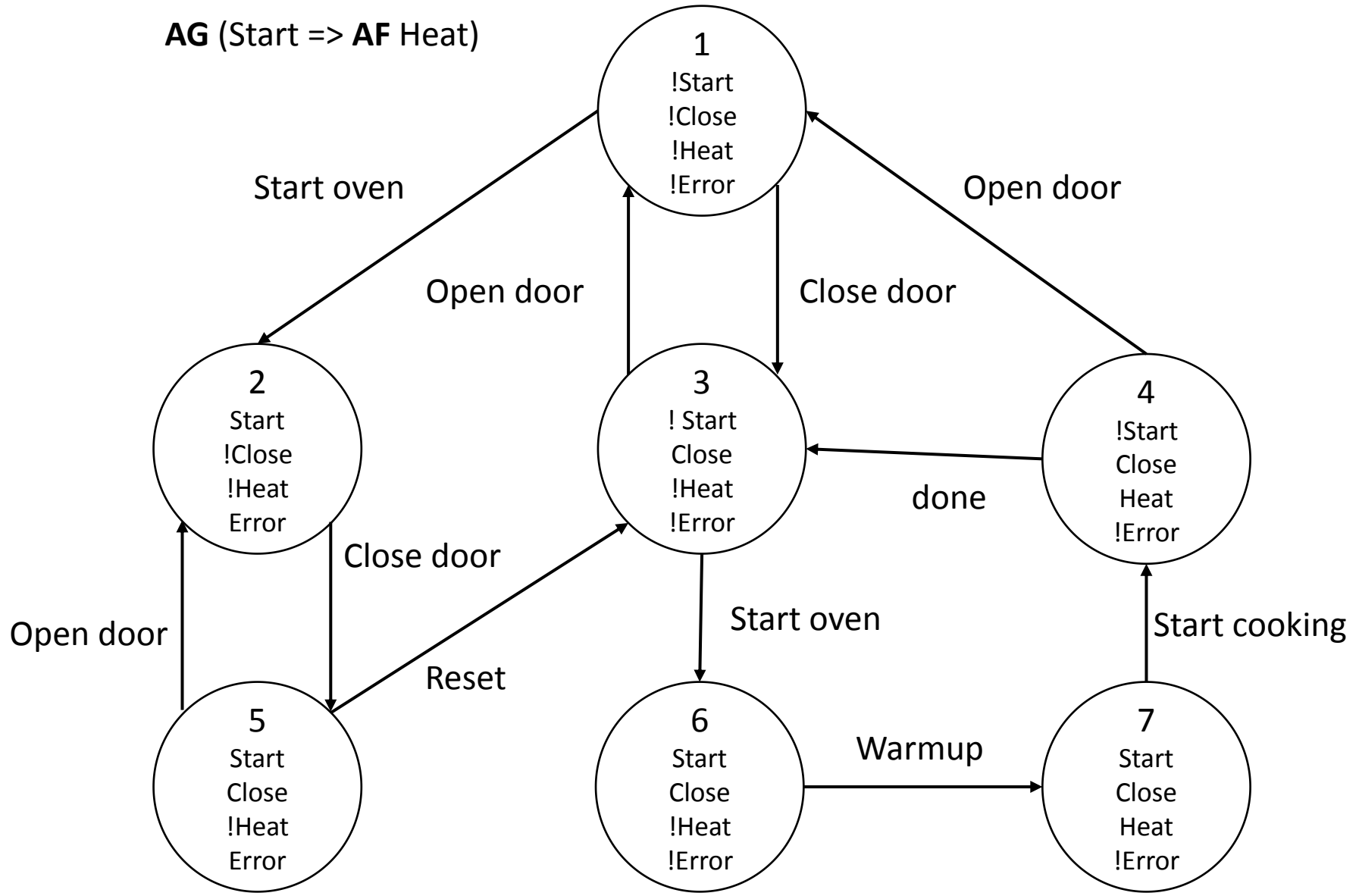
Explicit model checking algorithm input  $\mathcal{A} \models f?$

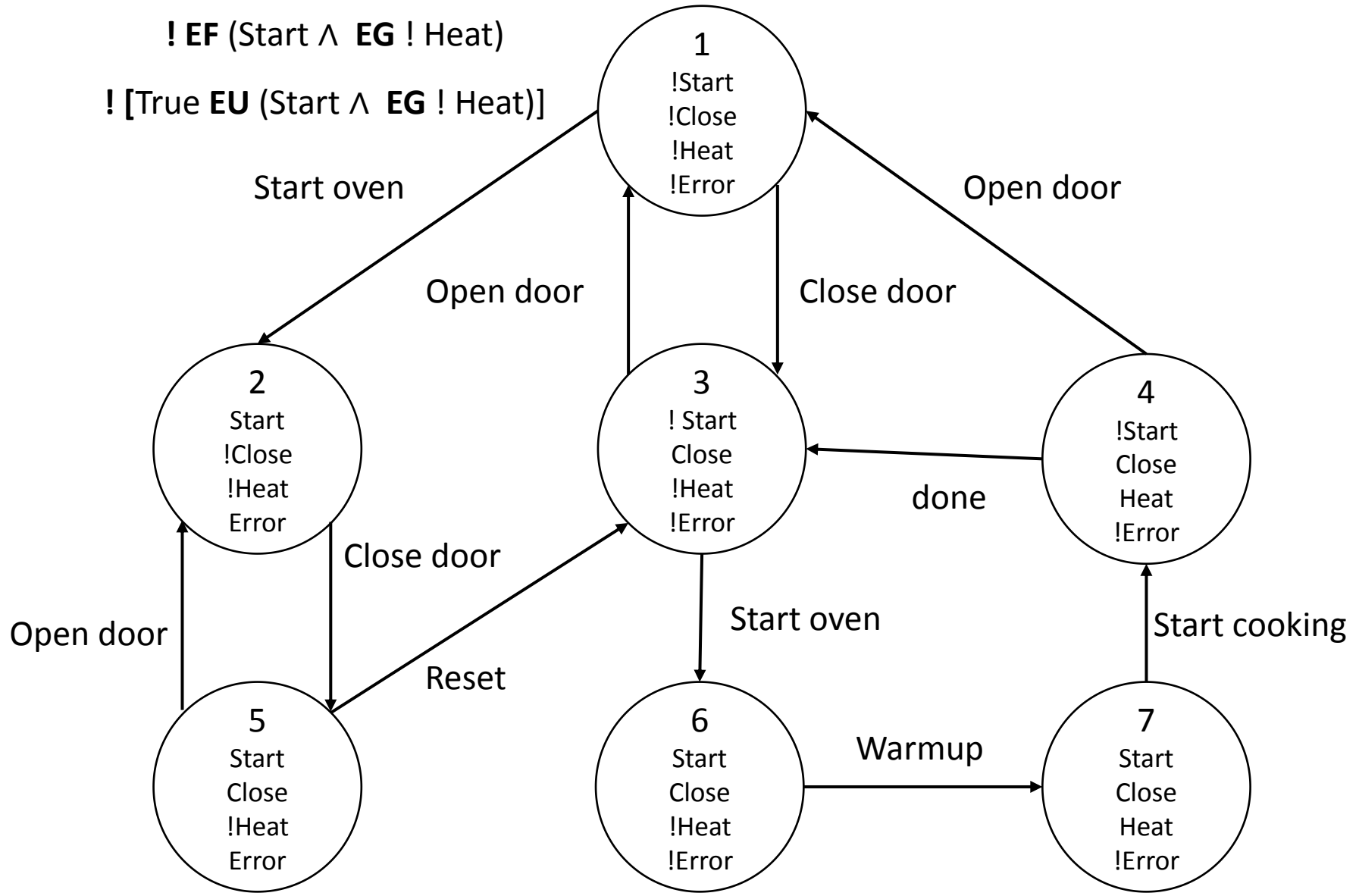
Structural induction over CTL formula

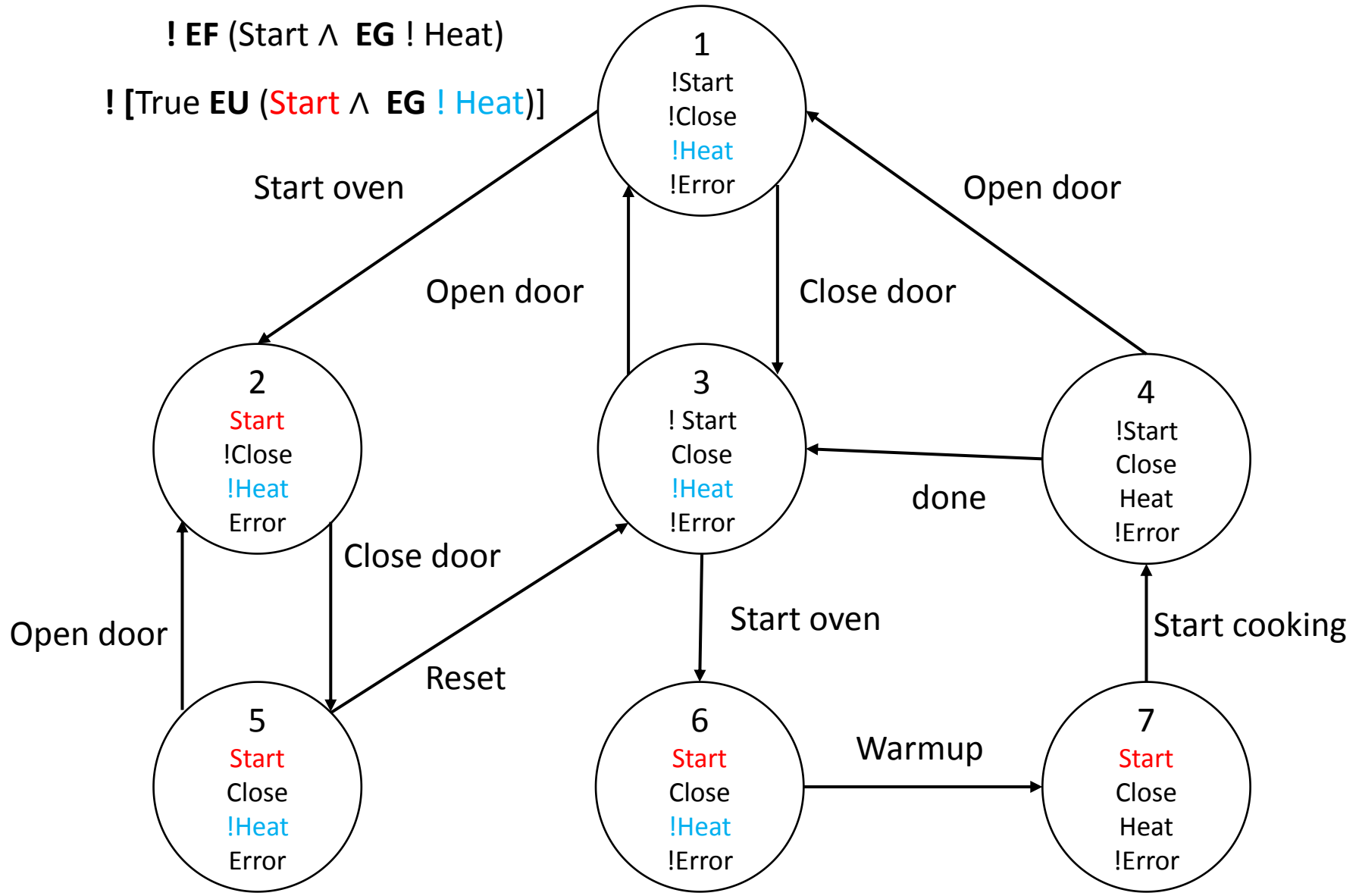
$f = p,$	for some $p \in AP, \forall q, label(q) := label(q) \cup \{p\}$
$f = \neg f_1$	if $f_1 \notin label(q)$ then $label(q) := label(q) \cup f$
$f = f_1 \wedge f_2$	if $f_1, f_2 \in label(q)$ then $label(q) := label(q) \cup f$
$f = EXf_1$	if $\exists q' \in Q$ such that $(q, q') \in T$ and $f_1 \in label(q')$ then $label(q) := label(q) \cup f$
$f = E[f_1 U f_2]$	$CheckEU(f_1, f_2, Q, T, L)$
$f = EGf_1$	$CheckEG(f_1, Q, T, L)$

**Proposition.** Overall complexity of CTL model checking  $O(|f|(|Q| + |T|))$  steps.

**AG (Start => AF Heat)**







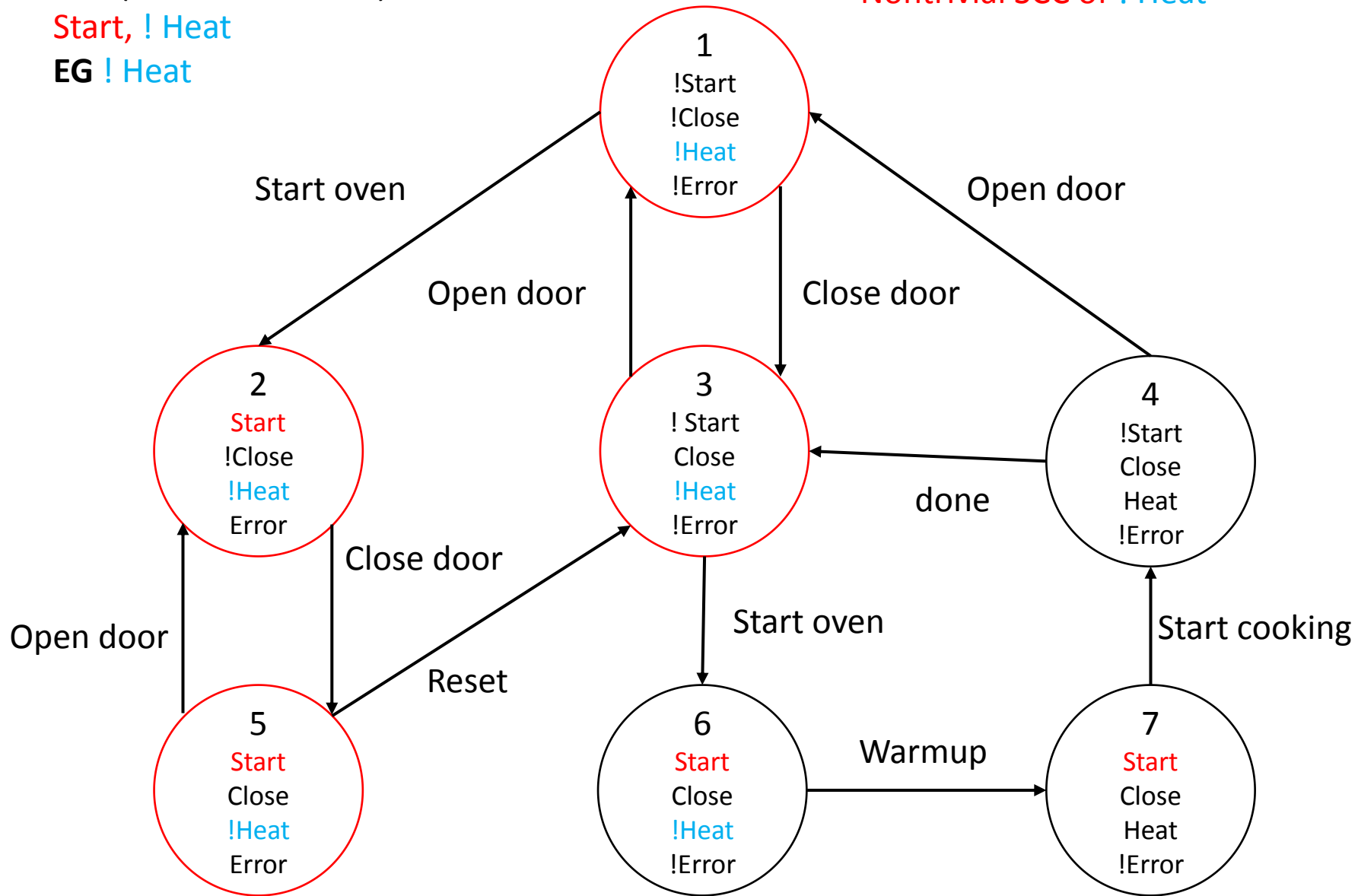


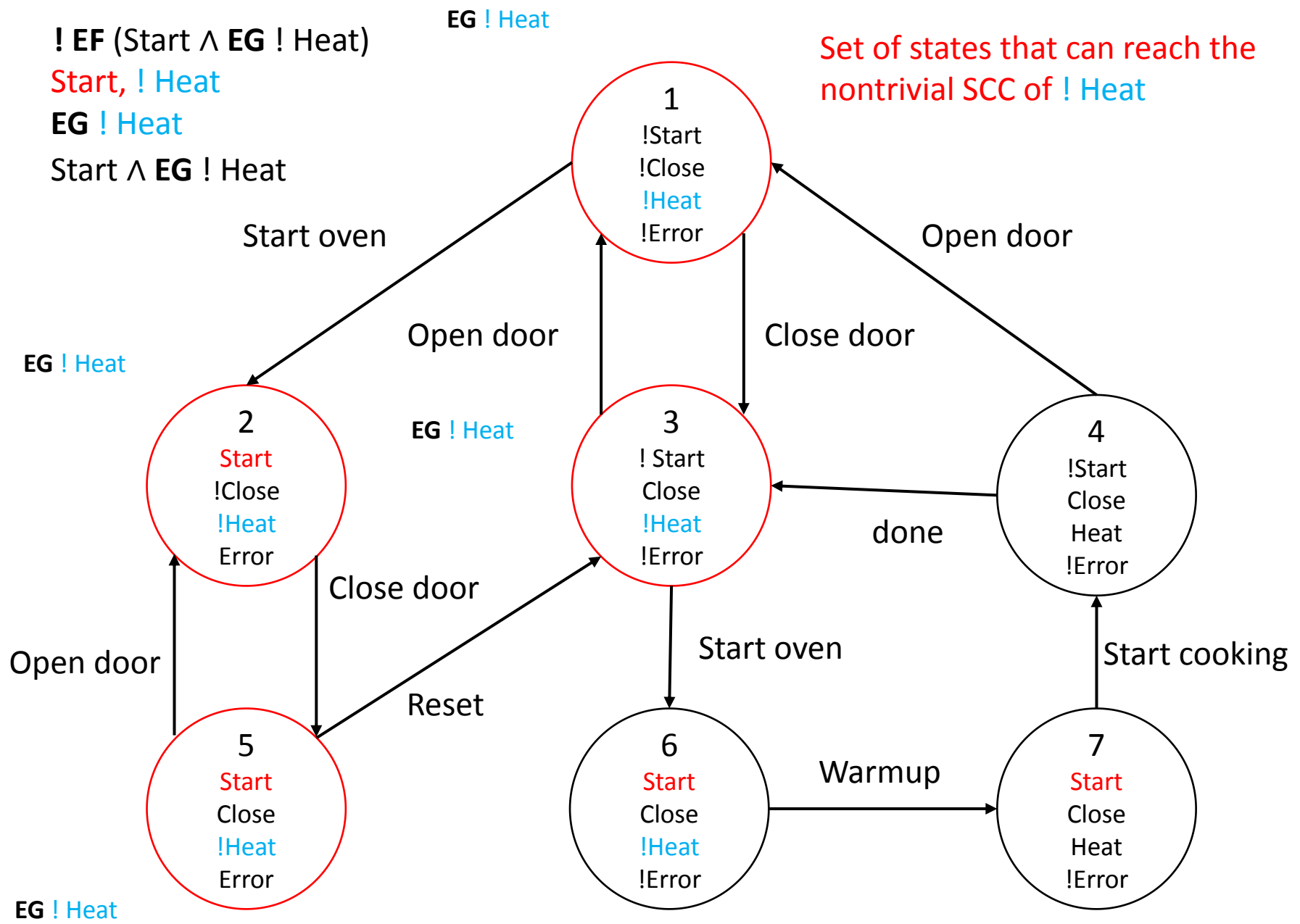
**! EF (Start  $\wedge$  EG ! Heat)**

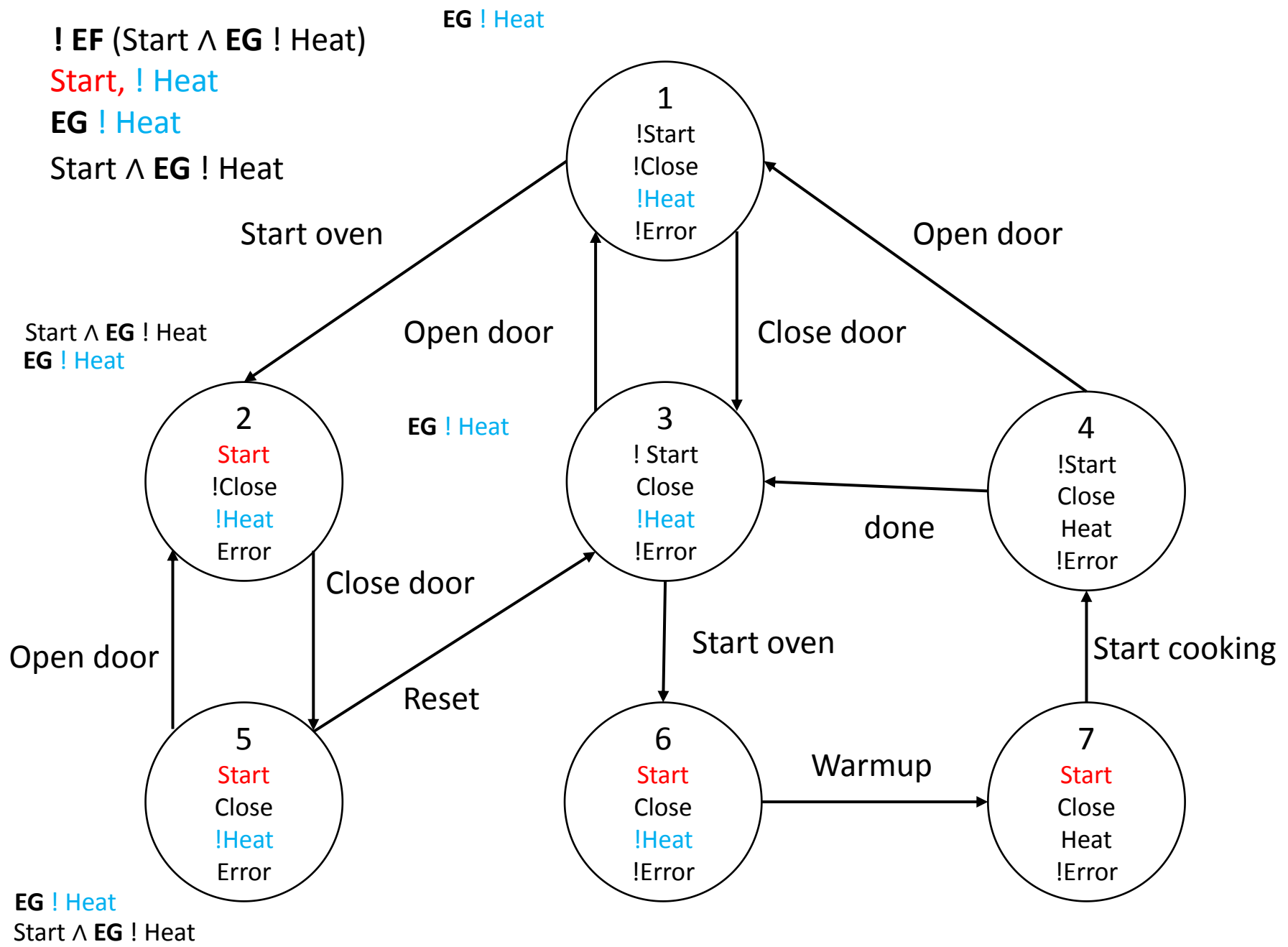
Start, ! Heat

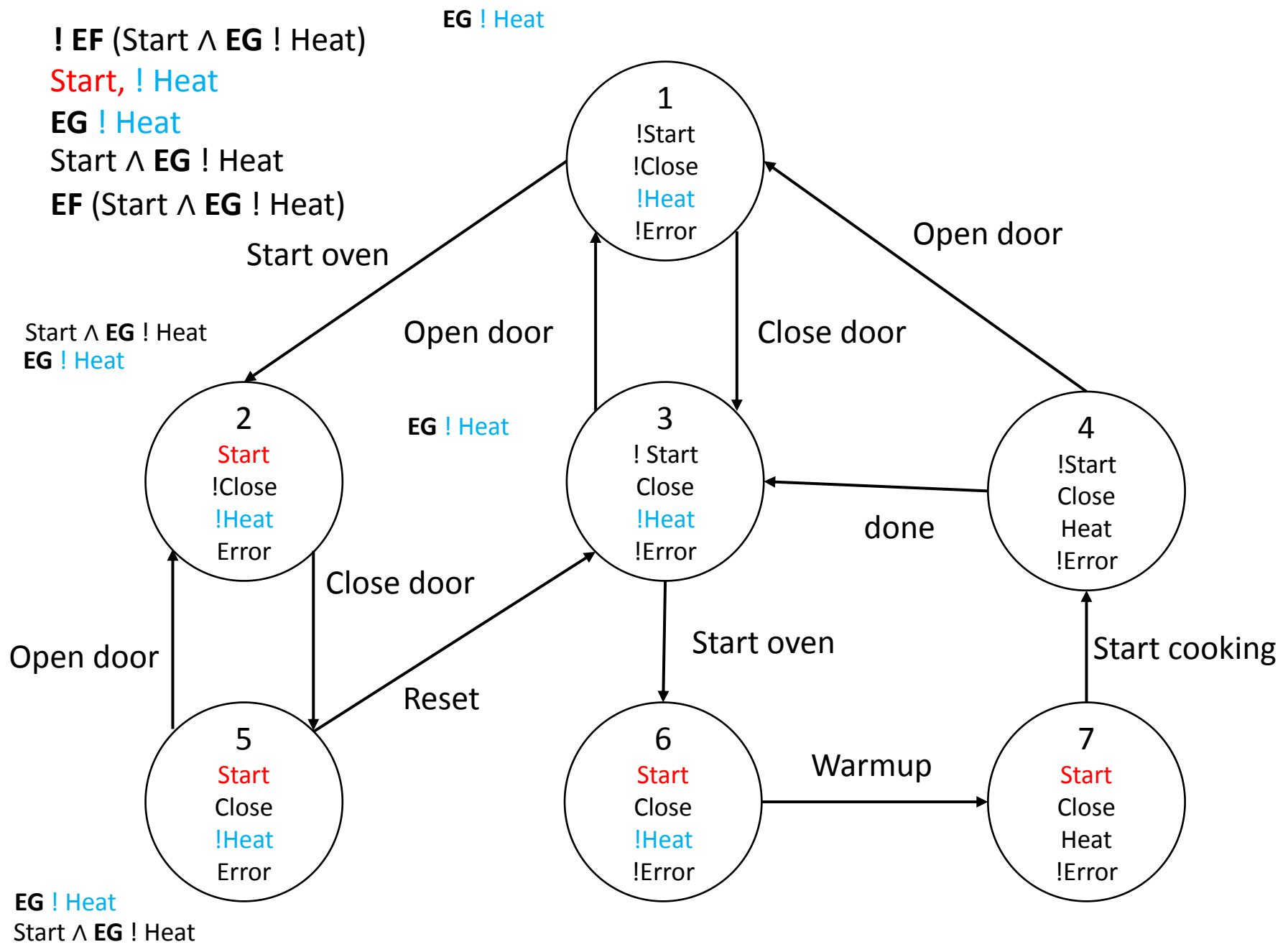
EG ! Heat

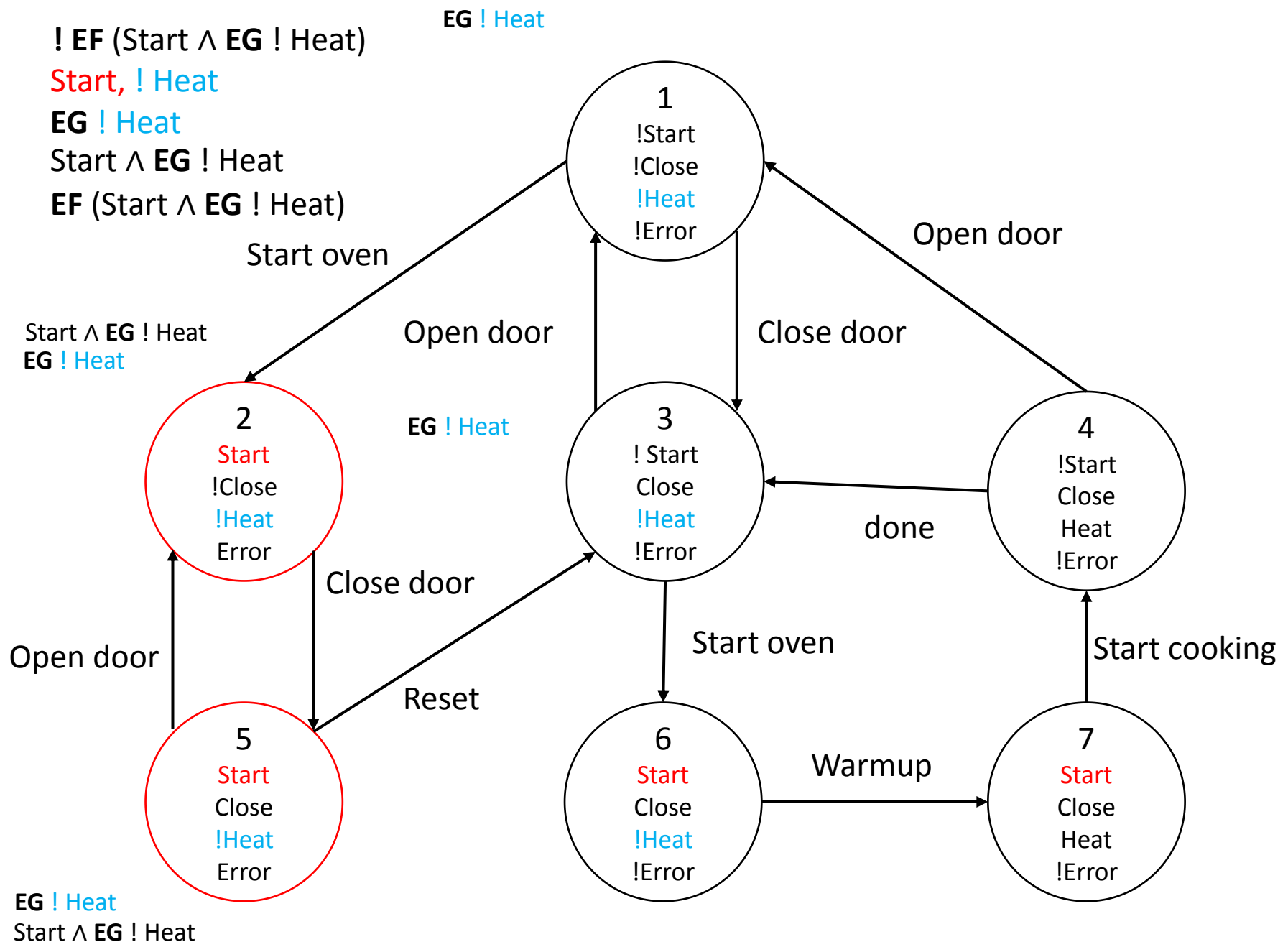
Nontrivial SCC of ! Heat

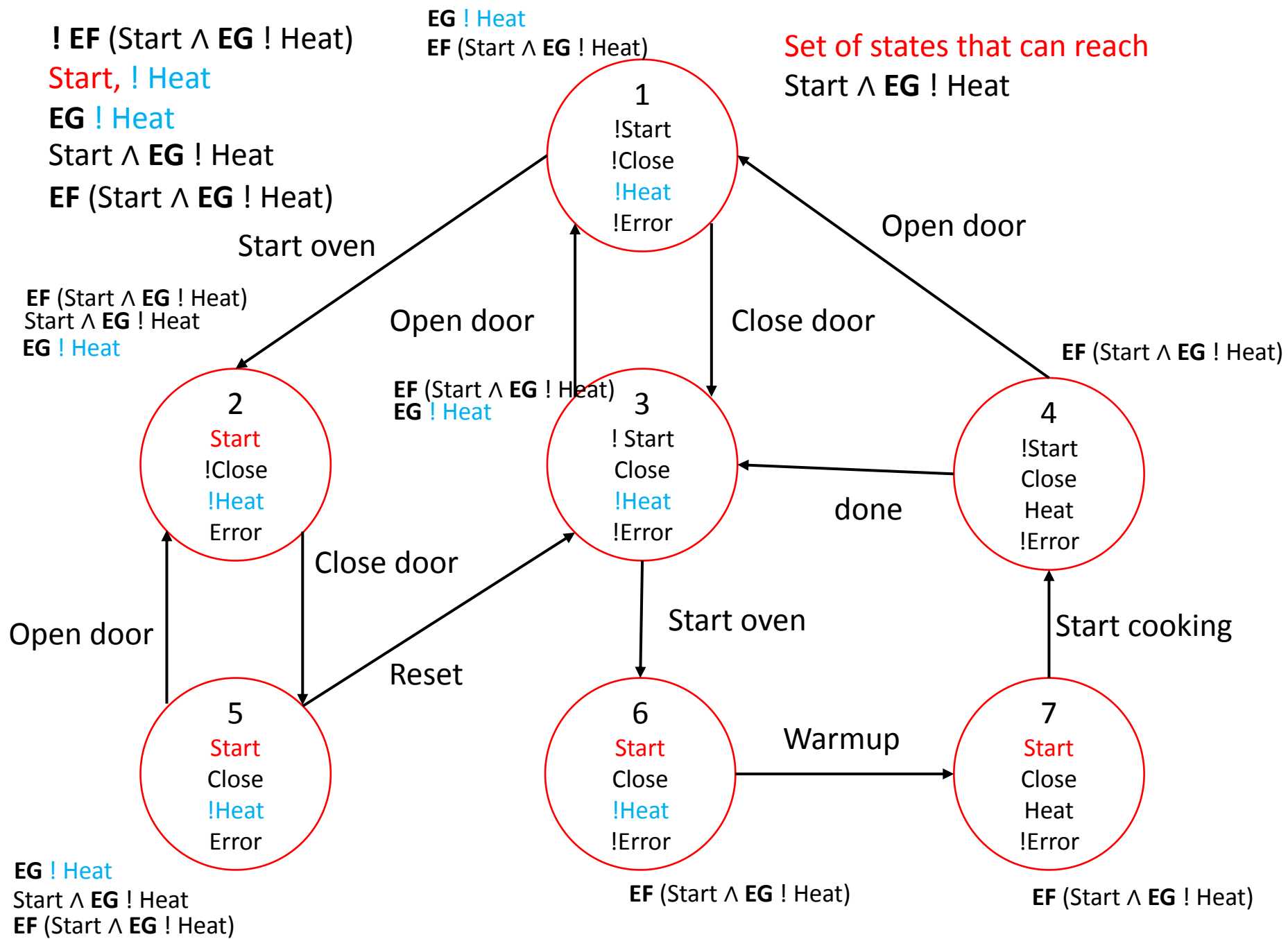










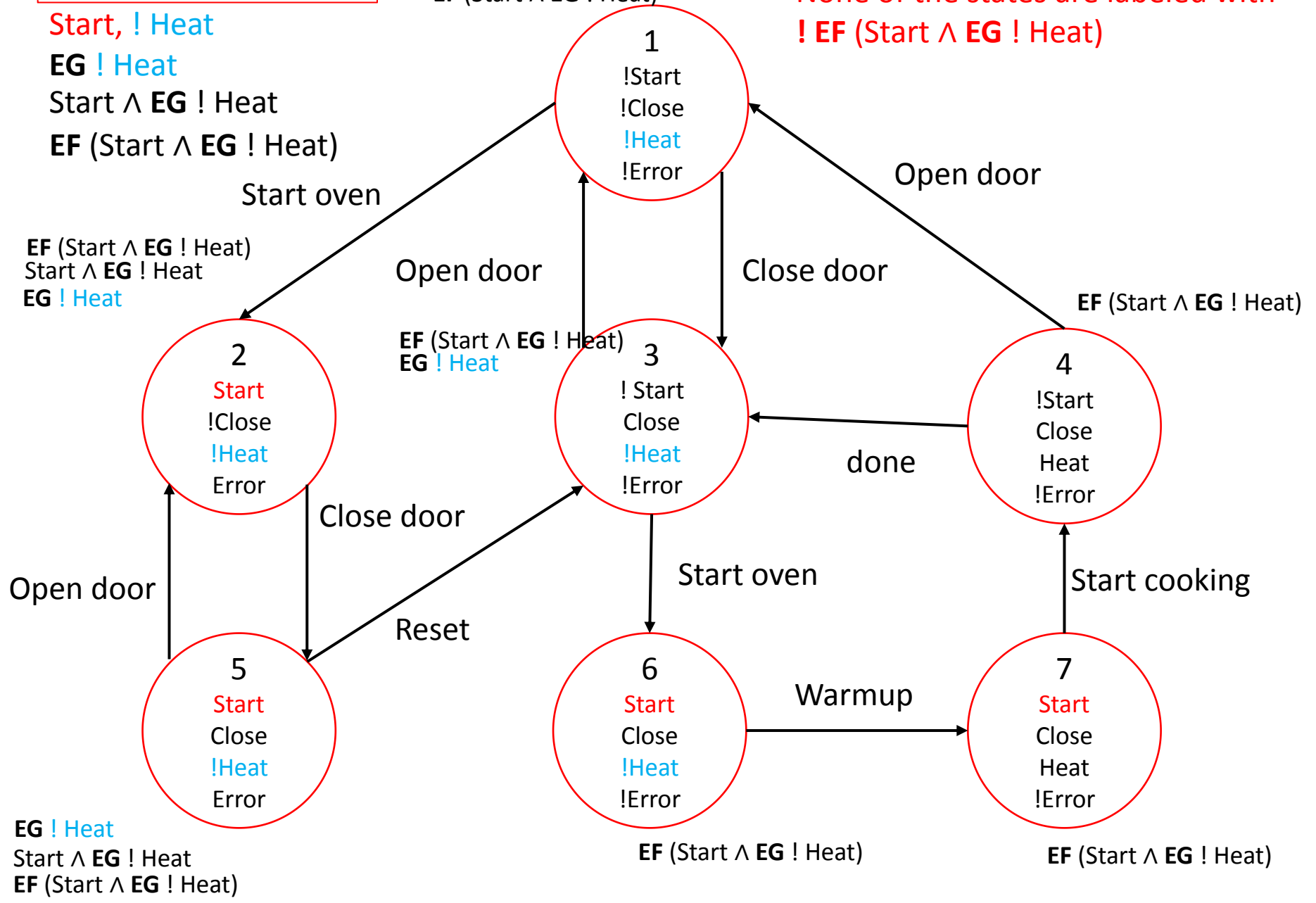


**! EF (Start  $\wedge$  EG ! Heat)**

Start, ! Heat  
EG ! Heat  
Start  $\wedge$  EG ! Heat  
EF (Start  $\wedge$  EG ! Heat)

EG ! Heat  
EF (Start  $\wedge$  EG ! Heat)

None of the states are labeled with  
**! EF (Start  $\wedge$  EG ! Heat)**



EG ! Heat  
Start  $\wedge$  EG ! Heat  
EF (Start  $\wedge$  EG ! Heat)