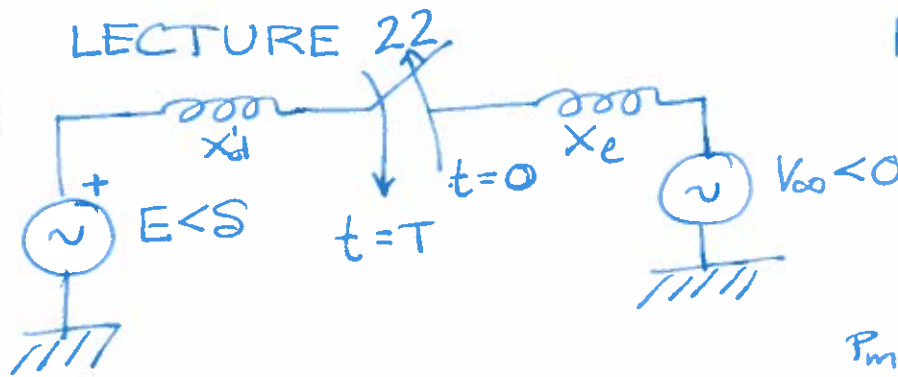


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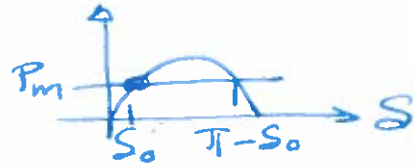
LECTURE 22

$$M \frac{d^2s}{dt^2} + D \frac{ds}{dt} = P_m - P_e$$



Assume $D=0$

$$x := x_d' + x_e$$



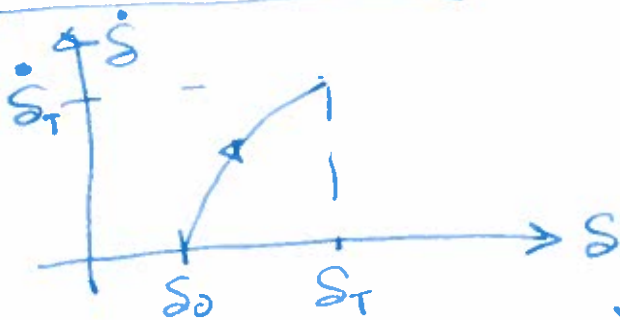
STAGE 1 ($t < 0$)

$$\frac{ds}{dt} = \frac{d^2s}{dt^2} = 0 \rightarrow S_0 = \arcsin\left(\frac{P_m}{\frac{E V_{oo}}{X}}\right) < \frac{\pi}{2}$$

STAGE 2 ($0 \leq t < T$)

$$M \cdot \frac{d^2s}{dt^2} = P_m \rightarrow \frac{ds}{dt} = \frac{P_m}{M} t, \quad s = \frac{P_m}{2M} t^2 + S_0$$

$$s = \frac{M}{2P_m} \dot{s} + S_0$$



$$\dot{s}_T = \frac{P_m}{M} T$$

$$S_T = \frac{P_m}{2M} T^2 + S_0$$

STAGE 3 ($t \geq T$)

$$M \frac{d^2s(t)}{dt^2} = P_m - \frac{E V_{oo}}{X} \sin s(t)$$

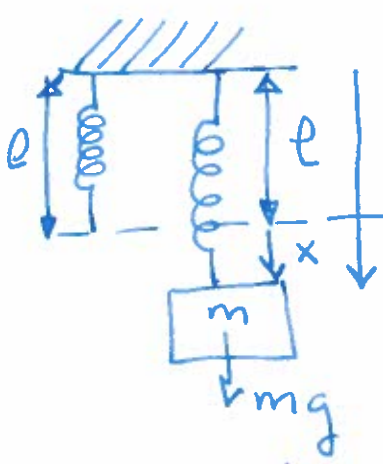
$$s(0) = s_T = \frac{P_m}{2M} T^2 + S_0$$

$$\dot{s}(0) = \dot{s}_T = \frac{P_m}{M} T$$

What happens with $(s(t), \dot{s}(t))$?

To answer the question, we resort to an energy argument

DETOUR [MASS-SPRING SYSTEM]



OBSERVER

$$m \frac{d^2 y(t)}{dt^2} = mg - k(y(t) - l)$$

$$x(t) = y(t) - l$$

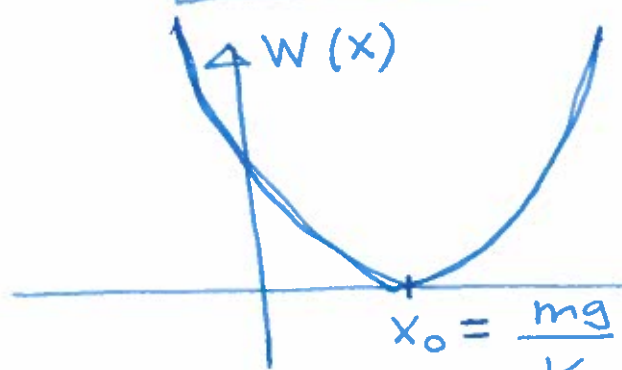
$$m \frac{d^2 x(t)}{dt^2} = mg - kx(t)$$

Potential energy function:

$$W(x_0) - W(x) = \int_{x_0}^x \vec{F} d\vec{x} = \int_{x_0}^x (mg - k \cdot z) dz$$

$$W(x) = -mg(x - x_0) + \frac{1}{2} k (x^2 - x_0^2)$$

$$W(x) = -mg(x - x_0) + \frac{1}{2} k (x^2 - x_0^2)$$



equilibrium point [we take the potential energy of this point to be zero.]

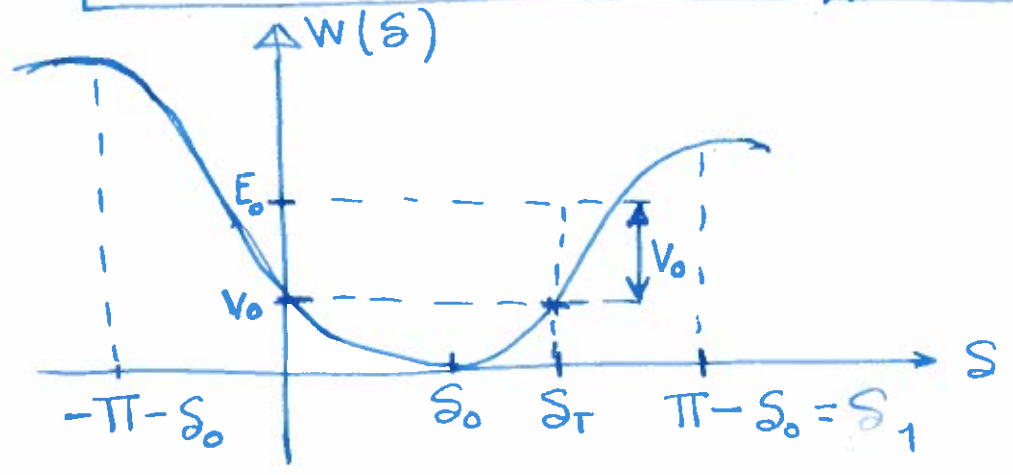
STAGE 3 ANALYSIS

For the swing equation, we have

$$M \cdot \frac{d^2 s(t)}{dt^2} = P_m - \frac{EV_{\infty}}{x} \sin s = P(s)$$

$$W(s) = - \int_{s_0}^s P(u) du = - \int_{s_0}^s \left(P_m - \frac{EV_{\infty}}{x} \sin u \right) du$$

$$W(\delta) = -P_m(\delta - \delta_0) - \frac{EV_\infty}{X} (\cos \delta - \cos \delta_0)$$



At the beginning of STAGE 3, we have $\delta(0) = \delta_T$ and $\dot{\delta}(0) = \dot{\delta}_T$; thus

the potential energy is:

$$W_0 = -P_m(\delta_T - \delta_0) - \frac{EV_\infty}{X} (\cos \delta_T - \cos \delta_0)$$

The system also has Kinetic energy because $\dot{\delta}(0) = \dot{\delta}_T \neq 0$:

$$V_0 = \frac{1}{2} M \cdot \dot{\delta}_T^2$$

The total energy @ the beginning of stage 3 is:

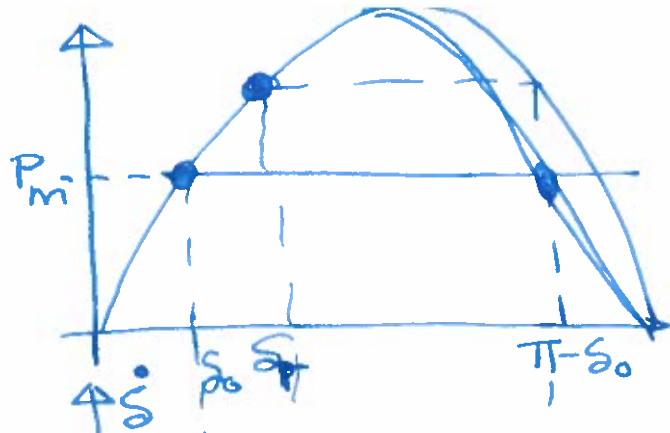
$$E_0 = \underbrace{\frac{1}{2} M \dot{\delta}_T^2}_{\text{Kinetic}} + \underbrace{\left(-P_m(\delta_T - \delta_0) - \frac{EV_\infty}{X} (\cos \delta_T - \cos \delta_0) \right)}_{\text{Potential}}$$

Because $D \neq 0$; the initial energy will remain constant; i.e.,

$$E(t) = E_0, \quad t \geq T$$

$$\frac{d}{dt} E(\delta(t), \dot{\delta}(t)) = \frac{1}{2} 2M\dot{\delta} \cdot \frac{d}{dt} \dot{\delta} = \left(P_m - \frac{EV_\infty}{X} \sin \delta \right) \dot{\delta}$$

$$= (M\ddot{\delta} - P_m + \frac{EV_\infty}{X} \sin \delta) \dot{\delta} = 0!$$



First swing:

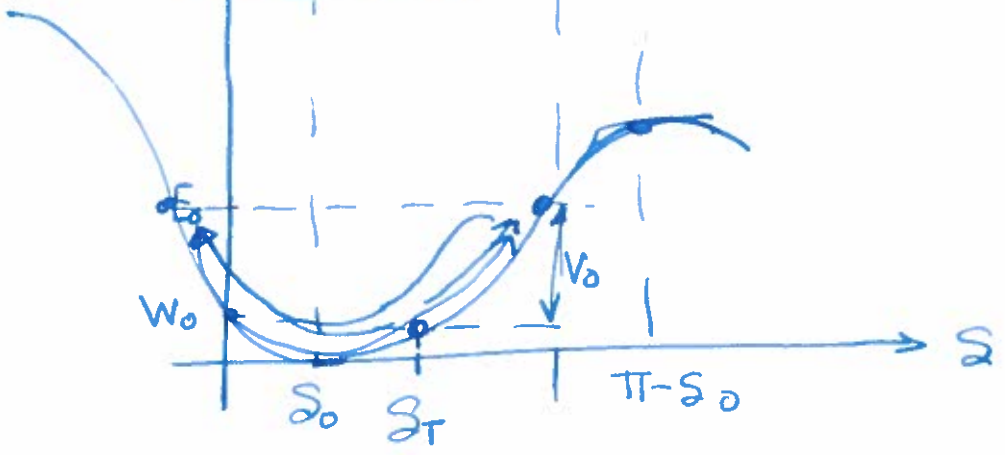
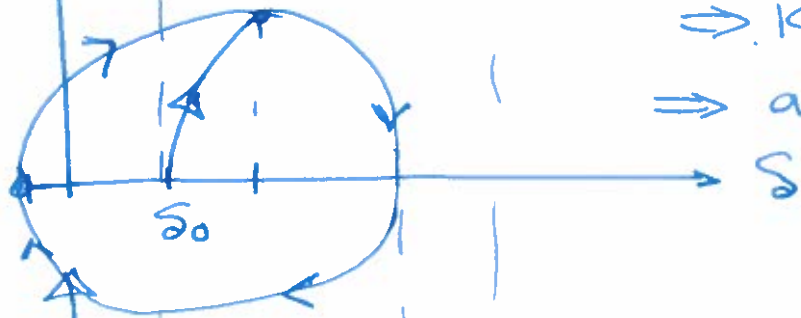
Initially ($\dot{\delta} = T$)

$$P_m - \frac{EV_{\infty}}{X} \cdot \sin \delta_T < 0$$

\Rightarrow the system will decelerate \Rightarrow

\Rightarrow Kinetic energy decreases

\Rightarrow angle increases



What's the effect of the friction coefficient?

$$M\ddot{\delta} = -D\dot{\delta} + \underbrace{P_m - \frac{EV_{\infty} \sin \delta}{X}}_{P(\delta)}$$

~~$$\frac{d}{dt} E(\delta(t), \dot{\delta}(t)) = \frac{\partial E}{\partial \delta} \cdot \dot{\delta}$$~~

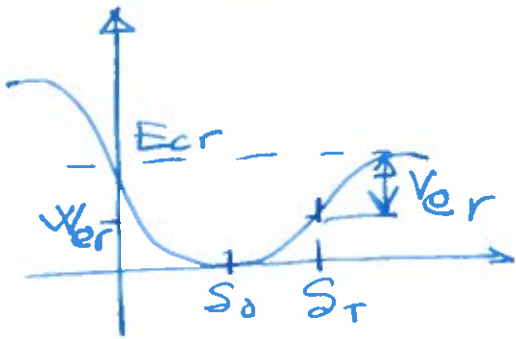
$$\frac{d}{dt} E(\delta(t), \dot{\delta}(t)) = \frac{\partial E}{\partial \delta} \cdot \frac{d\delta}{dt} + \frac{\partial E}{\partial \dot{\delta}} \frac{d\dot{\delta}}{dt}$$

$$= M \cdot \dot{\delta} \cdot \ddot{\delta} + P(\delta) \dot{\delta}$$

$$= [M\ddot{\delta} - P(\delta)] \dot{\delta} = -D\dot{\delta}^2 < 0$$

EQUAL AREA CRITERION

Clearly there is an initial energy level that if the system has, it won't be able to recover after the fault has been cleared.



$$E_{cr} = W_{cr} + V_{cr}$$

$$E_{cr} = W(\pi - S_0)$$

$$= -P_m(\pi - 2S_0)$$

$$= -\frac{EV_{\infty}}{X} \cos(\pi - S_0) + \frac{EV_{\infty}}{X} \cos S_0$$

$$= -P_m(\pi - 2S_0) + \frac{2EV_{\infty}}{X} \cos S_0$$

Corresponding to this E_{cr} , there is a critical T .

Mathematically:

$$\frac{1}{2} M \dot{S}_T^2 + \int_{S_0}^{S_T} -P(u) du < \int_{S_0}^{\pi - S_0} -P(u) du$$

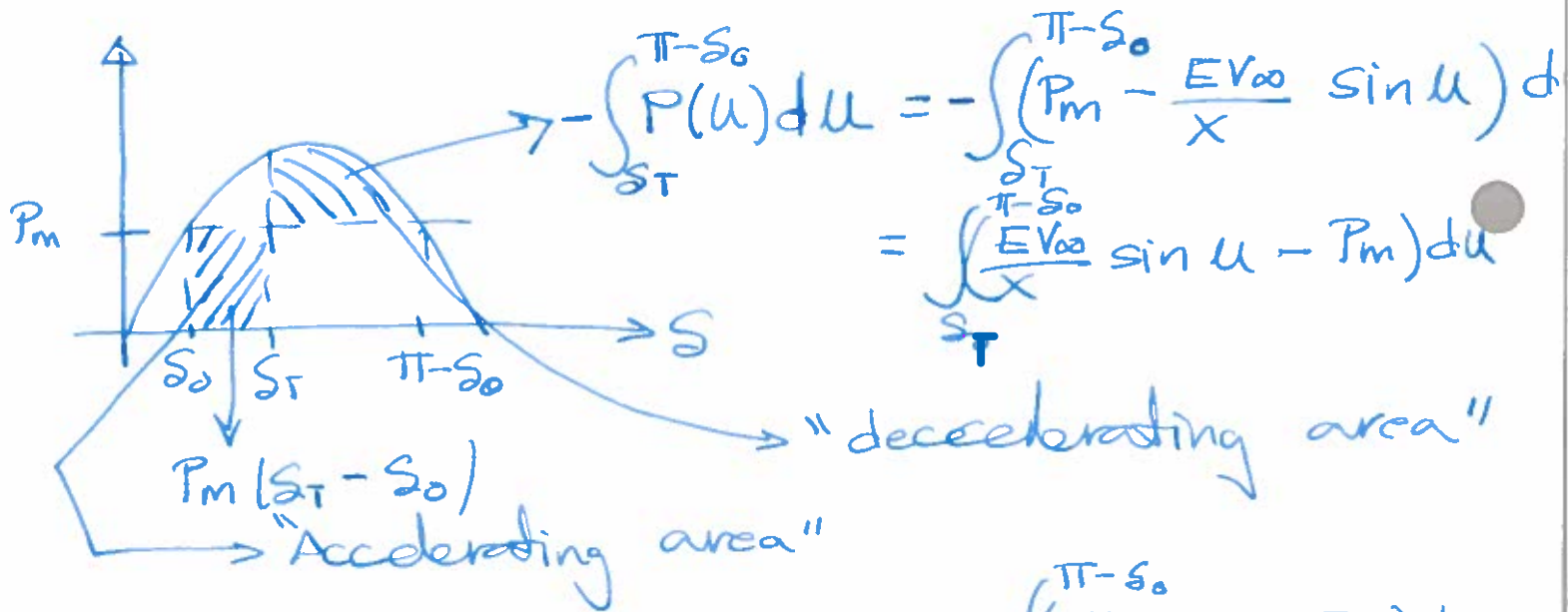
$$\frac{1}{2} M \dot{S}_T^2 < \int_{S_T}^{\pi - S_0} -P(u) du$$

We also saw that @ the end of STAGE 2, we had:

$$S_T = S_0 + \frac{M}{2P_m} \dot{S}_T^2 \rightarrow \boxed{P_m(S_T - S_0) = \frac{1}{2} M \dot{S}_T^2}$$

Thus, the criterion is

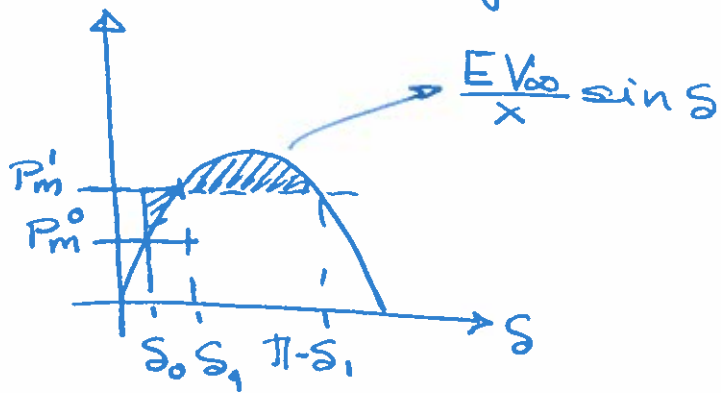
$$P_m(S_T - S_0) < T \int_{S_T}^{\pi - S_0} P(u) du$$



Critical T: $P_m (S_T - S_0) = \int_{S_0}^{\pi-S_0} \left(\frac{EV_{\infty}}{X} \sin u - P_m \right) du$

OTHER APPLICATIONS OF THE EQUAL-AREA CRITERION

1. Sudden change in P_m



The idea is always the same: need to compare the initial energy after the change with the critical potential energy

In this case, after P_m changes, the potential energy curve changes as well.

$$W(S) = - \int_{S_1}^S \left(P_m' - \frac{EV_{\infty}}{X} \sin u \right) du$$

↑
this is the eq. point we need to use

Initially, the potential energy the system has is

$$W(\delta_0) = - \int_{\delta_1}^{\delta_0} \left(P_m' - \frac{E V_{\infty}}{x} \sin u \right) du$$

- No Kinetic energy.

- Thus the criterion is

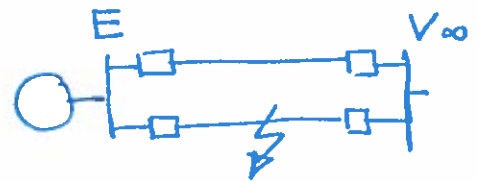
$$W(\delta_0) \leq W(\pi - \delta_1)$$

$$- \int_{\delta_1}^{\delta_0} \left(P_m' - \frac{E V_{\infty}}{x} \sin u \right) du \leq - \int_{\delta_1}^{\pi - \delta_1} \left(P_m' - \frac{E V_{\infty}}{x} \sin u \right) du$$

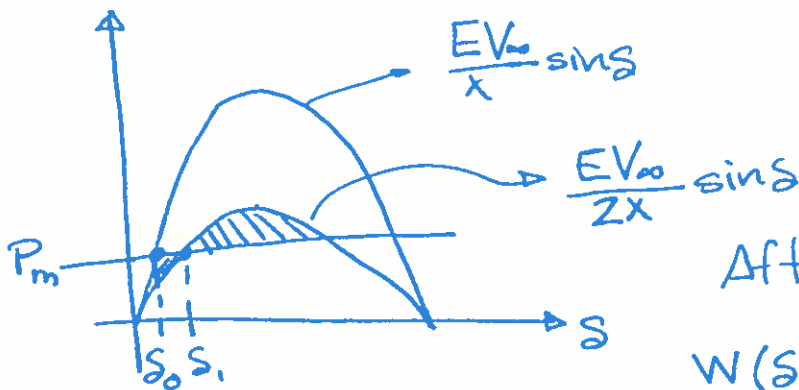
$$\int_{\delta_0}^{\delta_1} \left(P_m' - \frac{E V_{\infty}}{x} \sin u \right) du \leq \int_{\delta_1}^{\pi - \delta_1} \left(\frac{E V_{\infty}}{x} \sin u - P_m' \right) du$$

consistent with the shaded areas in the figures.

2. Sudden change in x



After the fault occurs x goes to $2x$



After the fault (initial potential energy)

$$W(\delta_0) = - \int_{\delta_1}^{\delta_0} \left(P_m - \frac{E V_{\infty}}{2x} \sin u \right) du$$

- Critical potential energy:

$$W(\pi - \delta_1) = - \int_{\delta_1}^{\pi - \delta_1} \left(P_m - \frac{EV_0}{2x} \sin u \right) du$$

- Initially, no kinetic energy; thus, the criterion is

$$W(\delta_0) \leq W(\pi - \delta_1)$$

$$+ \int_{\delta_0}^{\delta_1} \left(P_m - \frac{EV_0}{2x} \sin u \right) du \leq - \int_{\delta_1}^{\pi - \delta_1} \left(P_m - \frac{EV_0}{2x} \sin u \right) du$$

$$\int_{\delta_0}^{\delta_1} \left(P_m - \frac{EV_0}{2x} \sin u \right) du \leq \int_{\delta_1}^{\pi - \delta_1} \left(\frac{EV_0}{2x} \sin u - P_m \right) du$$

→ consistent with the shaded areas in the figure.