

LECTURE 2

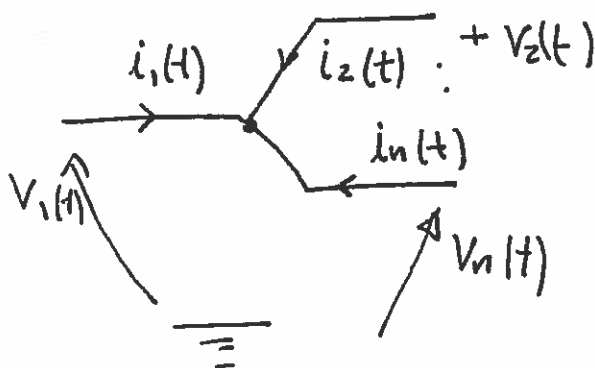
08/31/17

- CONSERVATION OF POWER
- REACTIVE POWER COMPENSATION
- THREE-PHASE POWER
 - 3 ϕ VOLTAGE SOURCES
 - 3 ϕ CONNECTIONS
 - 3 ϕ POWER NOTIONS

CONSERVATION OF POWER

- For any node in an electrical network:

- (i) Sum of real power into the node must be zero
- (ii) Sum of reactive power into the node must be zero



$$KVL = \frac{\bar{V}_i = \bar{V}_j, \forall i, j}{v_i(t) = v_j(t)}$$

$$KCL: \sum_{j=1}^n i_j(t) = 0 \rightarrow$$

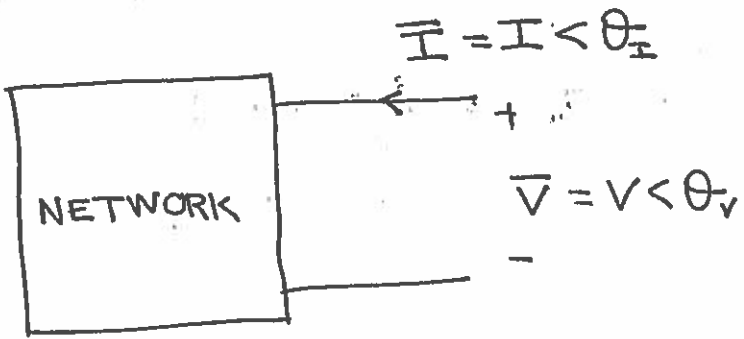
$$\rightarrow \sum_{j=1}^n \bar{I}_j = 0$$

$$\left. \begin{aligned} \bar{S}_1 &= \bar{V}_1 \cdot \bar{I}_1^* \\ \bar{S}_2 &= \bar{V}_2 \cdot \bar{I}_2^* \\ \vdots \\ \bar{S}_n &= \bar{V}_n \cdot \bar{I}_n^* \end{aligned} \right\}$$

$$\begin{aligned} \rightarrow \sum_{j=1}^n \bar{S}_j &= \bar{V}_1 \cdot \bar{I}_1^* + \bar{V}_2 \cdot \bar{I}_2^* + \dots + \bar{V}_n \cdot \bar{I}_n^* \\ &= \bar{V} (\bar{I}_1^* + \bar{I}_2^* + \dots + \bar{I}_n^*) \\ &= \bar{V} (\bar{I}_1 + \bar{I}_2 + \dots + \bar{I}_n)^* \end{aligned}$$

$$\bar{V}_1 = \bar{V}_2 = \dots = \bar{V}_n = \bar{V}$$

REACTIVE POWER COMPENSATION

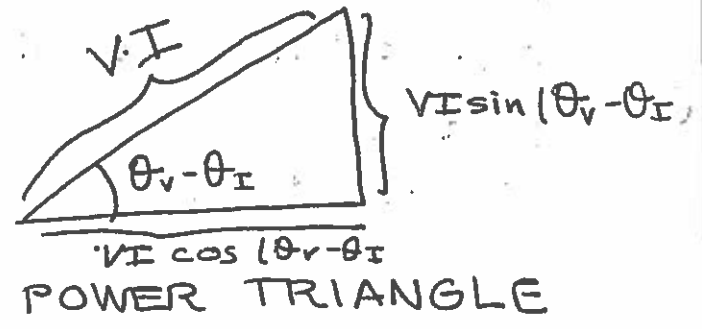


$$\bar{S} = \bar{V} \cdot \bar{I}^* = P + jQ$$

$$P = VI \cos(\theta_V - \theta_I)$$

$$Q = VI \sin(\theta_V - \theta_I)$$

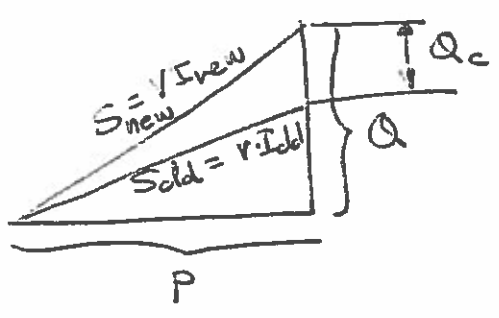
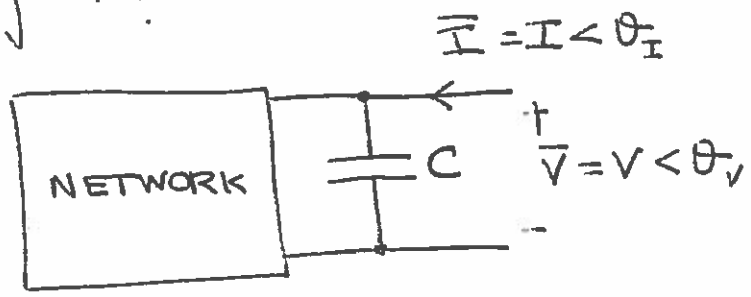
$$S = \sqrt{P^2 + Q^2}$$



- The nature of the network determines $\theta_V - \theta_I$

\Rightarrow for a fixed V , we will have $\rightarrow P, Q$
a corresponding I

- Is there a way we can reduce \bar{S} while maintaining P ?



$$S_{new} = \sqrt{P^2 + (Q - Q_c)^2} = V I_{new}$$

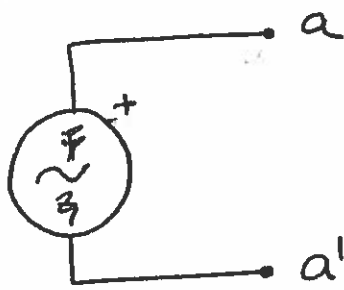
$$Q_c = \frac{V^2}{X_c}$$

$$S_{new} = V I_{new}$$

$$S_{old} = V I_{old}$$

$\Rightarrow S_{new} < S_{old}$
 $\Rightarrow I_{new} < I_{old}$

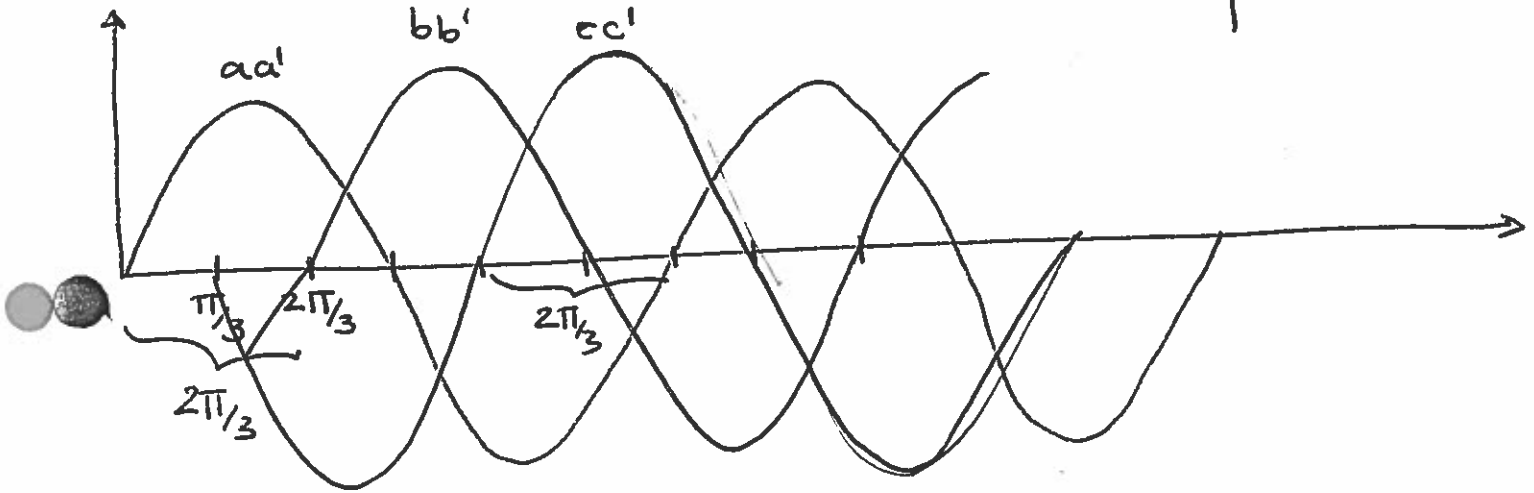
THREE-PHASE SYSTEMS



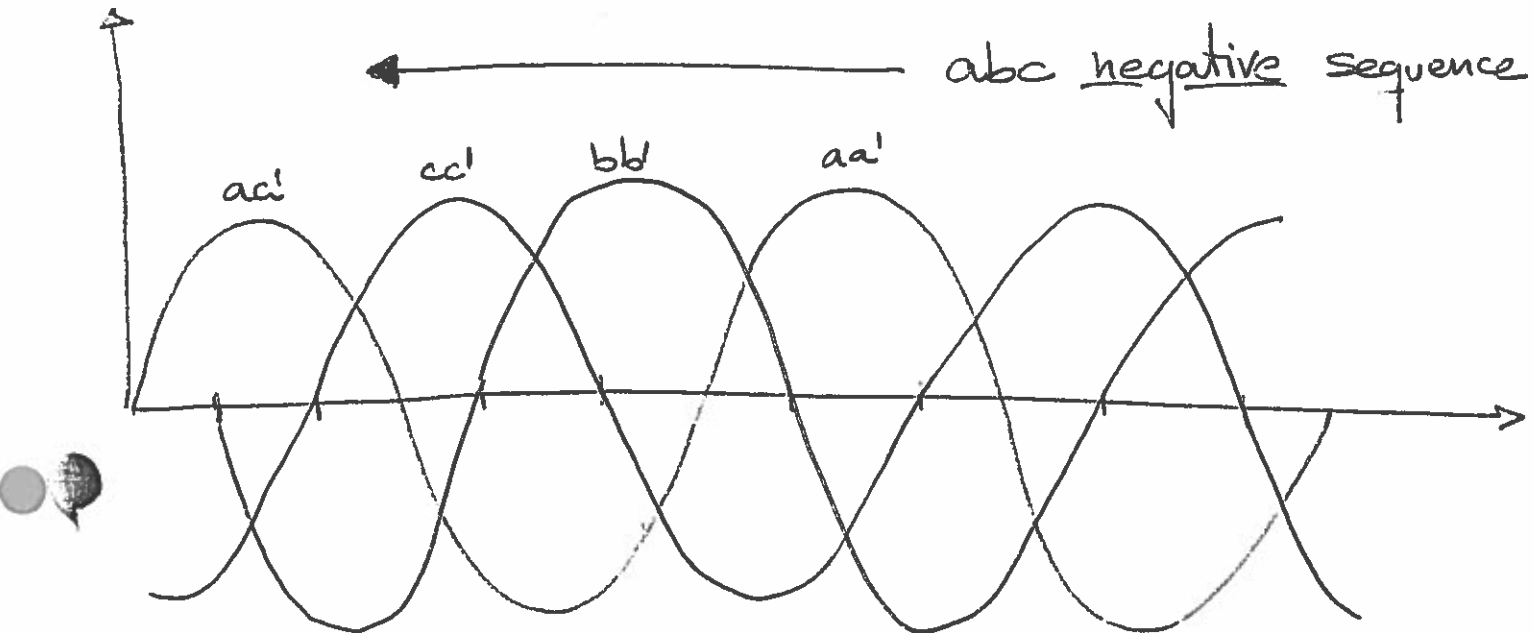
$$V_{bb'}(t) = \sqrt{2}V \cos(\omega t - \frac{2\pi}{3})$$

$$V_{cc'}(t) = \sqrt{2}V \cos(\omega t + \frac{2\pi}{3})$$

→ abc positive sequence

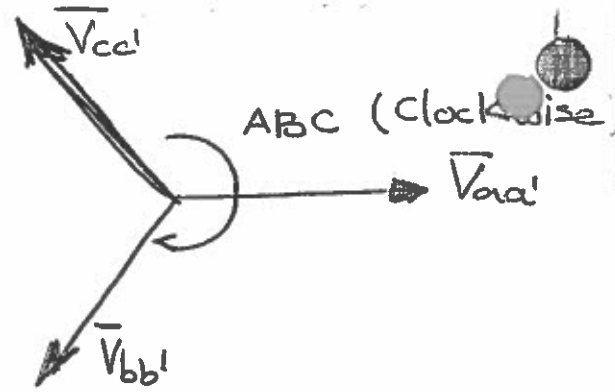


← abc negative sequence

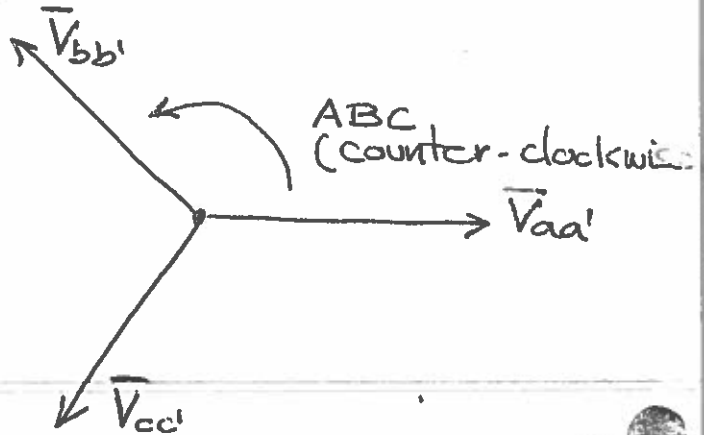


PHASOR REPRESENTATION

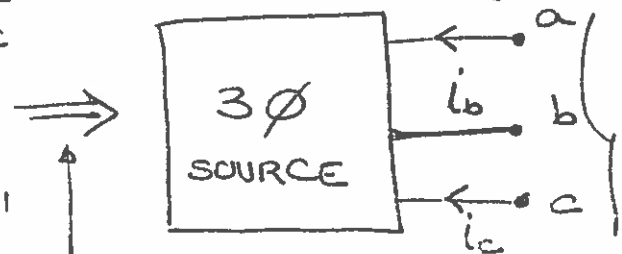
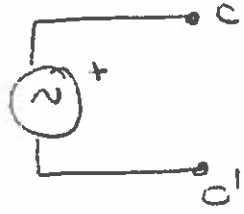
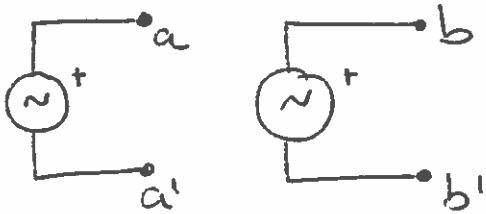
$$\oplus \begin{cases} \bar{V}_{aa'} = V \angle \theta_v = V \angle 0 \\ \bar{V}_{bb'} = V \angle -\frac{2\pi}{3} \\ \bar{V}_{cc'} = V \angle \frac{2\pi}{3} \end{cases}$$



$$\ominus \begin{cases} \bar{V}_{aa'} = V \angle \theta_v \\ \bar{V}_{bb'} = V \angle \frac{2\pi}{3} \\ \bar{V}_{cc'} = V \angle -\frac{2\pi}{3} \end{cases}$$



THREE-PHASE CONNECTIONS

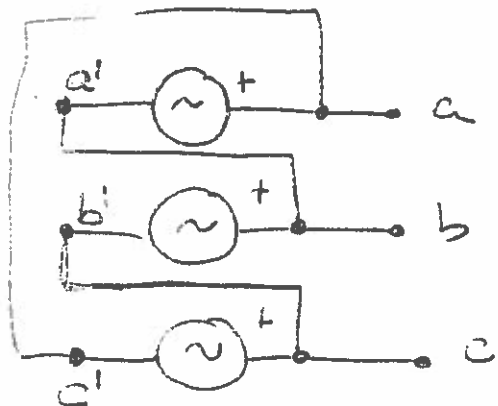
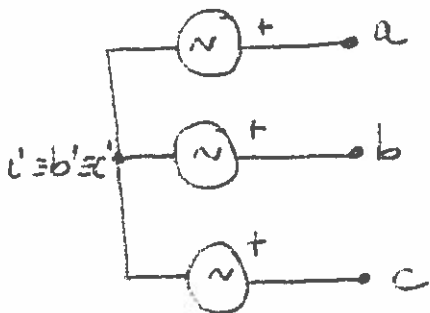


interconnection?

Two possibilities

Three terminals
two ports.

WYE CONNECTION



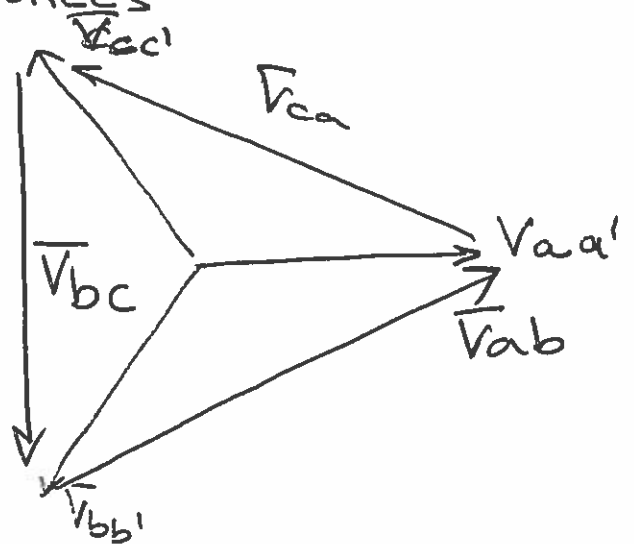
Definitions: rms values of:

- i) Line voltage (V_L): voltage across any two terminals
- ii) Phase voltage (V_ϕ): voltage across the terminals of a source
- iii) Line current (I_L): current flowing out of a terminal
- iv) Phase current (I_ϕ): current flowing across a source

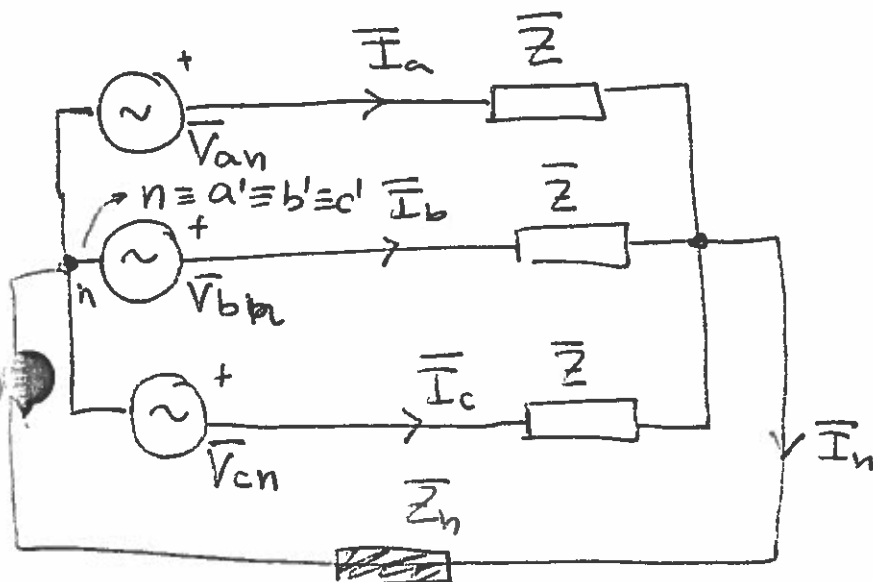
Y-connection (if balanced operation) Δ -connection
 $V_L = \sqrt{3} V_\phi, I_L = I_\phi$ $V_L = V_\phi, I_L = \sqrt{3} I_\phi$

RELATIONS BETWEEN LINE & PHASE VOLTAGES FOR Y-CONNECTED SOURCES

$$\begin{aligned} -\bar{V}_{ab} &= \bar{V}_{a'a} - \bar{V}_{b'b} \\ \bar{V}_{bc} &= \bar{V}_{b'b} - \bar{V}_{c'c} \\ \bar{V}_{ca} &= \bar{V}_{c'c} - \bar{V}_{a'a} \end{aligned}$$



Y-Y CONNECTION W/ BALANCED LOAD



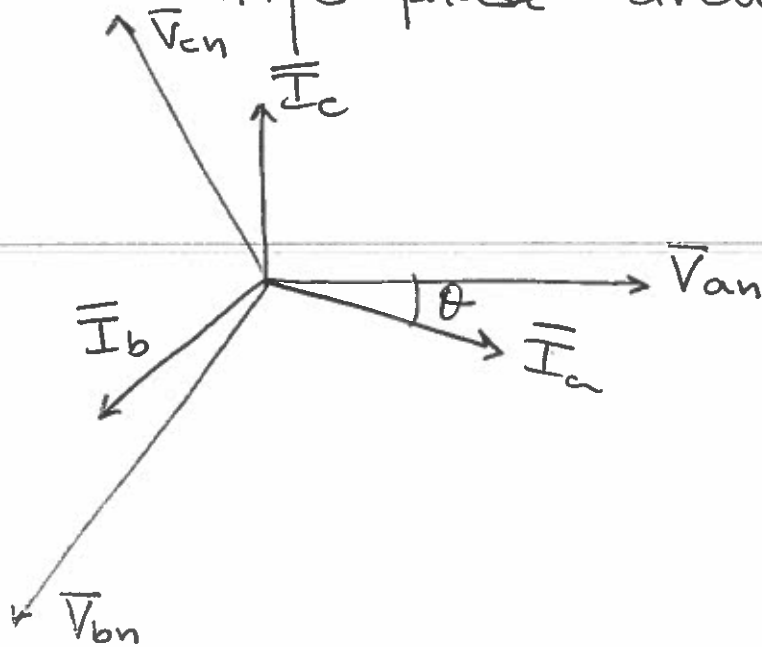
$$\begin{aligned} \bar{V}_{an} &= \bar{Z} \bar{I}_a + \bar{Z}_n \bar{I}_n \\ \bar{V}_{bn} &= \bar{Z} \bar{I}_b + \bar{Z}_n \bar{I}_n \\ \bar{V}_{cn} &= \bar{Z} \bar{I}_c + \bar{Z}_n \bar{I}_n \end{aligned}$$

$$\underbrace{\bar{V}_{an} + \bar{V}_{bn} + \bar{V}_{cn}}_0 = \bar{Z} \underbrace{(\bar{I}_a + \bar{I}_b + \bar{I}_c)}_{\bar{I}_n} + 3\bar{I}_n \bar{Z}_n$$

$$(\bar{Z} + 3\bar{Z}_n)\bar{I}_n = 0$$

$$\text{if } \bar{Z} + 3\bar{Z}_n \neq 0 \rightarrow \bar{I}_n = 0$$

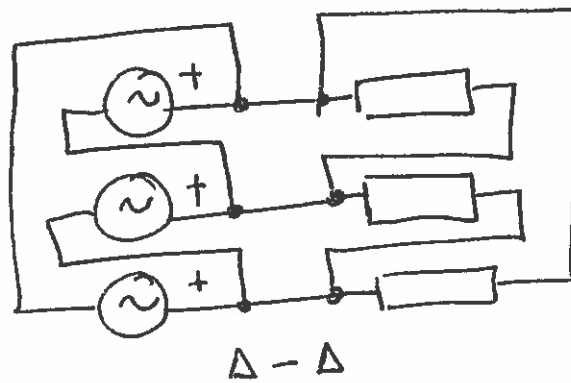
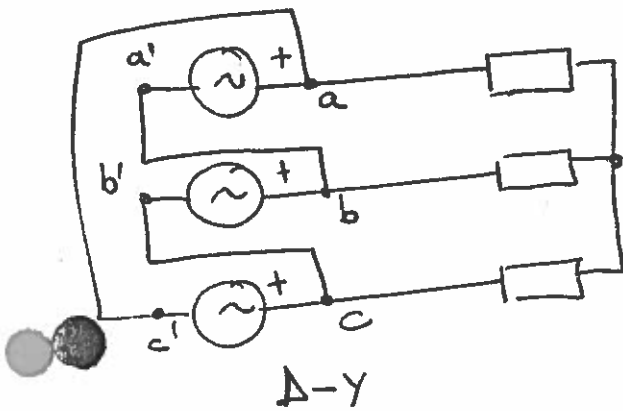
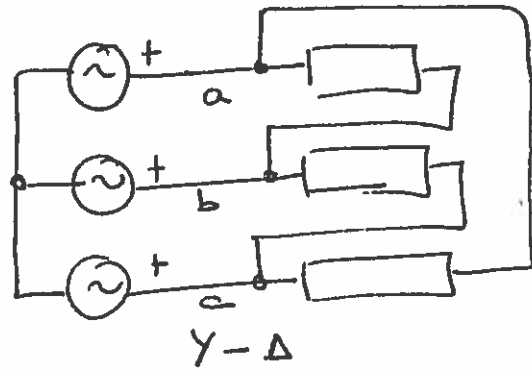
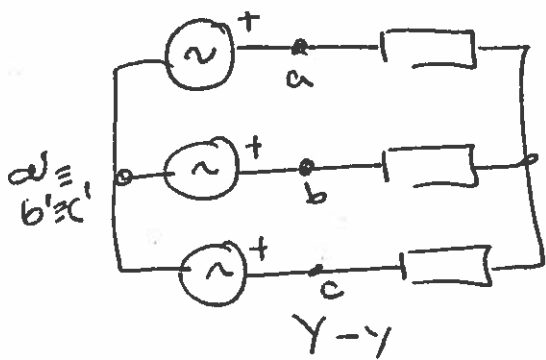
This analysis suggest that we can analyze each single-phase circuit independently.



OBSERVATION

The currents also form a three-phase balance set.

OTHER THREE PHASE CONNECTIONS



THREE-PHASE POWER

Y:

$$\bar{V}_{an} = \sqrt{2} V \cos(\omega t)$$

$$\bar{V}_{bn} = \sqrt{2} V \cos(\omega t - \frac{2\pi}{3})$$

$$\bar{V}_{cn} = \sqrt{2} V \cos(\omega t + \frac{2\pi}{3})$$

$$\bar{I}_a = \sqrt{2} I \cos(\omega t - \theta)$$

$$\bar{I}_b = \sqrt{2} I \cos(\omega t - \theta - \frac{2\pi}{3})$$

$$\bar{I}_c = \sqrt{2} I \cos(\omega t - \theta + \frac{2\pi}{3})$$

$$P_a(t) = VI [\cos \theta + \cos(2\omega t - \theta)]$$

$$P_b(t) = VI [\cos \theta + \cos(2\omega t - \frac{4\pi}{3} - \theta)]$$

$$P_c(t) = VI [\cos \theta + \cos(2\omega t + \frac{4\pi}{3} - \theta)]$$

$$P(t) = 3VI \cos \theta + VI (\cos(2\omega t - \theta) + \cos(2\omega t - \frac{4\pi}{3} - \theta) + \cos(2\omega t + \frac{4\pi}{3} - \theta))$$

$$= 3VI \cos \theta$$

$$P(t) = 3VI \cos \theta \quad \text{CONSTANT}$$

$$V = V_\phi$$

$$I = I_\phi$$

$$\text{IN } \gamma\text{-CONN: } V_\phi = \frac{V_L}{\sqrt{3}} \quad I_\phi = I_L$$

$$P = \sqrt{3} V_L I_L \cos \theta$$

↑
watch out

This is not the angle between ~~any~~
 $\underline{V_{ab}}$ and $\underline{I_a}$!!
↓ ↓
 V_L I_L

$$\bar{S} = 3VI \cos \theta + jVI \sin \theta$$

$$\bar{S} = \sqrt{3} V_L I_L (\cos \theta + j \sin \theta)$$

$$S = \sqrt{3} V_L I_L$$