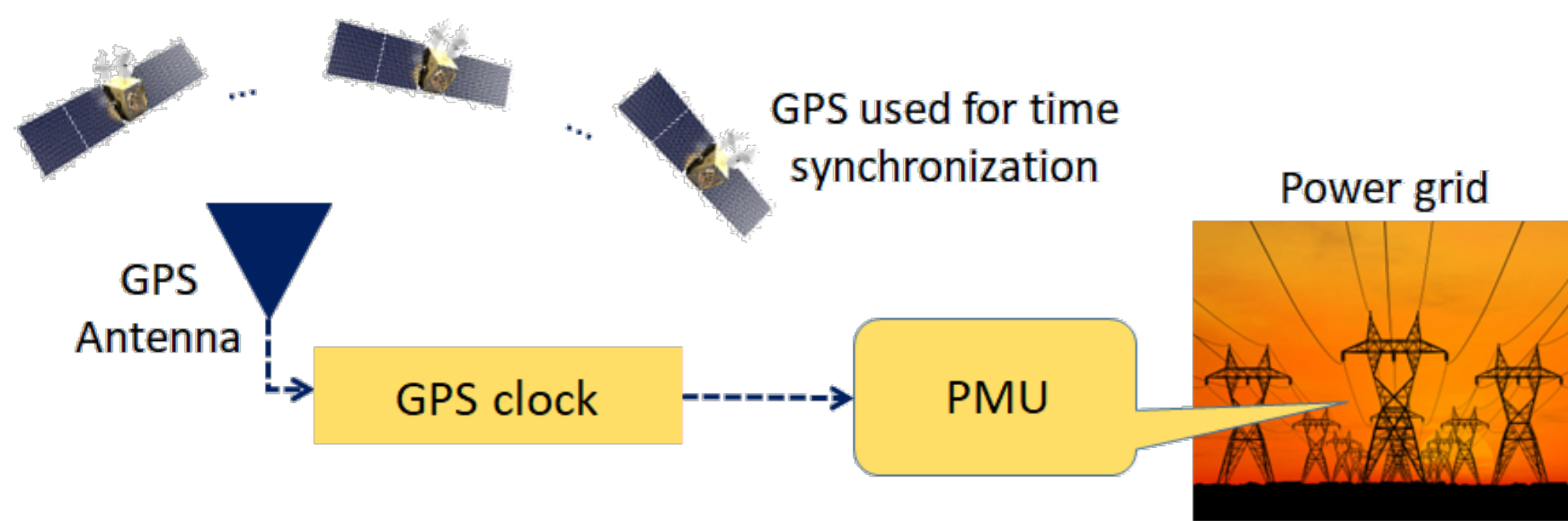


GRID VULNERABILITY TO GPS SPOOFING ATTACKS

- GPS provides accurate and precise time synchronization for PMUs to perform wide area monitoring and control
 - GPS time accuracy $\sim 100ns$ and frequency accuracy $\sim 10^{-12}Hz$

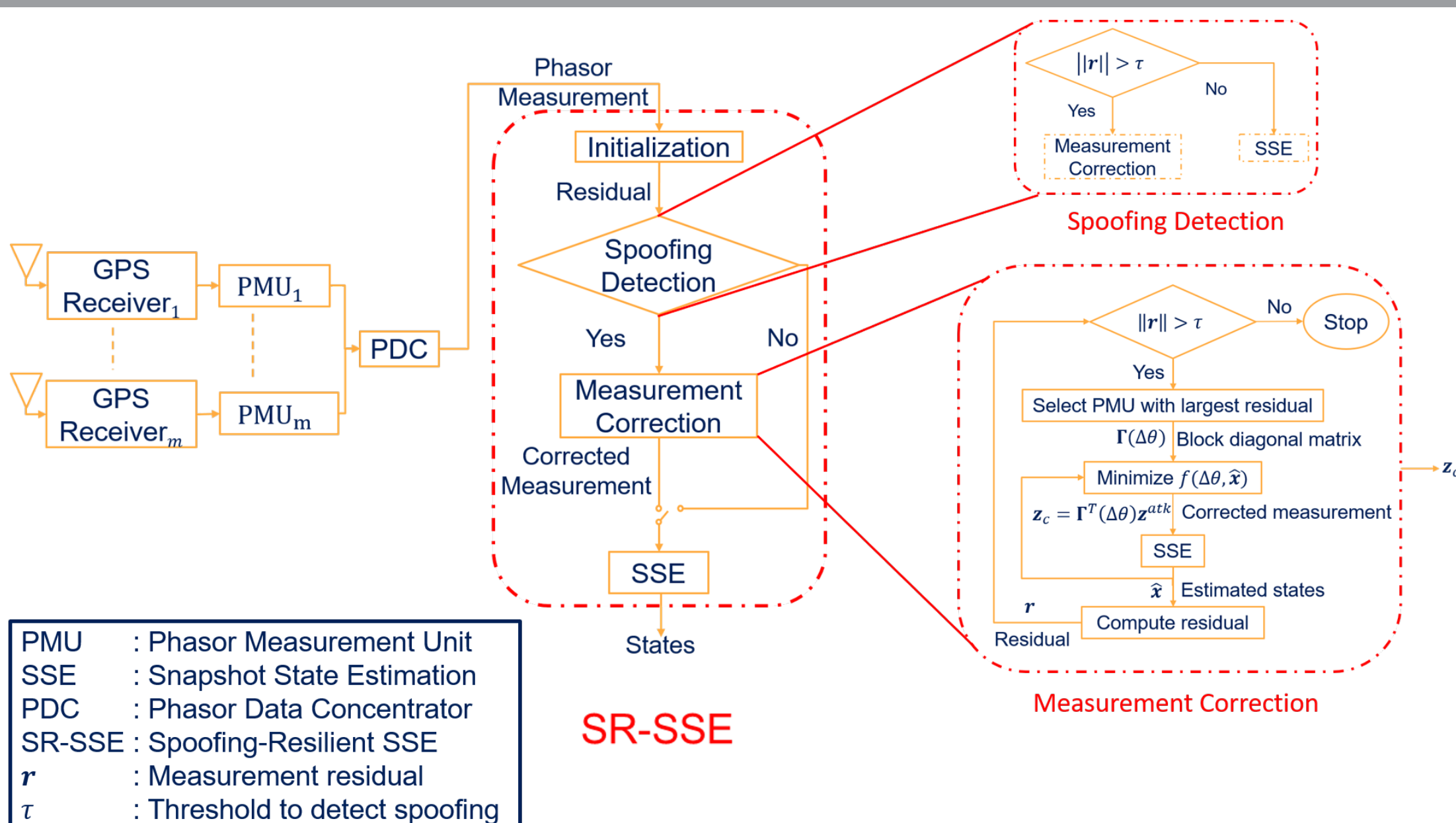


- Civil GPS signals are susceptible to malicious spoofing attacks
 - The received signal power is as low as $-130dBm$; the civil signal structure is unencrypted and known to the public
 - An attacker broadcasts counterfeit civil GPS signals and manipulate victim receivers' time
- Manipulated receivers' time shifts the phase angles for all the PMU measurements at the attacked bus
 - Degrades the performance of the state estimation algorithm
 - Reduces the efficacy of the fault location and voltage stability monitoring algorithms
- GPS spoofing attack detection and mitigation are critical to ensure safe operation of the power grid
- The following aspects related to detection and mitigation of GPS spoofing attacks will increase the resiliency of the power grid
 - Mitigation of multiple spoofing attacks on different buses of the power grid network
 - Necessary condition based on PMU measurement residuals for detecting GPS spoofing attacks
 - Simultaneous detection and mitigation of spoofing attacks using PMU measurements for state estimation algorithms

RESEARCH GOALS

- Provide a necessary condition for detecting GPS spoofing attacks using PMU measurement residuals
- Devise algorithm to mitigate the effect of multiple GPS spoofing attacks by correcting PMU measurements
- Develop a method for simultaneous detection and mitigation of GPS spoofing attacks, thereby advancing power grid resiliency

OUR ARCHITECTURE



Key aspects:

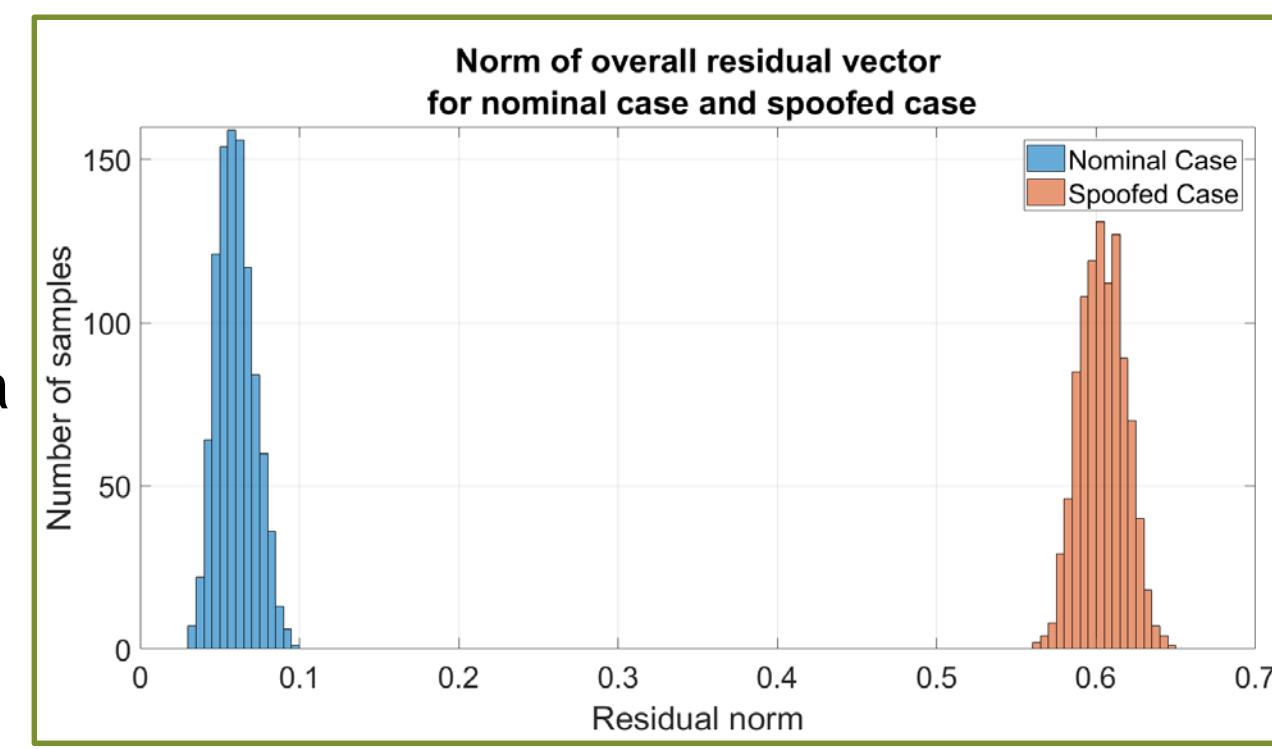
- Our method jointly estimate voltage phasors and attack angles. This is achieved by two algorithms that simultaneously detect and mitigate GPS spoofing attacks
 - Spoofing Detection: Residual-based detection algorithm
 - Measurement Correction: An iterative-minimization algorithm to correct PMU measurements
- Derived mathematical necessary condition for detecting GPS spoofing attacks using PMU measurement residuals

$$(I - HH^+) \geq 0$$

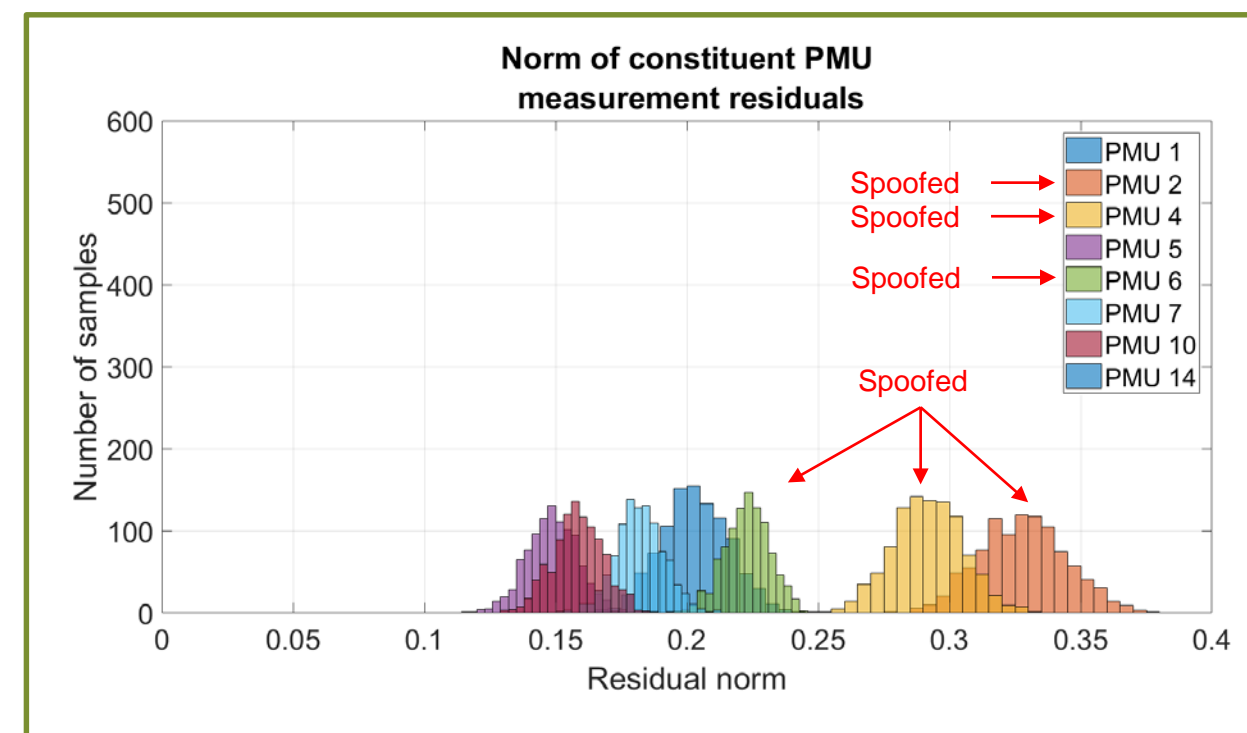
Identity Matrix Admittance Matrix Pseudoinverse Necessary Condition

KEY IDEAS USED IN OUR METHOD

- Monte-Carlo simulation confirms our theoretical analysis and shows that distribution of measurement residual norm changes under a GPS spoofing attack as shown on the right plot
- The introduced bias in the measurement residual norm is used as a detection criteria to detect single or multiple attacks



Measurement residual norm under nominal and spoofed scenario

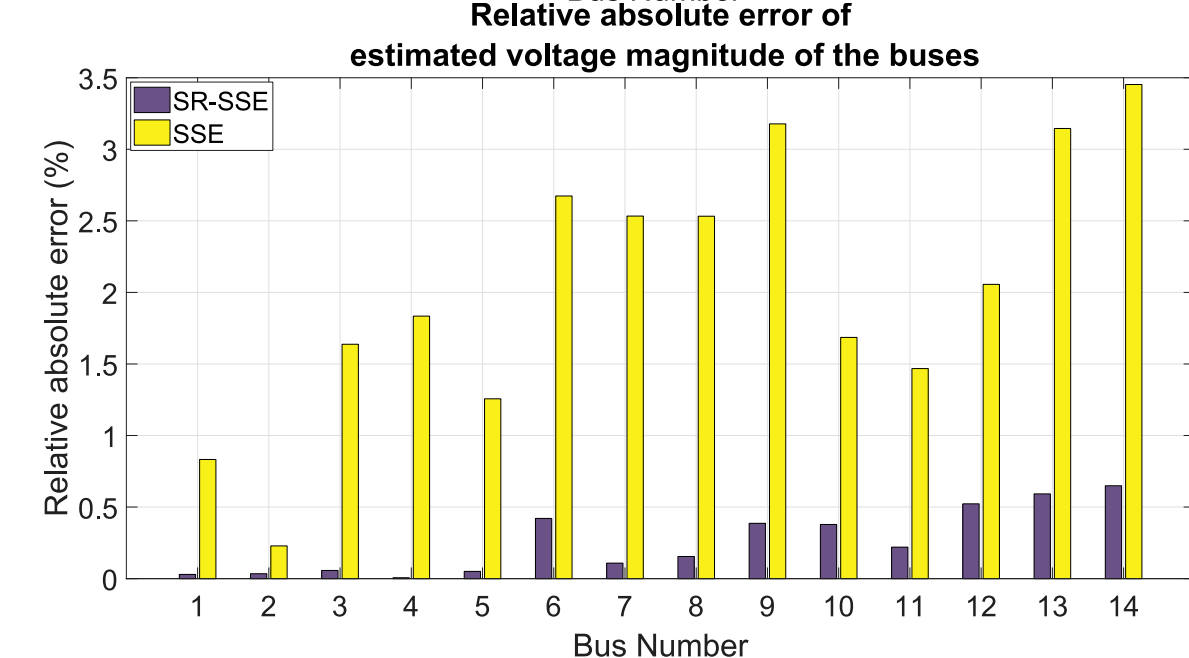
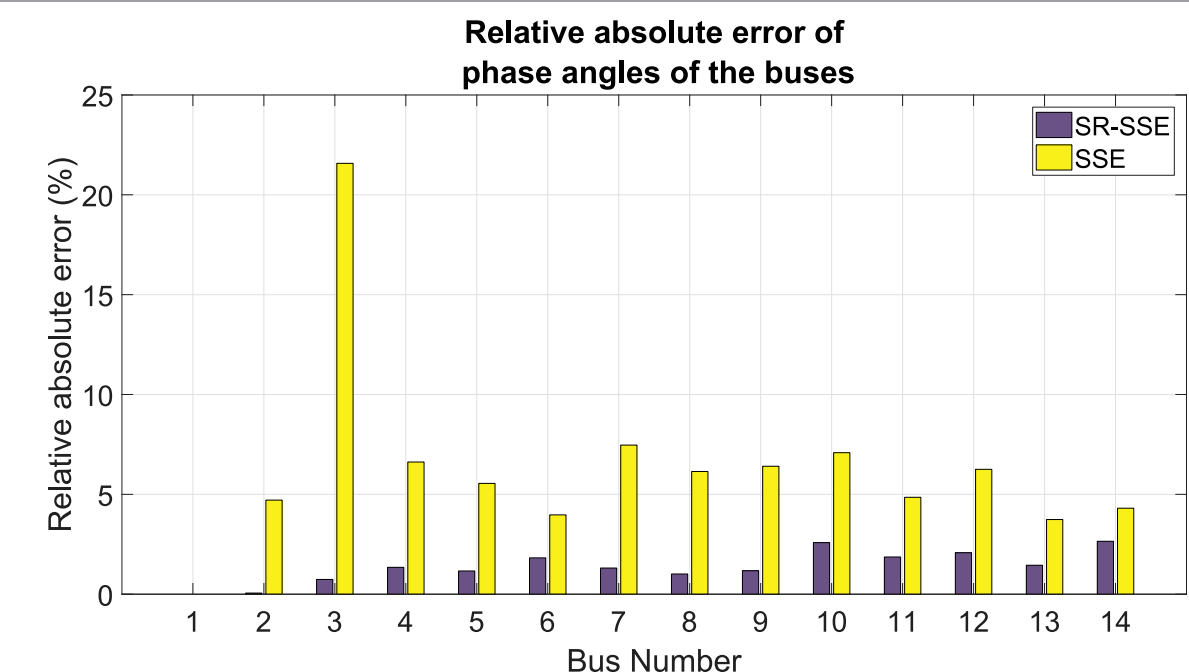


Constituent measurement residual norm under spoofed scenario

- A major contribution in measurement residual norm comes from the spoofed PMU measurements as shown on the left plot
- Above criteria is utilized in the Measurement Correction algorithm to distinguish spoofed PMUs from other

OUR RESEARCH RESULTS

- Simulated IEEE 14 test bus case in Matlab using Matpower. Single and multiple GPS spoofing attacks at various nodes were simulated
- Validated our algorithm for multiple GPS spoofing attacks. Our algorithm reduces the estimation error by an order of magnitude
 - Shown results in which PMU measurements at bus 2,4 and 6 were spoofed



Voltage and Phase angle estimation errors for SR-SSE and SSE

	RMSE	
	Voltage (pu)	Phase (deg)
SSE	2.42×10^{-2}	1.06
SR-SSE	3.69×10^{-3}	2.38×10^{-1}

IMPACT ON POWER GRID

Performance benefits:

- By implementing our method, the power grid monitoring systems will:
 - Provide spoofing resilient voltage phasor estimates
 - Reduce the system risks against external timing attacks
 - Ensure continued robust performance even in degraded scenarios
 - Elevate the maturity of wide area monitoring for future power grids

Business benefits:

- No added hardware and infrastructure costs
- Real time implementation capability
- Increased resilience against GPS spoofing attacks

POTENTIAL COLLABORATION OPPORTUNITIES

Cooperation, support and guidance from industry partners in the following areas would benefit this research activity:

- Inputs regarding the details of PMU setup including latencies, communication network and processing capabilities
- Specifications regarding the expected response time to counteract the timing attacks on the PMUs
- Platform for state estimation analysis via datasets or test bed setup to validate the impact of our algorithm
- Contact: gracegao@illinois.edu, chauhan7@illinois.edu, sbhamid2@illinois.edu
- Activity webpage: <https://cred-c.org/researchactivity/robust-and-secure-gps-based-timing-power-systems>